

CS:4980 Topics in Computer Science II

Introduction to Automated Reasoning

Combining Theory Solvers with SAT solvers

Cesare Tinelli

Spring 2024



Credits

These slides are based on slides originally developed by **Cesare Tinelli** at the University of Iowa, and by **Clark Barrett, Caroline Trippel**, and **Andrew (Haoze) Wu** at Stanford University. Adapted by permission.

Checking the satisfiability of quantifier-free formulas

Theory solvers check the satisfiability of conjunctions of literals

What if we have formulas with disjunctions, like this \mathcal{T}_{EUF} -formula?

$$g(a) \doteq c \wedge (f(g(a)) \neq f(c) \vee g(a) \doteq d) \wedge c \neq d$$

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Theorem 1

For all theories \mathcal{T} , the \mathcal{T} -satisfiability of **quantifier-free** formulas is decidable iff the \mathcal{T} -satisfiability of conjunctions/sets of literals is decidable.

Proof.

Convert the formula to DNF and check if any of its disjuncts is \mathcal{T} -satisfiable. □

Problem: the DNF conversion is **very inefficient!** (formula size can explode exponentially)

A better solution: exploit **propositional satisfiability technology** to deal with the Boolean structure

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Lifting SAT Technology to SMT

Two main approaches:

1. *Eager*

- translate into an equisatisfiable propositional formula
- feed it to any SAT solver

Notable systems: **UCLID**

2. *Lazy*

- abstract the input formula to a propositional one
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- use a theory decision procedure to refine the formula and guide the SAT solver

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Lazy Approach for SMT

Given a quantifier-free Σ -formula φ , for each **atomic formula** α in φ , we associate a **unique** propositional variable $e(\alpha)$

The *Boolean skeleton* of a formula φ is a propositional logic formula, where each atomic formula α in φ is replaced with $e(\alpha)$

Example:

$$\varphi := \underbrace{x < 0}_{p_1} \vee \underbrace{(x + y < 1)}_{p_2} \wedge \neg \underbrace{(x < 0)}_{p_1} \Rightarrow \underbrace{y < 0}_{p_3}$$

Boolean skeleton of φ : $p_1 \vee (p_2 \wedge \neg p_1) \Rightarrow p_3$

with $e := \{ (x < 0) \mapsto p_1, (x + y < 1) \mapsto p_2, (y < 0) \mapsto p_3 \}$

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(Very) Lazy Approach for SMT – Example

$$g(a) \doteq c \wedge (f(g(a)) \neq f(c) \vee g(a) \doteq d) \wedge c \neq d$$

Simplest setting:

- Off-line SAT solver
- Non-incremental *theory solver* for conjunctions of equalities and disequalities
- Theory atoms (e.g., $g(a) \doteq c$) *abstracted* to propositional atoms (e.g., 1)

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- SAT solver returns model $\{1, \bar{2}, \bar{4}\}$
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Done! The original formula is unsatisfiable in \mathcal{T}_{EUF}

Eager Approach for SMT – Example

$$f(b) \doteq a \vee f(a) \not\doteq a$$

Step 1: Eliminate all function applications (Ackermann's encoding)

- introduce a constant symbol f_x to replace function application $f(x)$
- for each pair of introduced variables f_x, f_y , add the formula $x \doteq y \Rightarrow f_x \doteq f_y$

$$\begin{aligned} f(b) \Rightarrow f_b \quad f(a) \Rightarrow f_a \\ (f_b \doteq a \vee f_a \not\doteq a) \wedge (a \doteq b \Rightarrow f_a \doteq f_b) \end{aligned}$$

Now, atomic formulas are equalities between constants/variables

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Rename f_b as c and f_a as d :

$$(f_b \doteq a \vee f_a \not\doteq a) \wedge (a \doteq b \Rightarrow f_a \doteq f_b)$$

becomes

$$(c \doteq a \vee d \not\doteq a) \wedge (a \doteq b \Rightarrow d \doteq c)$$

Step 2: Eliminate all equalities

- replace each pair of constants x, y with a unique propositional variable $p_{x,y}$
- add facts about reflexivity, symmetry, transitivity

$$\begin{aligned} & (p_{c,a} \vee \neg p_{d,a}) \wedge (p_{a,b} \Rightarrow p_{d,c}) \\ & \wedge p_{a,a} \wedge p_{b,b} \wedge p_{c,c} \wedge p_{d,d} \wedge (p_{a,b} \Leftrightarrow p_{b,a}) \wedge (p_{a,c} \Leftrightarrow p_{c,a}) \wedge (p_{a,d} \Leftrightarrow p_{d,a}) \wedge \dots \\ & \wedge ((p_{a,b} \wedge p_{b,c}) \Rightarrow p_{a,c}) \wedge ((p_{a,c} \wedge p_{c,d}) \Rightarrow p_{a,d}) \wedge \dots \end{aligned}$$

The resulting propositional formula is equisatisfiable with the original T_{EUF} -formula

Note: Not all the transitivity cases are needed

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Discussion: eager vs. lazy approach

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What are the pros and cons of the two approaches?

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Pros and cons: eager vs. lazy approach

Eager

- Can always use the best SAT solver off the shelf
- Requires care in encoding
- Tends not to scale well

Lazy

- Theory-specific reasoning
- Designing new theory solvers can be challenging
- Might require extension of a SAT solver for more efficiency interplay with theory solver
- Scales much better

Lazy Approach – Enhancements

Several enhancements are possible to increase efficiency:

- Check \mathcal{T} -satisfiability only of full propositional model

Check \mathcal{T} -satisfiability of partial assignment M as it grows

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Lazy Approach – Enhancements

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Lazy Approach – Main Benefits

Every tool does what it is good at:

- SAT solver takes care of Boolean information
- Theory solver takes care of theory information

The theory solver works only with conjunctions of literals

Modular approach:

- SAT and theory solvers communicate via a simple API
- SMT for a new theory only requires new theory solver
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An Abstract Framework for Lazy SMT

Several variants and enhancements of lazy SMT solvers exist

They can be modeled a satisfiability proof system like those for Abstract DPLL and Abstract CDCL

Review: Abstract DPLL

States:

UNSAT

$\langle M, \Delta \rangle$

where

- M is a *sequence of literals* and *decision points* (\bullet) denoting a **partial variable assignment**
- Δ is a *set of clauses* denoting a CNF formula

