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Closed FOL formula is either valid or not wrt model \mathcal{M} Consider $\mathcal{M} = (\mathcal{D}, \delta, \mathcal{I})$ to be static part of snapshot, ie state

Let x be program (local) variable or attribute

Execution of program p may change state, ie value of \boldsymbol{x}

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Example

Executing x = 3; results in \mathcal{M} such that $\mathcal{M} \models x \doteq 3$

Executing x = 4; results in \mathcal{M} such that $\mathcal{M} \not\models x \doteq 3$

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Need a logic to capture state before/after program execution

Signature of program logic defined as in FOL, **but**:

In addition there are program variables, attributes, etc.

Rigid versus Flexible

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Rigid symbols, same interpretation in all execution states Needed, for example, to hold initial value of program variable

Logical variables and built-in functions/predicates are rigid

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Rigid versus Flexible

Rigid symbols, same interpretation in all execution states Needed, for example, to hold initial value of program variable

Logical variables and built-in functions/predicates are rigid

Non-rigid (or flexible) symbols, interpretation depends on state
 Needed to capture state change after program execution

Functions modeling program variables and attributes are flexible

Signature of Dynamic Logic (Simple Version)

Given type hierarchy $\mathcal{T}_q = \{ \texttt{int}, \texttt{boolean}, \top \}$

Signature $\Sigma = (\text{VSym}, \text{PSym}, \text{FSym}, \text{PVSym}, \alpha)$

Variable Symbols Rigid Predicate Symbols Rigid Function Symbols Non-rigid Function Symbols

$$\begin{split} \mathbf{VSym} &= \{x_i \mid i \in I\!\!N\} \\ \mathbf{PSym}_r &= \{>, >=, \dots, \} \\ \mathbf{FSym}_r &= \{+, -, *, 0, 1, \text{TRUE}, \text{FALSE}\} \\ \mathbf{FSym}_{nr} &= \{i, j, k, \dots, p, q, r, \dots\} \end{split}$$

Signature of Dynamic Logic (Simple Version)

Typing function α for all symbols:

- $\alpha(j) \in \{int, boolean\}$ for all $j \in FSym_{nr}$ When $b : \rightarrow boolean$, write boolean b, etc.;, use as program variable
- Standard typing for rigid function/predicate symbols For example, TRUE : → boolean, >: int, int

First-order terms may contain rigid and non-rigid symbols Different syntactic categories: $FSym_r \cap FSym_{nr} = \emptyset$

Program variables are non-rigid (=flexible) constants

Emphasize distinction to variables VSym: call them logical variables

A term containing at least one flexible symbol is flexible, otherwise rigid

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Examples

$$\begin{split} \mathbf{VSym} &= \{x:\texttt{int}, b:\texttt{boolean}\}\\ \mathbf{FSym}_{nr} &= \{\texttt{int j}, \texttt{boolean p}\} \end{split}$$

Well-formed terms: j+x, j, bIll-formed terms: j+b, j+p

Atomic Programs Π_0

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Examples

$$\begin{split} \mathbf{VSym} &= \{x:\texttt{int}, b:\texttt{boolean}\}\\ \mathbf{FSym}_{nr} &= \{\texttt{int j},\texttt{boolean p}\} \end{split}$$

Well-formed atomic programs: j = j + 1, j = 0, p = FALSE

III-formed atomic programs: j = j + x, x = 1, $j \doteq j$, p = 0

Programs Π

- If π is an atomic program, then π ; is a program
- \checkmark If p and q are programs, then pq is a program
- If b is a variable-free term of type boolean, p and q programs, then if (b) {p} else {q};

is a program

If b is a variable-free term of type boolean, p a program, then

while (b) {p};

is a program

Programs contain no logical variables

Given signature

 $\mathbf{PSym}_r = \{<\}$

```
FSym_r = \{0, +, -\}
```

 $\mathbf{FSym}_{nr} = \{\texttt{int i}, \texttt{int r}, \texttt{int n}\}$

An admissible DL program **p**:

```
i=0;
r=0;
while (i<n) {
    i=i+1;
    r=r+i;
};
r=r+r-n;
```

What does \boldsymbol{p} compute?

