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## State Dependency of Formula Evaluation

Closed FOL formula is either valid or not wrt model $\mathcal{M}$
Consider $\mathcal{M}=(\mathcal{D}, \delta, \mathcal{I})$ to be static part of snapshot, ie state

Let x be program (local) variable or attribute
Execution of program $p$ may change state, ie value of $x$

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Example
Executing $\mathrm{x}=3$; results in $\mathcal{M}$ such that $\mathcal{M} \models \mathrm{x} \doteq 3$
Executing $\mathrm{x}=4 ;$ results in $\mathcal{M}$ such that $\mathcal{M} \not \models \mathrm{x} \doteq 3$

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Need a logic to capture state before/after program execution

## Rigid versus Flexible Symbols

Signature of program logic defined as in FOL, but:
In addition there are program variables, attributes, etc.
Rigid versus Flexible

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- Rigid symbols, same interpretation in all execution states

Needed, for example, to hold initial value of program variable
Logical variables and built-in functions/predicates are rigid

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Rigid versus Flexible

- Rigid symbols, same interpretation in all execution states Needed, for example, to hold initial value of program variable

Logical variables and built-in functions/predicates are rigid

- Non-rigid (or flexible) symbols, interpretation depends on state Needed to capture state change after program execution

Functions modeling program variables and attributes are flexible

## Signature of Dynamic Logic (Simple Version)

Given type hierarchy $\mathcal{T}_{q}=\{$ int, boolean, $\boldsymbol{\top}\}$
Signature $\Sigma=($ VSym, PSym, FSym, PVSym, $\alpha)$

Variable Symbols
Rigid Predicate Symbols
Rigid Function Symbols
Non-rigid Function Symbols
$\mathbf{V S y m}=\left\{x_{i} \mid i \in \mathbb{I N}\right\}$
$\mathbf{P S y m}_{r}=\{>,>=, \ldots$,
$\boldsymbol{F S y m}_{r}=\{+,-, *, 0,1$, TRUE, FALSE $\}$
$\mathbf{F S y m}_{n r}=\{i, j, k, \ldots, p, q, r, \ldots\}$

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& \text { FSym }_{n r}=\{i, j, k, \ldots, p, q, r, \ldots\}
\end{aligned}
$$

Typing function $\alpha$ for all symbols:

- $\alpha(\mathbf{j}) \in\{$ int, boolean $\}$ for all $\mathbf{j} \in \mathbf{F S y m}_{n r}$

When $b: \rightarrow$ boolean, write boolean b, etc.;, use as program variable

- Standard typing for rigid function/predicate symbols

For example, TRUE $: \rightarrow$ boolean, $>:$ int, int

## Terms

First-order terms may contain rigid and non-rigid symbols
Different syntactic categories: FSym $_{r} \cap \mathbf{F S y m}_{n r}=\emptyset$
Program variables are non-rigid (=flexible) constants
Emphasize distinction to variables VSym: call them logical variables
A term containing at least one flexible symbol is flexible, otherwise rigid

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## Examples

VSym $=\{x:$ int, $b:$ boolean $\}$
$\mathbf{F S y m}_{n r}=\{$ int j , boolean p$\}$
Well-formed terms: $\mathrm{j}+x, \mathrm{j}, \quad b$
III-formed terms: $\mathrm{j}+b, \mathrm{j}+\mathrm{p}$

## Atomic Programs

## Atomic Programs $\Pi_{0}$

- Assignments $\mathrm{j}=t$ with:
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## Examples

VSym $=\{x$ : int, $b:$ boolean $\}$
FSym $_{n r}=\{$ int j , boolean p$\}$
Well-formed atomic programs: $j=j+1, \quad j=0, \quad p=$ FALSE
III-formed atomic programs: $\mathrm{j}=\mathrm{j}+x, \quad x=1, \quad \mathrm{j} \doteq \mathrm{j}, \quad \mathrm{p}=0$