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Note: When convenient, we treat M as a set

Provided M contains no complementary literals it determines the assignment

$$v_M(p) = \begin{cases} \text{true} & \text{if } p \in M \\ \text{false} & \text{if } \neg p \in M \\ \text{undef} & \text{otherwise} \end{cases}$$

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Notation: If $M = M_0 \bullet M_1 \bullet \dots \bullet M_n$ where each M_i contains no decision points

- M_i is *decision level* i of M
- $M^{[i]}$ denotes the subsequence $M_0 \bullet \dots \bullet M_i$, from decision level 0 through decision level i

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Initial state:

- $\langle \epsilon, \Delta_0 \rangle$ where ϵ is the empty assignment and Δ_0 is to be checked for satisfiability

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Expected final states:

- UNSAT if Δ_0 is unsatisfiable
- $\langle M, \Delta_n \rangle$ otherwise, where Δ_n is equisatisfiable with Δ_0 and satisfied by M

Review: Abstract CDCL

States:

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$\langle M, \Delta, C \rangle$

where

- M and Δ are as in Abstract DPLL
- C is either **no** or a *conflict clause*

Initial state:

- $\langle \epsilon, \Delta_0, \text{no} \rangle$, where Δ_0 is to be checked for satisfiability

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Review: CDCL proof rules

$$\begin{array}{l}
 \text{DECIDE} \frac{l \in \text{Lits}(\Delta) \quad l, \bar{l} \notin M}{M := M \bullet l} \\
 \\
 \text{FAIL} \frac{C \neq \text{no} \quad \bullet \notin M}{\text{UNSAT}} \\
 \\
 \text{RESTART} \frac{}{M := M^{[0]} \quad C := \text{no}} \\
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 \text{LEARN} \frac{D \text{ is a clause} \quad \Delta \models D \quad D \notin \Delta}{\Delta := \Delta \cup \{D\}} \\
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 \text{PROPAGATE} \frac{\{l_1, \dots, l_n, l\} \in \Delta \quad \bar{l}_1, \dots, \bar{l}_n \in M \quad l, \bar{l} \notin M}{M := M l} \\
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 \text{EXPLAIN} \frac{C = \{l\} \cup C' \quad \{l_1, \dots, l_n, \bar{l}\} \in \Delta \quad \bar{l}_1, \dots, \bar{l}_n, \bar{l} \in M \quad \bar{l}_1, \dots, \bar{l}_n \prec_M \bar{l}}{C := \{l_1, \dots, l_n\} \cup C'} \\
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 \text{BACKJUMP} \frac{C = D \quad D = \{l_1, \dots, l_n, l\} \quad \text{lev}(\bar{l}_1), \dots, \text{lev}(\bar{l}_n) \leq i < \text{lev}(\bar{l})}{M := M^{[i]} l \quad C := \text{no} \quad \Delta := \Delta \cup \{D\}} \\
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 \text{FORGET} \frac{C = \text{no} \quad \Delta = \Delta' \cup \{C\} \quad \Delta' \models C}{\Delta := \Delta'}
 \end{array}$$

We are going to extend this abstract framework to lazy SMT

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We are going to **extend** this abstract framework **to lazy SMT**

From SAT to SMT

Same state components and transitions as in Abstract CDCL **except** that

- Δ contains quantifier-free clauses in some theory \mathcal{T}
- M is a sequence of theory literals (i.e., atomic formulas or their negations) and decision points
- CDCL Rules operate on the Boolean skeleton of Δ , given by a mapping from theory literals to propositional literals
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SMT-level Rules

At SAT level:

$$\text{Conflict} \frac{C = \text{no} \quad \{l_1, \dots, l_n\} \in \Delta \quad \bar{l}_1, \dots, \bar{l}_n \in M}{C := \{l_1, \dots, l_n\}}$$

At SMT level:

$$\mathcal{T}\text{-Conflict} \frac{C = \text{no} \quad \bar{l}_1 \wedge \dots \wedge \bar{l}_n \models_{\mathcal{T}} \perp \quad \bar{l}_1, \dots, \bar{l}_n \in M}{C := \{l_1, \dots, l_n\}}$$

If a **set of literals** in M are unsatisfiable in \mathcal{T} , make their **negation** a conflict clause

SMT-level Rules

At SAT level:

$$\text{PROPAGATE} \frac{\{l_1, \dots, l_n, l\} \in \Delta \quad \bar{l}_1, \dots, \bar{l}_n \in M \quad l, \bar{l} \notin M}{M := M \, l}$$

At SMT level:

$$\mathcal{T}\text{-PROPAGATE} \frac{l \in \text{Lits}(\Delta) \quad M \models_{\mathcal{T}} l \quad l, \bar{l} \notin M}{M := M \, l}$$

If M entails some literal l in \mathcal{T} , extend it with l

SMT-level Rules

At SAT level:

$$\text{EXPLAIN} \frac{C = \{l\} \cup C' \quad \{l_1, \dots, l_n, \bar{l}\} \in \Delta \quad \bar{l}_1, \dots, \bar{l}_n, \bar{l} \in M \quad \bar{l}_1, \dots, \bar{l}_n \prec_M \bar{l}}{C := \{l_1, \dots, l_n\} \cup C'}$$

At SMT level:

$$\mathcal{T}\text{-EXPLAIN} \frac{C = \{l\} \cup D \quad \bar{l}_1 \wedge \dots \wedge \bar{l}_n \models_{\mathcal{T}} \bar{l} \quad \bar{l}_1, \dots, \bar{l}_n \prec_M \bar{l}}{C := \{l_1, \dots, l_n\} \cup D}$$

If the complement \bar{l} of a literal in the conflict clause is entailed in \mathcal{T} by some literals $\bar{l}_1, \dots, \bar{l}_n$ at lower decision levels, **derive a new conflict clause** by resolution with $\{l_1, \dots, l_n, \bar{l}\}$