Dynamic Logic Formulas (DL Formulas)

Each FOL formula is a DL formula

DL formulas closed under FOL operators and connectives

 \checkmark If p is a program and ϕ a DL formula then

 $\langle \mathbf{p} \rangle \phi$ is a DL formula

 $[p] \phi$ is a DL-Formula

Program variables are constants: never bound in quantifiers Programs contain no logical variables

The operators $\langle \ \rangle$ and $[\]$ can be arbitrarily nested

$$\forall y. ((\langle \mathbf{x} = \mathbf{1}; \rangle \mathbf{x} \doteq y) < > (\langle \mathbf{x} = \mathbf{1} * \mathbf{1}; \rangle \mathbf{x} \doteq y))$$
 Syntax ?

$$\forall y. ((\langle \mathbf{x} = \mathbf{1}; \rangle \mathbf{x} \doteq y) \triangleleft (\langle \mathbf{x} = \mathbf{1} \ast \mathbf{1}; \rangle \mathbf{x} \doteq y)) \qquad \qquad \mathsf{ok} (y: \mathsf{int})$$

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 ok (y : int)
$$\exists \mathbf{x}. ([\mathbf{x} = \mathbf{1};] (\mathbf{x} \doteq 1))$$
 Syntax ?

$$\forall y. ((\langle \mathbf{x} = \mathbf{1}; \rangle \mathbf{x} \doteq y) \triangleleft (\langle \mathbf{x} = \mathbf{1} \ast \mathbf{1}; \rangle \mathbf{x} \doteq y)) \qquad \qquad \mathsf{ok} (y: \mathsf{int})$$

 $\exists x. ([x = 1;] (x \doteq 1))$ bad

- *x* cannot be logical variable, because it occurs in program
- *x* cannot be program variable, because it is quantified

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$$\langle x = 1; \rangle$$
 ([while (true) { }] false) Syntax ?

$$\forall y. ((\langle \mathbf{x} = \mathbf{1}; \rangle \mathbf{x} \doteq y) \triangleleft (\langle \mathbf{x} = \mathbf{1} \ast \mathbf{1}; \rangle \mathbf{x} \doteq y)) \qquad \qquad \mathsf{ok} (y: \mathsf{int})$$

 $\exists x. ([x = 1;] (x \doteq 1))$ bad

- *x* cannot be logical variable, because it occurs in program
- *x* cannot be program variable, because it is quantified

$$\langle x = 1; \rangle ([while (true) { }] false)$$
 ok (int x)

Program formulas can appear nested

More Examples of DL Formulas

1.
$$x \doteq i$$
 & $y \doteq j$ -> $\langle z = x; x = y; y = x; \rangle x \doteq j$ & $y \doteq i$

2.
$$x \doteq 3 \mid y \doteq -2 \Rightarrow \langle y = x * x - x + 6; \rangle y \doteq 0$$

3.
$$(if 0 \le a then \{\} else \{a = -a; \}) < = a$$

4. (while
$$(c \le n - 1) \{ p = p + m; c = c + 1; \} \rangle p \doteq m * m$$

First-order model can be considered as (execution) state

Interpretation of non-rigid symbols can vary from state to state (eg, program variables)

Interpretation of rigid symbols is the same in all states (eg, built-in functions and predicates)

State = First-order model:

 $\mathcal{M} = s = (\mathcal{D}, \delta, \mathcal{I}) \text{ over FSym} = \mathrm{FSym}_r \cup \mathrm{FSym}_{nr}$

Set of all states s is S

Dynamic Logic Semantics: Kripke Structure

Kripke structure $K = (S, \rho)$

State (model) $s = (\mathcal{D}, \delta, \mathcal{I}) \in S$ and $\rho : \Pi \to (S \to S) \quad \rho(\mathbf{p}), \ \rho(\mathbf{q})$



Each state is first-order model $s = (\mathcal{D}, \delta, \mathcal{I})$ over same domain \mathcal{D}

Dynamic Logic Semantics: Program Formulas

- $\textbf{ } \textbf{ } s,\beta\models\langle \textbf{p}\rangle\phi \quad \text{iff} \quad \rho(\textbf{p})(s),\beta\models\phi \ \text{ and } \rho(\textbf{p})(s) \text{ defined }$
 - **p** terminates and ϕ is true in the final state after execution



Dynamic Logic Semantics: Program Formulas

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 - **p** terminates and ϕ is true in the final state after execution
- $s, \beta \models [p] \phi$ iff $\rho(p)(s), \beta \models \phi$ whenever $\rho(p)(s)$ defined

If p terminates then ϕ is true in the final state after execution



Dynamic Logic Semantics Example

Boolean program variables

 $FSym_{nr} = \{boolean a, boolean b, boolean c, ...\}$



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 $s_1 \models \langle \mathbf{p} \rangle \mathbf{a} \doteq \mathsf{TRUE}$?