## Dynamic Logic (Simple Version) Programs

## Programs $\Pi$

- If $\pi$ is an atomic program, then $\pi$; is a program
- If p and q are programs, then pq is a program
- If $b$ is a variable-free term of type boolean, p and q programs, then

$$
\text { if (b) }\{p\} \text { else }\{q\} ;
$$

is a program

- If $b$ is a variable-free term of type boolean, p a program, then while (b) $\{p\}$;
is a program

Programs contain no logical variables

## Dynamic Logic Syntax Example

Given signature
$\mathbf{P S y m}_{r}=\{<\}$
$\boldsymbol{F S y m}_{r}=\{0,+,-\}$
$\mathbf{F S y m}_{n r}=\{$ int i, int r, int n$\}$
An admissible DL program p:

```
i=0;
r=0;
while (i<n) {
    i=i+1;
    r=r+i;
};
r=r+r-n;
```

What does p compute?

## Dynamic Logic (Simple Version) Formulas

## Dynamic Logic Formulas (DL Formulas)

- Each FOL formula is a DL formula

DL formulas closed under FOL operators and connectives

- If $\mathbf{p}$ is a program and $\phi$ a DL formula then | $\langle\mathrm{p}\rangle \phi$ | is a DL formula |
| :--- | :--- |
| $[\mathrm{p}] \phi$ | is a DL-Formula |

Program variables are constants: never bound in quantifiers
Programs contain no logical variables
The operators $\rangle$ and [] can be arbitrarily nested

## Dynamic Logic Syntax Example

Check for syntactic well-formedness and derive the signature
$\forall y .((\langle\mathrm{x}=1 ;\rangle \mathrm{x} \doteq y)<->(\langle\mathrm{x}=1 * 1 ;\rangle \mathrm{x} \doteq y)) \quad$ Syntax ?

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- $x$ cannot be program variable, because it is quantified


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$\langle\mathrm{x}=1 ;\rangle([$ while (true) $\}]$ false $)$ Syntax ?


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- $x$ cannot be logical variable, because it occurs in program
. $x$ cannot be program variable, because it is quantified
$\langle\mathrm{x}=1 ;\rangle([$ while (true) $\mathbf{~}\}]$ false $)$
- Program formulas can appear nested


## More Examples of DL Formulas

1. $\mathrm{x} \doteq i \boldsymbol{\&} \mathrm{y} \doteq j \rightarrow\langle\mathrm{z}=\mathrm{x} ; \mathrm{x}=\mathrm{y} ; \mathrm{y}=\mathrm{x} ;\rangle \mathrm{x} \doteq j \boldsymbol{=} \mathrm{y} \doteq i$
2. $x \doteq 3 \mid y \doteq-2->\langle y=x * x-x+6 ;\rangle y \doteq 0$
3. $\langle$ if $0<=$ a then $\}$ else $\{a=-a ;\}\rangle 0<=a$
4. $\langle$ while $(\mathrm{c}<=\mathrm{n}-1)\{\mathrm{p}=\mathrm{p}+\mathrm{m} ; \mathrm{c}=\mathrm{c}+1 ;\}\rangle \mathrm{p} \doteq \mathrm{m} * \mathrm{~m}$

## Dynamic Logic Semantics: States

First-order model can be considered as (execution) state
Interpretation of non-rigid symbols can vary from state to state (eg, program variables)

Interpretation of rigid symbols is the same in all states (eg, built-in functions and predicates)

State $=$ First-order model:
$\mathcal{M}=s=(\mathcal{D}, \delta, \mathcal{I})$ over $\mathbf{F S y m}=\mathbf{F S y m}_{r} \cup \mathbf{F S y m}_{n r}$
Set of all states $s$ is $S$

## Dynamic Logic Semantics: Kripke Structure

Kripke structure $K=(S, \rho)$
State (model) $s=(\mathcal{D}, \delta, \mathcal{I}) \in S$ and $\rho: \Pi \rightarrow(S \rightarrow S) \quad \rho(\mathrm{p}), \rho(\mathrm{q})$


Each state is first-order model $s=(\mathcal{D}, \delta, \mathcal{I})$ over same domain $\mathcal{D}$