CDCL Modulo Theories proof rules

$$\text{DECIDE} \frac{l \in \text{Lits}(\Delta) \quad l, \bar{l} \notin M}{M := M \bullet l}$$

$$\text{FAIL} \frac{C \neq \text{no} \quad \bullet \notin M}{\text{UNSAT}}$$

$$\text{RESTART} \frac{}{M := M^{[0]} \quad C := \text{no}}$$

$$\text{LEARN} \frac{D \text{ is a clause} \quad \Delta \models D \quad D \notin \Delta}{\Delta := \Delta \cup \{D\}}$$

$$\text{FORGET} \frac{C = \text{no} \quad \Delta = \Delta' \cup \{C\} \quad \Delta' \models C}{\Delta := \Delta'}$$

$$\mathcal{T}\text{-PROPAGATE} \frac{l \in \text{Lits}(\Delta) \quad M \models_{\mathcal{T}} l \quad l, \bar{l} \notin M}{M := M \upharpoonright l}$$

$$\mathcal{T}\text{-CONFLICT} \frac{C = \text{no} \quad \bar{l}_1 \wedge \dots \wedge \bar{l}_n \models_{\mathcal{T}} \perp \quad \bar{l}_1, \dots, \bar{l}_n \in M}{C := \{l_1, \dots, l_n\}}$$

$$\mathcal{T}\text{-EXPLAIN} \frac{C = \{l\} \cup D \quad \bar{l}_1 \wedge \dots \wedge \bar{l}_n \models_{\mathcal{T}} \bar{l} \quad \bar{l}_1, \dots, \bar{l}_n \prec_M \bar{l}}{C := \{l_1, \dots, l_n\} \cup D}$$

$$\text{PROPAGATE} \frac{\{l_1, \dots, l_n, l\} \in \Delta \quad \bar{l}_1, \dots, \bar{l}_n \in M \quad l, \bar{l} \notin M}{M := M \upharpoonright l}$$

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$$\text{BACKJUMP} \frac{C = D \quad D = \{l_1, \dots, l_n, l\} \quad \text{lev}(\bar{l}_1), \dots, \text{lev}(\bar{l}_n) \leq i < \text{lev}(\bar{l})}{M := M^{[i]} \upharpoonright l \quad C := \text{no} \quad \Delta := \Delta \cup \{D\}}$$

$$\text{CONFLICT} \frac{C = \text{no} \quad \{l_1, \dots, l_n\} \in \Delta \quad \bar{l}_1, \dots, \bar{l}_n \in M}{C := \{l_1, \dots, l_n\}}$$

Modeling the Very Lazy Theory Approach

\mathcal{T} -CONFLICT is enough to model the naive integration of SAT solvers and theory solvers seen in the earlier EUF example

$$\underbrace{g(a) \doteq c}_1 \wedge \underbrace{f(g(a)) \neq f(c)}_2 \vee \underbrace{g(a) \doteq d}_3 \wedge \underbrace{c \neq d}_4$$

| M | Δ | C | rule |
|----------------------|--|-------------------------------|----------------------------|
| | $1, 2 \vee 3, 4$ | no | |
| $1\bar{4}$ | $1, 2 \vee 3, \bar{4}$ | no | by PROPAGATE ⁺ |
| $1\bar{4} * \bar{2}$ | $1, 2 \vee 3, \bar{4}$ | no | by DECIDE |
| $1\bar{4} * \bar{2}$ | $1, 2 \vee 3, \bar{4}$ | $\bar{1} \vee 2 \vee 4$ | by \mathcal{T} -CONFLICT |
| $1\bar{4} * \bar{2}$ | $1, 2 \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | $\bar{1} \vee 2 \vee 4$ | by LEARN |
| $1\bar{4}$ | $1, 2 \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | no | by RESTART |
| $1\bar{4} 2 3$ | $1, 2 \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | no | by PROPAGATE ⁺ |
| $1\bar{4} 2 3$ | $1, 2 \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | $\bar{1} \vee \bar{3} \vee 4$ | by \mathcal{T} -CONFLICT |
| $1\bar{4} 2 3$ | $1, 2 \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4, \bar{1} \vee \bar{3} \vee 4$ | no | by LEARN |
| \vdots | | | |
| UNSAT | | | by UNSAT |

Modeling the Very Lazy Theory Approach

$$\underbrace{g(a) \doteq c}_1 \wedge \underbrace{f(g(a)) \neq f(c)}_{\bar{2}} \vee \underbrace{g(a) \doteq d}_3 \wedge \underbrace{c \neq d}_{\bar{4}}$$

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| | 1, 2 \vee 3, 4 | no | |
| 1 $\bar{4}$ | 1, $\bar{2}$ \vee 3, $\bar{4}$ | no | by PROPAGATE ⁺ |
| 1 $\bar{4}$ * 2 | 1, 2 \vee 3, $\bar{4}$ | no | by DECIDE |
| 1 $\bar{4}$ * $\bar{2}$ | 1, $\bar{2}$ \vee 3, $\bar{4}$ | $\bar{1}$ \vee 2 \vee 4 | by T-CONFLICT |
| 1 $\bar{4}$ * $\bar{2}$ | 1, $\bar{2}$ \vee 3, $\bar{4}$, $\bar{1}$ \vee 2 \vee 4 | $\bar{1}$ \vee 2 \vee 4 | by LEARN |
| 1 $\bar{4}$ | 1, $\bar{2}$ \vee 3, $\bar{4}$, $\bar{1}$ \vee 2 \vee 4 | no | by RESTART |
| 1 $\bar{4}$ 2 3 | 1, $\bar{2}$ \vee 3, $\bar{4}$, $\bar{1}$ \vee 2 \vee 4 | no | by PROPAGATE ⁺ |
| 1 $\bar{4}$ 2 3 | 1, $\bar{2}$ \vee 3, $\bar{4}$, $\bar{1}$ \vee 2 \vee 4 | $\bar{1}$ \vee 3 \vee 4 | by T-CONFLICT |
| 1 $\bar{4}$ 2 3 | 1, $\bar{2}$ \vee 3, $\bar{4}$, $\bar{1}$ \vee 2 \vee 4, $\bar{1}$ \vee 3 \vee 4 | no | by LEARN |
| ... | | | |
| UNSAT | | | by FAIL |

Modeling the Very Lazy Theory Approach

$$\underbrace{g(a) \doteq c}_1 \wedge \underbrace{f(g(a)) \neq f(c)}_{\bar{2}} \vee \underbrace{g(a) \doteq d}_3 \wedge \underbrace{c \neq d}_4$$