 $\mathbf{FSym}_{nr} = \{ \texttt{boolean a, boolean b, boolean c, } \ldots \}$



 $s_1 \models \langle \mathbf{p} \rangle \mathbf{a} \doteq \mathsf{TRUE}$ (ok),

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 $s_1 \models \langle \mathbf{p} \rangle \mathbf{a} \doteq \mathsf{TRUE}$ (ok), $s_1 \models \langle \mathbf{q} \rangle \mathbf{a} \doteq \mathsf{TRUE}$?

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•
$$s, \beta \models \langle \mathbf{p} \rangle \phi$$

p totally correct (with respect to ϕ) in s, β

 $\textbf{ s},\beta \models \langle \textbf{p} \rangle \phi$

 ${\bf p}$ totally correct (with respect to $\phi{\bf)}$ in s,β

 $\textbf{ s},\beta\models [\textbf{p}]\,\phi$

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• Duality $\langle \mathbf{p} \rangle \phi$ iff $![\mathbf{p}]!\phi$

Exercise: justify this with semantic definitions

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Exercise: justify this with semantic definitions

 ${\scriptstyle
m {\scriptstyle Implication}}$ if $\langle {
m p}
angle \phi$ then $[{
m p}] \phi$

Total correctness implies partial correctness (holds only for deterministic programs)

Let $\Gamma = \{\phi_1, \dots, \phi_n\} \subseteq$ For and $\Delta = \{\psi_1, \dots, \psi_m\} \subseteq$ For

 $\textbf{Recall: } s \models (\Gamma \implies \Delta) \qquad \textbf{iff} \qquad s \models (\phi_1 \& \cdots \& \phi_n) \quad \textbf{->} \quad (\psi_1 | \cdots | \psi_m)$

Semantics of DL sequents should be defined identically with semantics of FOL sequents (assume Γ, Δ are sets of closed DL formulas):

 $\Gamma \implies \Delta$ is valid iff $s \models (\Gamma \implies \Delta)$ in all states s

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Consequence for program variables

In valid formulas they represent any possible value of their type

How to restrict validity to set of initial states $S_0 \subseteq S$?

- 1. Design closed FOL formula Init with
 - $s \models \text{Init} \quad \text{iff} \quad s \in S_0$
- **2.** Use sequent Γ , Init ==> Δ

Later: simple method for specifying initial value of program variables

Dynamic Logic Semantics: States, Updates

- **•** States $s = (\mathcal{D}, \delta, \mathcal{I})$ all have
 - the same domain \mathcal{D} (all objects present from start)
 - the same typing function δ (dynamic type never changes)

May assume $\rho(\mathbf{p})$ works on interpretations $\mathcal I$

Define $\mathcal{I}, \beta \models \phi$ as $s, \beta \models \phi$, where $s = (\mathcal{D}, \delta, \mathcal{I})$

Program variables j as flexible constants in s with value $\mathcal{I}(j)$

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Program variables j as flexible constants in s with value $\mathcal{I}(j)$

Modified state update of \mathcal{I} at j of type z with $d \in \mathcal{D}^z$

$$\mathcal{I}_{j}^{d}(\mathbf{x}) = \begin{cases} \mathcal{I}(\mathbf{x}) & \mathbf{x} \neq \mathbf{j} \\ \\ d & \mathbf{x} = \mathbf{j} \end{cases}$$

Cf. modified variable assignment

Operational Semantics of Programs

State transformation ρ defines semantics of programs

Same ρ for all programs, so not part of s

•
$$\rho(\mathbf{x} = \mathbf{t};)(\mathcal{I}) = \mathcal{I}^{val_{\mathcal{I},\beta}(t)}_{\mathbf{x}}$$

(can ignore β)