## Dynamic Logic Semantics: Program Formulas

- $s, \beta \models\langle\mathrm{p}\rangle \phi \quad$ iff $\quad \rho(\mathrm{p})(s), \beta \models \phi$ and $\rho(\mathrm{p})(s)$ defined
p terminates and $\phi$ is true in the final state after execution



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- $s, \beta \models[\mathrm{p}] \phi \quad$ iff $\quad \rho(\mathrm{p})(s), \beta \models \phi$ whenever $\rho(\mathrm{p})(s)$ defined

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## Dynamic Logic Semantics Example

## Boolean program variables

$\mathbf{F S y m}_{n r}=\{$ boolean a , boolean b , boolean $\mathrm{c}, \ldots\}$


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## Program Correctness

- $s, \beta \models\langle\mathrm{p}\rangle \phi$
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- Duality $\langle\mathrm{p}\rangle \phi$ iff ! $[\mathrm{p}]!\phi$

Exercise: justify this with semantic definitions

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- Implication if $\langle\mathrm{p}\rangle \phi$ then $[\mathrm{p}] \phi$

Total correctness implies partial correctness (holds only for deterministic programs)

## Semantics of Sequents

Let $\Gamma=\left\{\phi_{1}, \ldots, \phi_{n}\right\} \subseteq$ For and $\Delta=\left\{\psi_{1}, \ldots, \psi_{m}\right\} \subseteq$ For

Recall: $s \models(\Gamma==>\Delta) \quad$ iff $\quad s \models\left(\phi_{1} \& \cdots \& \phi_{n}\right) \quad$-> $\quad\left(\psi_{1}|\cdots| \psi_{m}\right)$

Semantics of DL sequents should be defined identically with semantics of FOL sequents (assume $\Gamma, \Delta$ are sets of closed DL formulas):
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Consequence for program variables
In valid formulas they represent any possible value of their type

## Initial States

How to restrict validity to set of initial states $S_{0} \subseteq S$ ?

1. Design closed FOL formula Init with

$$
s \models \text { Init } \quad \text { iff } \quad s \in S_{0}
$$

2. Use sequent

$$
\Gamma, \text { Init }==>\Delta
$$

Later: simple method for specifying initial value of program variables

## Dynamic Logic Semantics: States, Updates

- States $s=(\mathcal{D}, \delta, \mathcal{I})$ all have
- the same domain $\mathcal{D}$ (all objects present from start)
- the same typing function $\delta$ (dynamic type never changes)

May assume $\rho(\mathbf{p})$ works on interpretations $\mathcal{I}$
Define $\mathcal{I}, \beta \models \phi$ as $s, \beta \models \phi$, where $s=(\mathcal{D}, \delta, \mathcal{I})$

- Program variables j as flexible constants in $s$ with value $\mathcal{I}(\mathrm{j})$


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Modified state update of $\mathcal{I}$ at j of type z with $d \in \mathcal{D}^{z}$

$$
\mathcal{I}_{\mathrm{j}}^{d}(\mathrm{x})= \begin{cases}\mathcal{I}(\mathrm{x}) & \mathrm{x} \neq \mathrm{j} \\ d & \mathrm{x}=\mathrm{j}\end{cases}
$$

Cf. modified variable assignment

## Operational Semantics of Programs

State transformation $\rho$ defines semantics of programs
Same $\rho$ for all programs, so not part of $s$

$$
\text { - } \rho(\mathrm{x}=\mathrm{t} ;)(\mathcal{I})=\mathcal{I}_{\mathrm{x}}^{v a l_{\mathcal{I}, \beta}(t)}
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## Proof by Symbolic Program Execution

Need to have rules for program formulas: but which?
What corresponds to top-level connective in sequential program?

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Sound and complete rule for conclusions with main formulas:

$$
\langle\xi \mathrm{q}\rangle \phi, \quad[\xi \mathrm{q}] \phi
$$

$\xi$ one single admissible program statement, q remaining program

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What corresponds to top-level connective in sequential program?