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|----------------------|--|-------------------------|---------------------------|
| | $1, \bar{2} \vee 3, \bar{4}$ | no | |
| $1\bar{4}$ | $1, \bar{2} \vee 3, \bar{4}$ | no | by PROPAGATE ⁺ |
| $1\bar{4} * 2$ | $1, \bar{2} \vee 3, \bar{4}$ | no | by DECIDE |
| $1\bar{4} * \bar{2}$ | $1, \bar{2} \vee 3, \bar{4}$ | $\bar{1} \vee 2 \vee 4$ | by T-CONFLICT |
| $1\bar{4} * \bar{2}$ | $1, \bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | $\bar{1} \vee 2 \vee 4$ | by LEARN |
| $1\bar{4}$ | $1, \bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | no | by RESTART |
| $1\bar{4} 2 3$ | $1, \bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | no | by PROPAGATE ⁺ |
| $1\bar{4} 2 3$ | $1, \bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | $\bar{1} \vee 3 \vee 4$ | by T-CONFLICT |
| $1\bar{4} 2 3$ | $1, \bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4, \bar{1} \vee 3 \vee 4$ | no | by LEARN |
| \vdots | | | |
| | UNSAT | | by FAIL |

Modeling the Very Lazy Theory Approach

$$\underbrace{g(a) \doteq c}_1 \wedge \underbrace{f(g(a)) \not\doteq f(c)}_{\bar{2}} \vee \underbrace{g(a) \doteq d}_3 \wedge \underbrace{c \not\doteq d}_{\bar{4}}$$

| M | Δ | C | rule |
|-----------------------|--|-------------------------|----------------------------------|
| | $1, \bar{2} \vee 3, \bar{4}$ | no | |
| $1 \bar{4}$ | $1, \bar{2} \vee 3, \bar{4}$ | no | by PROPAGATE ⁺ |
| $1 \bar{4} * 2$ | $1, \bar{2} \vee 3, \bar{4}$ | no | by DECIDE |
| $1 \bar{4} * \bar{2}$ | $1, \bar{2} \vee 3, \bar{4}$ | $\bar{1} \vee 2 \vee 4$ | by T-CONFLICT |
| $1 \bar{4} * \bar{2}$ | $1, \bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | $\bar{1} \vee 2 \vee 4$ | by LEARN |
| $1 \bar{4}$ | $1, \bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | no | by RESTART |
| $1 \bar{4} 2 3$ | $1, \bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | no | by PROPAGATE ⁺ |
| $1 \bar{4} 2 3$ | $1, \bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | $\bar{1} \vee 3 \vee 4$ | by T-CONFLICT |
| $1 \bar{4} 2 3$ | $1, \bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4, \bar{1} \vee 3 \vee 4$ | no | by LEARN |
| \vdots | | | |
| | UNSAT | | by FAIL |

Modeling the Very Lazy Theory Approach

$$\underbrace{g(a) \doteq c}_1 \wedge \underbrace{f(g(a)) \neq f(c)}_{\bar{2}} \vee \underbrace{g(a) \doteq d}_3 \wedge \underbrace{c \neq d}_{\bar{4}}$$

| M | Δ | C | rule |
|-----------------------------|--|-------------------------|---------------------------------|
| | $1, \bar{2} \vee 3, \bar{4}$ | no | |
| $1 \bar{4}$ | $1, \bar{2} \vee 3, \bar{4}$ | no | by PROPAGATE⁺ |
| $1 \bar{4} \bullet \bar{2}$ | $1, \bar{2} \vee 3, \bar{4}$ | no | by DECIDE |
| $1 \bar{4} \bullet 2$ | $1, \bar{2} \vee 3, \bar{4}$ | $\bar{1} \vee 2 \vee 4$ | by T-CONFLICT |
| $1 \bar{4} \bullet \bar{2}$ | $1, \bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | $\bar{1} \vee 2 \vee 4$ | by LEARN |
| $1 \bar{4}$ | $1, \bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | no | by RESTART |
| $1 \bar{4} 2 3$ | $1, \bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | no | by PROPAGATE⁺ |
| $1 \bar{4} 2 3$ | $1, \bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | $\bar{1} \vee 3 \vee 4$ | by T-CONFLICT |
| $1 \bar{4} 2 3$ | $1, \bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4, \bar{1} \vee 3 \vee 4$ | no | by LEARN |
| \vdots | | | |
| \vdots | | | |
| | UNSAT | | by FAIL |

Modeling the Very Lazy Theory Approach

$$\underbrace{g(a) \doteq c}_1 \wedge \underbrace{f(g(a)) \neq f(c)}_{\bar{2}} \vee \underbrace{g(a) \doteq d}_3 \wedge \underbrace{c \neq d}_{\bar{4}}$$

| M | Δ | C | rule |
|-----------------------------|--|-------------------------|----------------------------------|
| | 1, $\bar{2} \vee 3, \bar{4}$ | no | |
| 1 $\bar{4}$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by PROPAGATE ⁺ |
| 1 $\bar{4} \bullet \bar{2}$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by DECIDE |
| 1 $\bar{4} \bullet \bar{2}$ | 1, $\bar{2} \vee 3, \bar{4}$ | $\bar{1} \vee 2 \vee 4$ | by T-CONFLICT |
| 1 $\bar{4} \bullet \bar{2}$ | 1, $\bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | $\bar{1} \vee 2 \vee 4$ | by LEARN |
| 1 $\bar{4}$ | 1, $\bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | no | by RESTART |
| 1 $\bar{4} 2 3$ | 1, $\bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | no | by PROPAGATE ⁺ |
| 1 $\bar{4} 2 3$ | 1, $\bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | $\bar{1} \vee 3 \vee 4$ | by T-CONFLICT |
| 1 $\bar{4} 2 3$ | 1, $\bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4, \bar{1} \vee 3 \vee 4$ | no | by LEARN |
| ... | | | |
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Modeling the Very Lazy Theory Approach