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$$\rho(\mathbf{x} = \mathbf{t};)(\mathcal{I}) = \mathcal{I}_{\mathbf{x}}^{val_{\mathcal{I},\beta}(t)}$$
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• $\rho(if(b) \{p\} else \{q\};)(\mathcal{I}) = \begin{cases} \rho(p)(\mathcal{I}) & \mathcal{I} \models b \doteq TRUE \\ \rho(q)(\mathcal{I}) & otherwise \end{cases}$

• $\rho(\mathbf{x} = \mathbf{t};)(\mathcal{I}) = \mathcal{I}_{\mathbf{x}}^{val_{\mathcal{I},\beta}(t)}$ (can ignore β) • $\rho(\inf(b) \{\mathbf{p}\} \text{ else } \{\mathbf{q}\};)(\mathcal{I}) = \begin{cases} \rho(\mathbf{p})(\mathcal{I}) & \mathcal{I} \models b \doteq \text{TRUE} \\ \rho(\mathbf{q})(\mathcal{I}) & \text{otherwise} \end{cases}$ • $\rho(\mathbf{pq})(\mathcal{I}) = \rho(\mathbf{q})(\rho(\mathbf{p})(\mathcal{I})), \text{ if } \rho(\mathbf{p})(\mathcal{I}) \text{ defined, undefined otherwise} \end{cases}$

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p(pq)(x) - p(q)(p(p)(x)), n p(p)(x) defined,

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Proof by Symbolic Program Execution

Need to have rules for program formulas: but which?

What corresponds to top-level connective in sequential program?

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Idea: follow natural program control flow

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Sound and complete rule for conclusions with main formulas:

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 ξ one single admissible program statement, q remaining program

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Sound and complete rule for conclusions with main formulas:

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 ξ one single admissible program statement, q remaining program

Rules execute symbolically the first active statement Proof corresponds to symbolic program execution

$$\mathsf{CONCATENATE} \frac{\Gamma \implies \langle \mathbf{p} \rangle \left(\langle \mathbf{q} \rangle \phi \right), \Delta}{\Gamma \implies \langle \mathbf{p} \mathbf{q} \rangle \phi, \Delta}$$

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 x_{old} new program variable that "rescues" old value of x

$$\begin{aligned} & \operatorname{CONCATENATE} \frac{\Gamma \implies \langle \mathbf{p} \rangle \left(\langle \mathbf{q} \rangle \phi \right), \Delta}{\Gamma \implies \langle \mathbf{p} \mathbf{q} \rangle \phi, \Delta} \\ & \Gamma \implies \langle \mathbf{p} \mathbf{q} \rangle \phi, \Delta \\ & \Pi \mathbf{F} \frac{\Gamma, b \doteq \mathrm{TRUE} \implies \langle \mathbf{p} \rangle \phi, \Delta}{\Gamma \implies \langle \mathbf{p} \rangle \phi, \Delta} \quad \Gamma, b \doteq \mathrm{FALSE} \implies \langle \mathbf{q} \rangle \phi, \Delta} \\ & \Gamma \implies \langle \mathrm{if} (b) \{ \mathbf{p} \} \mathrm{else} \{ \mathbf{q} \}; \rangle \phi, \Delta \\ & \operatorname{ASSIGN} \frac{\{ \mathbf{x} / \mathbf{x}_{old} \} \Gamma, \ \mathbf{x} \doteq \{ \mathbf{x} / \mathbf{x}_{old} \} t \implies \phi, \ \{ \mathbf{x} / \mathbf{x}_{old} \} \Delta}{\Gamma \implies \langle \mathbf{x} = \mathbf{t}; \rangle \phi, \Delta} \end{aligned}$$

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Partial correctness assertion (Hoare formula) $\{\psi\} \ p \ \{\phi\}$

If p is started in a state satisfying ψ and terminates, then its final state satisfies ϕ

In DL $\psi \rightarrow [p] \phi$

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Valid formulas

 $[\mathtt{x}=\mathtt{1};]\,(\mathtt{x}\doteq1)$

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Validity depends on p, q

 $\forall y. ((\langle \mathbf{p} \rangle \mathbf{x} \doteq y) \triangleleft (\langle \mathbf{q} \rangle \mathbf{x} \doteq y))$ meaning ?

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p, q equivalent relative to x

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p, q equivalent relative to x

 $p \ \mbox{terminates}$ for some initial value of x

Motivation

- UNWIND-rule only works if number of loop iterations small & known
- Properties of inductive FO data structures unprovable (numbers, lists, trees, etc.)