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| M | Δ | C | rule |
|-----------------------------|--|-------------------------|----------------------------------|
| | 1, $\bar{2} \vee 3, \bar{4}$ | no | |
| 1 $\bar{4}$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by PROPAGATE ⁺ |
| 1 $\bar{4} \bullet \bar{2}$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by DECIDE |
| 1 $\bar{4} \bullet \bar{2}$ | 1, $\bar{2} \vee 3, \bar{4}$ | $\bar{1} \vee 2 \vee 4$ | by T-CONFLICT |
| 1 $\bar{4} \bullet \bar{2}$ | 1, $\bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | $\bar{1} \vee 2 \vee 4$ | by LEARN |
| 1 $\bar{4}$ | 1, $\bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | no | by RESTART |
| 1 $\bar{4} 2 3$ | 1, $\bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | no | by PROPAGATE ⁺ |
| 1 $\bar{4} 2 3$ | 1, $\bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | $\bar{1} \vee 3 \vee 4$ | by T-CONFLICT |
| 1 $\bar{4} 2 3$ | 1, $\bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4, \bar{1} \vee 3 \vee 4$ | no | by LEARN |
| ... | | | |
| | UNSAT | | by FAIL |

Modeling the Very Lazy Theory Approach

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| M | Δ | C | rule |
|-----------------------------|--|-------------------------|----------------------------------|
| | 1, $\bar{2} \vee 3, \bar{4}$ | no | |
| 1 $\bar{4}$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by PROPAGATE ⁺ |
| 1 $\bar{4} \bullet \bar{2}$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by DECIDE |
| 1 $\bar{4} \bullet \bar{2}$ | 1, $\bar{2} \vee 3, \bar{4}$ | $\bar{1} \vee 2 \vee 4$ | by T-CONFLICT |
| 1 $\bar{4} \bullet \bar{2}$ | 1, $\bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | $\bar{1} \vee 2 \vee 4$ | by LEARN |
| 1 $\bar{4}$ | 1, $\bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | no | by RESTART |
| 1 $\bar{4} 2 3$ | 1, $\bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | no | by PROPAGATE ⁺ |
| 1 $\bar{4} 2 3$ | 1, $\bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | $\bar{1} \vee 3 \vee 4$ | by T-CONFLICT |
| 1 $\bar{4} 2 3$ | 1, $\bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4, \bar{1} \vee 3 \vee 4$ | no | by LEARN |
| ... | | | |
| | UNSAT | | by FAIL |

Modeling the Very Lazy Theory Approach

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| M | Δ | C | rule |
|-----------------------------|--|-------------------------|----------------------------------|
| | 1, $\bar{2} \vee 3, \bar{4}$ | no | |
| 1 $\bar{4}$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by PROPAGATE ⁺ |
| 1 $\bar{4} \bullet \bar{2}$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by DECIDE |
| 1 $\bar{4} \bullet \bar{2}$ | 1, $\bar{2} \vee 3, \bar{4}$ | $\bar{1} \vee 2 \vee 4$ | by T-CONFLICT |
| 1 $\bar{4} \bullet \bar{2}$ | 1, $\bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | $\bar{1} \vee 2 \vee 4$ | by LEARN |
| 1 $\bar{4}$ | 1, $\bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | no | by RESTART |
| 1 $\bar{4} 2 3$ | 1, $\bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | no | by PROPAGATE ⁺ |
| 1 $\bar{4} 2 3$ | 1, $\bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | $\bar{1} \vee 3 \vee 4$ | by T-CONFLICT |
| 1 $\bar{4} 2 3$ | 1, $\bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4, \bar{1} \vee 3 \vee 4$ | no | by LEARN |
| ... | ... | ... | ... |
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Modeling the Very Lazy Theory Approach

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|-----------------------------|--|-------------------------------|---------------------------|
| | 1, $\bar{2} \vee 3, \bar{4}$ | no | |
| 1 $\bar{4}$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by PROPAGATE ⁺ |
| 1 $\bar{4} \bullet \bar{2}$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by DECIDE |
| 1 $\bar{4} \bullet \bar{2}$ | 1, $\bar{2} \vee 3, \bar{4}$ | $\bar{1} \vee 2 \vee 4$ | by T-CONFLICT |
| 1 $\bar{4} \bullet \bar{2}$ | 1, $\bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | $\bar{1} \vee 2 \vee 4$ | by LEARN |
| 1 $\bar{4}$ | 1, $\bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | no | by RESTART |
| 1 $\bar{4} 2 3$ | 1, $\bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | no | by PROPAGATE ⁺ |
| 1 $\bar{4} 2 3$ | 1, $\bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | $\bar{1} \vee \bar{3} \vee 4$ | by T-CONFLICT |
| 1 $\bar{4} 2 3$ | 1, $\bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4, \bar{1} \vee \bar{3} \vee 4$ | no | by LEARN |
| ... | | | |
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|-----------------------------|--|-------------------------------|----------------------------------|
| | 1, $\bar{2} \vee 3, \bar{4}$ | no | |
| 1 $\bar{4}$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by PROPAGATE ⁺ |
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| 1 $\bar{4} \bullet \bar{2}$ | 1, $\bar{2} \vee 3, \bar{4}$ | $\bar{1} \vee 2 \vee 4$ | by T-CONFLICT |
| 1 $\bar{4} \bullet \bar{2}$ | 1, $\bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | $\bar{1} \vee 2 \vee 4$ | by LEARN |
| 1 $\bar{4}$ | 1, $\bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | no | by RESTART |
| 1 $\bar{4} 2 3$ | 1, $\bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | no | by PROPAGATE ⁺ |
| 1 $\bar{4} 2 3$ | 1, $\bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4$ | $\bar{1} \vee \bar{3} \vee 4$ | by T-CONFLICT |
| 1 $\bar{4} 2 3$ | 1, $\bar{2} \vee 3, \bar{4}, \bar{1} \vee 2 \vee 4, \bar{1} \vee \bar{3} \vee 4$ | no | by LEARN |
| | \vdots | | |
| | UNSAT | | by FAIL |

A Better Lazy Approach

The very lazy approach can be improved considerably with

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| M | Δ | C | rule |
|----------------------|------------------------------|-------------------------------|----------------------------|
| | $1, \bar{2} \vee 3, 4$ | no | |
| $1\bar{4}$ | $1, \bar{2} \vee 3, \bar{4}$ | no | by PROPAGATE ⁺ |
| $1\bar{4} * \bar{2}$ | $1, \bar{2} \vee 3, \bar{4}$ | no | by DECIDE |
| $1\bar{4} * \bar{2}$ | $1, \bar{2} \vee 3, \bar{4}$ | $\bar{1} \vee 2$ | by \mathcal{T} -CONFLICT |
| $1\bar{4}2$ | $1, \bar{2} \vee 3, \bar{4}$ | no | by BACKJUMP |
| $1\bar{4}23$ | $1, \bar{2} \vee 3, \bar{4}$ | no | by PROPAGATE |
| $1\bar{4}23$ | $1, \bar{2} \vee 3, \bar{4}$ | $\bar{1} \vee \bar{3} \vee 4$ | by \mathcal{T} -CONFLICT |
| UNSAT | | | by FAIL |

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| M | Δ | C | rule |
|-----------------------|------------------------------|-------------------------------|----------------------------|
| | 1, $\bar{2} \vee 3, \bar{4}$ | no | |
| 1 $\bar{4}$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by PROPAGATE ⁺ |
| 1 $\bar{4} * \bar{2}$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by DECIDE |
| 1 $\bar{4} * \bar{2}$ | 1, $\bar{2} \vee 3, \bar{4}$ | $\bar{1} \vee 2$ | by \mathcal{T} -CONFLICT |
| 1 $\bar{4} 2$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by BACKJUMP |
| 1 $\bar{4} 2 3$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by PROPAGATE |
| 1 $\bar{4} 2 3$ | 1, $\bar{2} \vee 3, \bar{4}$ | $\bar{1} \vee \bar{3} \vee 4$ | by \mathcal{T} -CONFLICT |
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| M | Δ | C | rule |
|-----------------------|------------------------------|-------------------------------|---------------------------------|
| | 1, $\bar{2} \vee 3, \bar{4}$ | no | |
| 1 $\bar{4}$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by PROPAGATE⁺ |
| 1 $\bar{4} * \bar{2}$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by DECIDE |
| 1 $\bar{4} * \bar{2}$ | 1, $\bar{2} \vee 3, \bar{4}$ | $\bar{1} \vee 2$ | by T-Conflict |
| 1 $\bar{4} 2$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by BACKJUMP |
| 1 $\bar{4} 2 3$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by PROPAGATE |
| 1 $\bar{4} 2 3$ | 1, $\bar{2} \vee 3, \bar{4}$ | $\bar{1} \vee \bar{3} \vee 4$ | by T-Conflict |
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| M | Δ | C | rule |
|-----------------------------|------------------------------|-------------------------------------|---------------------------------|
| | 1, $\bar{2} \vee 3, \bar{4}$ | no | |
| 1 $\bar{4}$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by PROPAGATE⁺ |
| 1 $\bar{4} \bullet \bar{2}$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by DECIDE |
| 1 $\bar{4} \ast \bar{2}$ | 1, $\bar{2} \vee 3, \bar{4}$ | $\bar{1} \vee \bar{2}$ | by T-Conflict |
| 1 $\bar{4} \bar{2}$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by BACKJUMP |
| 1 $\bar{4} \bar{2} 3$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by PROPAGATE |
| 1 $\bar{4} \bar{2} 3$ | 1, $\bar{2} \vee 3, \bar{4}$ | $\bar{1} \vee \bar{3} \vee \bar{4}$ | by T-Conflict |
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| 1 $\bar{4} \bullet \bar{2}$ | 1, $\bar{2} \vee 3, \bar{4}$ | $\bar{1} \vee 2$ | by T-Conflict |
| 1 $\bar{4} 2$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by BACKJUMP |
| 1 $\bar{4} 2 3$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by PROPAGATE |
| 1 $\bar{4} 2 3$ | 1, $\bar{2} \vee 3, \bar{4}$ | $\bar{1} \vee \bar{3} \vee 4$ | by T-Conflict |
| UNSAT | | | by FAIL |

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| M | Δ | C | rule |
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| | 1, $\bar{2} \vee 3, \bar{4}$ | no | |
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| 1 $\bar{4} \bullet \bar{2}$ | 1, $\bar{2} \vee 3, \bar{4}$ | $\bar{1} \vee 2$ | by T-Conflict |
| 1 $\bar{4} 2$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by BACKJUMP |
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| | 1, $\bar{2} \vee 3, \bar{4}$ | no | |
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| 1 $\bar{4} 2$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by BACKJUMP |
| 1 $\bar{4} 2 3$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by PROPAGATE |
| 1 $\bar{4} 2 3$ | 1, $\bar{2} \vee 3, \bar{4}$ | $\bar{1} \vee 3 \vee 4$ | by T-Conflict |
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| M | Δ | C | rule |
|-----------------------------|------------------------------|-------------------------------|----------------------------------|
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| 1 $\bar{4}$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by PROPAGATE ⁺ |
| 1 $\bar{4} \bullet \bar{2}$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by DECIDE |
| 1 $\bar{4} \bullet \bar{2}$ | 1, $\bar{2} \vee 3, \bar{4}$ | $\bar{1} \vee 2$ | by T-Conflict |
| 1 $\bar{4} 2$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by BACKJUMP |
| 1 $\bar{4} 2 3$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by PROPAGATE |
| 1 $\bar{4} 2 3$ | 1, $\bar{2} \vee 3, \bar{4}$ | $\bar{1} \vee \bar{3} \vee 4$ | by T-Conflict |
| UNSAT | | by FAIL | |

A Better Lazy Approach

$$\underbrace{g(a) \doteq c}_1 \wedge \underbrace{f(g(a)) \neq f(c)}_{\bar{2}} \vee \underbrace{g(a) \doteq d}_3 \wedge \underbrace{c \neq d}_{\bar{4}}$$

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| 1 $\bar{4} 2$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by BACKJUMP |
| 1 $\bar{4} 2 3$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by PROPAGATE |
| 1 $\bar{4} 2 3$ | 1, $\bar{2} \vee 3, \bar{4}$ | $\bar{1} \vee \bar{3} \vee 4$ | by T-Conflict |
| UNSAT | | | by FAIL |

Lazy Approach – Strategies

Ignoring **RESTART** (for simplicity), a **common strategy** is to apply the rules using the following priorities:

1. If a clause is (propositionally) falsified by the current assignment **M**, apply **Conflict**
2. If **M** is **T**-unsatisfiable, apply **T-Conflict**
3. Apply **FAIL** or **EXPLAIN+LEARN+BACKJUMP** as appropriate
4. Apply **PROPAGATE**
5. Apply **DECIDE**

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Step (2) can be applied with lower frequency or priority