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Induction Rule (over natural numbers)

$$\Gamma \implies [n/0]\phi, \Delta \qquad \Gamma, [n/n']\phi \implies [n/n'+1]\phi, \Delta \qquad \Gamma, \forall n.\phi \implies \Delta$$
$$\Gamma \implies \Delta$$

Where n logical variable, n' constant of type int not occurring in Γ, Δ

Definition of even (unary predicate on int):

$$= \forall x.(\mathbf{even}(x) \rightarrow \mathbf{even}(x+2))$$

How to prove ==>even(2*7)?

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$$=> \operatorname{even}(2*0) \quad \operatorname{even}(2*n') ==> \operatorname{even}(2*(n'+1)) \quad \forall n.\operatorname{even}(2*n) ==> \operatorname{even}(2*7)$$
$$==> \operatorname{even}(2*7)$$

Demo in dlIntro/ind.key
Cannot quantify over program variables!

How to express validity for arbitrary initial value of program variable?

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Solution

Use explicit construct to record state change information

Update $\forall n.(\{i := n\} \langle p(i) \rangle \phi)$

Explicit State Updates

Updates record computation state in which we evaluate a formula

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Syntax

If v is program variable, t, t' FOL terms, and ϕ any DL formula, then $\{v := t\}\phi$ is DL formula and $\{v := t\}t'$ is DL term

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Semantics

$$\mathcal{I},\beta\models\{\mathtt{v}:=t\}\phi\quad\text{iff}\quad\mathcal{I}^{val_{\mathcal{I},\beta}(t)}_{\mathtt{v}},\beta\models\phi$$

Semantics identical to assignment, may depend on logical variables in t

Updates work like "lazy" assignments

Updates are not assignments: may contain logical variable

Updates are not equations: change interpretation of non-rigid terms

Computing Effect of Updates (Automatic)

Update followed by program variable

by logical variable

$$\{\mathbf{x} := t\} \mathbf{y} \quad \rightsquigarrow \quad \mathbf{y} \\ \{\mathbf{x} := t\} \mathbf{x} \quad \rightsquigarrow \quad t$$

$$\{\mathbf{x} := t\} w \quad \leadsto \quad w$$

Computing Effect of Updates (Automatic)

Update followed by program variable

${x := t}y \rightsquigarrow y$

 ${x := t}x \rightarrow t$

Update followed by complex term

$$\{\mathbf{x} := t\}f(t_1, \ldots, t_n) \quad \leadsto \quad f(\{\mathbf{x} := t\}t_1, \ldots, \{\mathbf{x} := t\}t_n)$$

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Update followed by first-order formula

$$\begin{aligned} \{\mathbf{x} := t\}(\phi \, \mathbf{\&} \, \psi) & \leadsto \quad \{\mathbf{x} := t\}\phi \, \mathbf{\&} \, \{\mathbf{x} := t\}\psi \quad \text{etc.} \\ \{\mathbf{x} := t\}(\forall y.\phi) & \leadsto \quad \forall y.(\{\mathbf{x} := t\}\phi) \quad \text{etc.} \end{aligned}$$

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Update followed by program formula

$${\mathbf{x} := t}(\langle \mathbf{p} \rangle \phi) \quad \leadsto \quad {\mathbf{x} := t}(\langle \mathbf{p} \rangle \phi) \qquad \qquad \text{unchanged}$$

Update computation delayed until \boldsymbol{p} symbolically executed

by logical variable

$$\{\mathbf{x} := t\} w \quad \leadsto \quad w$$

- p.28/3

Assignment Rule Using Updates

$$\operatorname{ASSIGN} \frac{\Gamma == \{ \mathbf{x} := t \} \phi, \Delta}{\Gamma == \langle \mathbf{x} = \mathbf{t}; \rangle \phi, \Delta}$$

Avoids renaming of program variables

Works as long as t has no side effects (ok in simple DL)

But: rules dealing with programs need to account for updates

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General form of conclusion in rule for symbolic execution



```
\programVariables { // program variables in FSym
  int x;
}
\problem {
\exists int y; (x = y - > // y \text{ logical variable})
    < \{ while (x > 0) \{ x = x-1; \} \} > true \}
      // modal brackets written as \<, \>
}
```

Intuitive Meaning? Satisfiable? Valid?

Demo

dlIntro/term.key