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Theory Propagation

With \mathcal{T} -CONFLICT as the **only theory rule**, the theory solver is used just to **validate** the choices of the SAT engine

With \mathcal{T} -PROPAGATE and \mathcal{T} -EXPLAIN, it can also be used to guide the engine's search

$$\mathcal{T}\text{-PROPAGATE} \frac{l \in \text{Lits}(\Delta) \quad M \models_{\mathcal{T}} l \quad l, \bar{l} \notin M}{M := M \cup l}$$

$$\mathcal{T}\text{-EXPLAIN} \frac{C = \{l\} \cup D \quad \bar{l}_1 \wedge \dots \wedge \bar{l}_n \models_{\mathcal{T}} \bar{l} \quad \bar{l}_1, \dots, \bar{l}_n \prec_M \bar{l}}{C := \{l_1, \dots, l_n\} \cup D}$$

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$$\underbrace{g(a) \doteq c}_1 \wedge \underbrace{f(g(a)) \not\doteq f(c)}_{\bar{2}} \vee \underbrace{g(a) \doteq d}_3 \wedge \underbrace{c \not\doteq d}_{\bar{4}}$$

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| 1 $\bar{4}$ | 1, $\bar{2} \vee 3, \bar{4}$ | no | by PROPAGATE ⁺ |
| 1 $\bar{4}$ 2 | 1, $\bar{2} \vee 3, \bar{4}$ | no | by \mathcal{T} -PROPAGATE (as $1 \models_{\mathcal{T}} 2$) |
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Theory Propagation Features

- With *exhaustive* theory propagation, every assignment M is \mathcal{T} -satisfiable (since $M \models \mathcal{T}$ is \mathcal{T} -unsatisfiable iff $M \models_{\mathcal{T}} \bar{I}$)
- For theory propagation to be effective in practice, it needs specialized theory solvers
- For some theories, e.g., *difference logic*, detecting \mathcal{T} -entailed literals is cheap and so exhaustive theory propagation is *extremely effective*
- For others, e.g., the *theory of equality*, detecting \mathcal{T} -entailed equalities is cheap but detecting \mathcal{T} -entailed disequalities is quite expensive
- If \mathcal{T} -PROPAGATE is not applied exhaustively, \mathcal{T} -CONFLICT is needed to repair \mathcal{T} -unsatisfiable assignments

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Theory Propagation Exercise

$$\underbrace{a \doteq b}_1 \wedge \underbrace{a \doteq c}_2 \vee \underbrace{c \doteq b}_3 \wedge \underbrace{a \not\doteq b}_{\bar{1}} \vee \underbrace{f(a) \not\doteq f(c)}_{\bar{4}} \wedge \underbrace{c \not\doteq b}_{\bar{3}} \vee \underbrace{g(a) \doteq g(c)}_5$$

$$\Delta_0 := 1, 2 \vee 3, \bar{1} \vee \bar{4}, \bar{3} \vee 5$$

Theory Propagation Exercise

Scenario 1: propagating **only** \mathcal{T} -entailed **equalities** (no disequalities)

$$\underbrace{a \doteq b}_1 \wedge \underbrace{a \doteq c}_2 \vee \underbrace{c \doteq b}_3 \wedge \underbrace{a \not\doteq b}_{\bar{1}} \vee \underbrace{f(a) \not\doteq f(c)}_{\bar{4}} \wedge \underbrace{c \not\doteq b}_{\bar{3}} \vee \underbrace{g(a) \doteq g(c)}_5$$

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| M | Δ | C | rule |
|-----------------------|----------------------------|-------------------------------|---|
| | Δ_0 | no | |
| $1 \bar{4}$ | Δ_0 | no | by PROPAGATE ⁺ |
| $1 \bar{4} \bullet 2$ | Δ_0 | no | by DECIDE |
| $1 \bar{4} \bullet 2$ | Δ_0 | $\bar{2} \vee 4$ | by \mathcal{T}-CONFLICT (as $2, \bar{4} \models_{\mathcal{T}} \perp$) |
| $1 \bar{4} \bar{2}$ | $\Delta_0, \bar{2} \vee 4$ | no | by BACKJUMP |
| $1 \bar{4} \bar{2} 3$ | $\Delta_0, \bar{2} \vee 4$ | no | by PROPAGATE |
| $1 \bar{4} \bar{2} 3$ | $\Delta_0, \bar{2} \vee 4$ | $\bar{1} \vee \bar{3} \vee 4$ | by \mathcal{T}-CONFLICT (as $1, \bar{3}, \bar{4} \models_{\mathcal{T}} \perp$) |
| UNSAT | | | by FAIL |

Theory Propagation Exercise

Scenario 2: propagating \mathcal{T} -entailed **equalities and disequalities**

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| 1 $\bar{4}$ | Δ_0 | no | by PROPAGATE ⁺ |
| 1 $\bar{4}$ $\bar{2}$ | $\Delta_0, \bar{2} \vee 4$ | no | by \mathcal{T}-PROPAGATE (as $1, \bar{4} \models_{\mathcal{T}} \bar{2}$) |
| 1 $\bar{4}$ $\bar{2}$ 3 | $\Delta_0, \bar{2} \vee 4$ | no | by PROPAGATE |
| 1 $\bar{4}$ $\bar{2}$ 3 | $\Delta_0, \bar{2} \vee 4$ | $\bar{1} \vee \bar{3} \vee 4$ | by \mathcal{T}-CONFLICT (as $1, 3, \bar{4} \models_{\mathcal{T}} \perp$) |
| UNSAT | | | by FAIL |

Modeling Modern Lazy SMT Solvers

At the core, current lazy SMT solvers are implementations of the proof system with rules:

(1) **PROPAGATE, DECIDE, CONFLICT, EXPLAIN, BACKJUMP, FAIL**

(2) \mathcal{T} -CONFLICT, \mathcal{T} -PROPAGATE, \mathcal{T} -EXPLAIN

(3) **LEARN, FORGET, RESTART**

Basic CDCL Modulo Theories $\stackrel{\text{def}}{=} (1) + (2)$

CDCL Modulo Theories $\stackrel{\text{def}}{=} (1) + (2) + (3)$

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Correctness

Irreducible state: state to which no **Basic CDCL Modulo Theories** rules apply (updated terminology)

Execution: a (single-branch) derivation tree starting with $M = \emptyset$ and $C = \text{no}$

Exhausted execution: execution ending in an irreducible state

Theorem 2 (Strong Termination)

Every execution in which (i) LEARN/FORGET are applied only finitely many times and (ii) RESTART is applied with increased periodicity is finite.

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Lemma 3

Every exhausted execution ends with either $C = \text{no}$ or **UNSAT**.

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Theorem 3 (Refutation Soundness)

For every exhausted execution starting with $\Delta = \Delta_0$ and ending with **UNSAT**, the clause set Δ_0 is \mathcal{T} -unsatisfiable.

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Theorem 4 (Refutation Completeness)

For every exhausted execution starting with $\Delta = \Delta_0$ and ending with $C = \text{no}$, the clause set Δ_0 is \mathcal{T} -satisfiable; specifically, M is \mathcal{T} -satisfiable and $M \models_P \Delta_0$.

CDCL(\mathcal{T}) Architecture

The approach formalized so far can be implemented with a simple architecture originally named DPLL(\mathcal{T}) but currently known as $CDCL(\mathcal{T})$

$$CDCL(\mathcal{T}) = CDCL(X) \text{ engine} + \mathcal{T}\text{-solver}$$

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CDCL(X):

- Very **similar to a SAT solver**, enumerates Boolean models
- **Not allowed**: pure literal rule (and other SAT specific optimizations)
- **Required**: incremental addition of clauses
- **Desirable**: partial model detection

CDCL(\mathcal{T}) Architecture

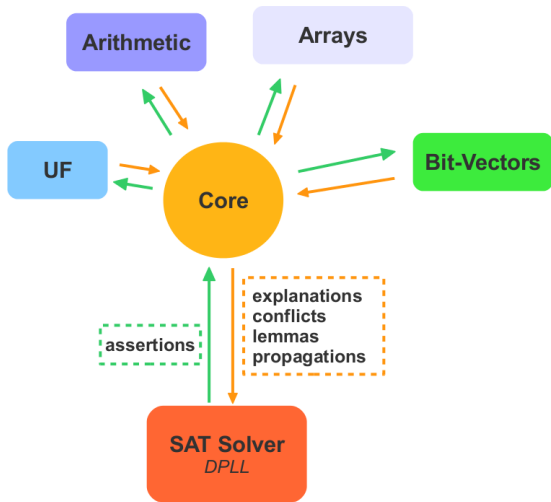
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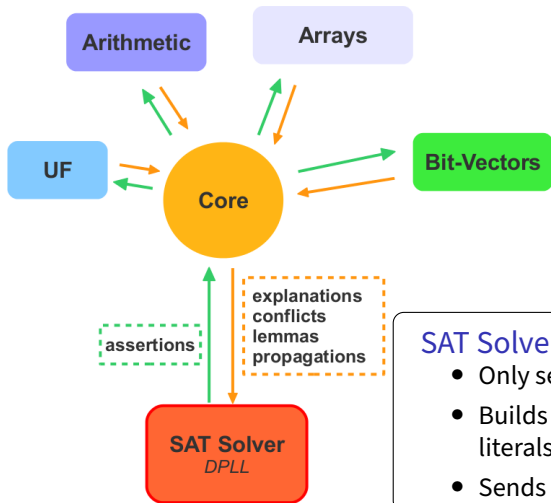
\mathcal{T} -solver:

- Checks the \mathcal{T} -satisfiability of conjunctions of literals
- Computes theory propagations
- Produces explanations of \mathcal{T} -unsatisfiability/propagation
- Must be incremental and backtrackable

Typical SMT solver architecture



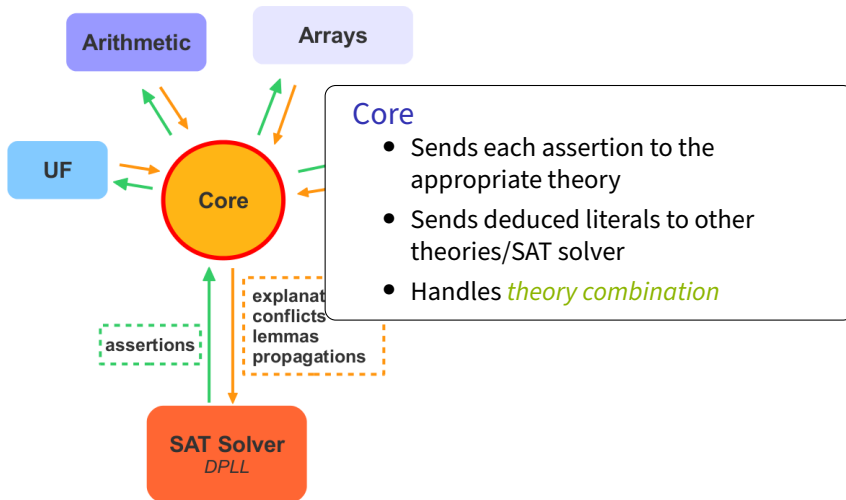
Typical SMT solver architecture



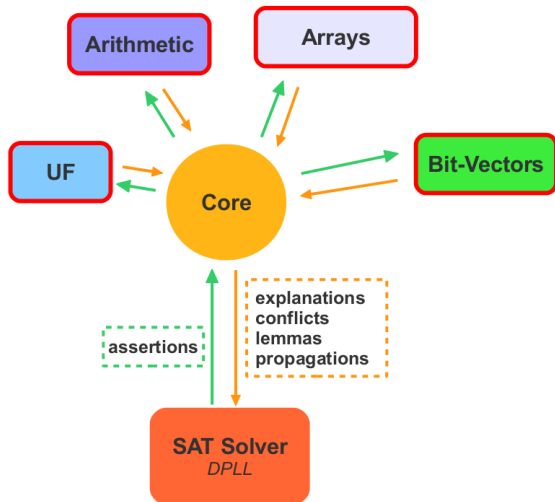
SAT Solver

- Only sees *Boolean skeleton* of problem
- Builds partial model by assigning truth values to literals
- Sends these literals to the core as *assertions*

Typical SMT solver architecture



Typical SMT solver architecture



Theory Solvers

- Check \mathcal{T} -satisfiability of sets of theory literals
- Incremental
- Backtrackable
- Conflict Generation
- Theory Propagation