Idea: follow natural program control flow

Sound and complete rule for conclusions with main formulas:

$$
\langle\xi \mathrm{q}\rangle \phi, \quad[\xi \mathrm{q}] \phi
$$

$\xi$ one single admissible program statement, q remaining program

Rules execute symbolically the first active statement
Proof corresponds to symbolic program execution

## Dynamic Logic Calculus

$$
\text { CONCATENATE } \frac{\Gamma==>\langle\mathrm{p}\rangle(\langle\mathrm{q}\rangle \phi), \Delta}{\Gamma==>\langle\mathrm{pq}\rangle \phi, \Delta}
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\begin{gathered}
\text { CONCATENATE } \frac{\Gamma==>\langle\mathrm{p}\rangle(\langle\mathrm{q}\rangle \phi), \Delta}{\Gamma==>\langle\mathrm{pq}\rangle \phi, \Delta} \\
\text { IF } \frac{\Gamma, b \doteq \operatorname{TRUE}==>\langle\mathrm{p}\rangle \phi, \Delta \quad \Gamma, b \doteq \mathrm{FALSE}==>\langle\mathrm{q}\rangle \phi, \Delta}{\Gamma==>\langle\text { if }(b)\{\mathrm{p}\} \text { else }\{\mathrm{q}\} ;\rangle \phi, \Delta}
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$\mathrm{x}_{\text {old }}$ new program variable that "rescues" old value of x

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$$
\text { UNWIND } \frac{\Gamma, b \doteq \operatorname{FALSE}==>\phi, \Delta \quad \Gamma, b \doteq \operatorname{TRUE}==>\langle\mathrm{p}\rangle\langle\text { while }(b)\{\mathrm{p}\} ;\rangle \phi, \Delta}{\Gamma==>\langle\text { while }(b)\{\mathrm{p}\} ;\rangle \phi, \Delta}
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## Dynamic Logic Examples

Partial correctness assertion (Hoare formula)

$$
\{\psi\} \mathrm{p}\{\phi\}
$$

If p is started in a state satisfying $\psi$ and terminates, then its final state satisfies $\phi$

In DL

$$
\psi->[\mathrm{p}] \phi
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$\mathrm{p}, \mathrm{q}$ equivalent relative to x
$\exists y .(\mathrm{x} \doteq y-\rangle\langle\mathrm{p}\rangle$ true $) \quad \mathrm{p}$ terminates for some initial value of x

## Induction Rule

Motivation

- UNWIND-rule only works if number of loop iterations small \& known
- Properties of inductive FO data structures unprovable (numbers, lists, trees, etc.)


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Induction Rule (over natural numbers)

$$
\begin{gathered}
\Gamma==>[n / 0] \phi, \Delta \quad \Gamma,\left[n / n^{\prime}\right] \phi==>\left[n / n^{\prime}+1\right] \phi, \Delta \quad \Gamma, \forall n \cdot \phi==>\Delta \\
\Gamma=\Delta \Delta
\end{gathered}
$$

Where $n$ logical variable, $n^{\prime}$ constant of type int not occurring in $\Gamma, \Delta$

## Induction Rule Example

Definition of even (unary predicate on int):

- ==> even ( 0 )
- $==>\forall x$. $(\mathbf{e v e n}(x)$-> $\operatorname{even}(x+2))$

How to prove ==> even $(2 * 7)$ ?

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$$
\begin{gathered}
==>\operatorname{even}(2 * 0) \quad \operatorname{even}\left(2 * n^{\prime}\right)==>\operatorname{even}\left(2 *\left(n^{\prime}+1\right)\right) \quad \forall n . \text { even }(2 * n)==>\operatorname{even}(2 * 7) \\
==>\operatorname{even}(2 * 7)
\end{gathered}
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Demo in dlintro/ind.key

## Quantifying over Program Variables

What if induction hypothesis contains program?
Cannot quantify over program variables!
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Solution
Use explicit construct to record state change information
Update $\quad \forall n .(\{\mathrm{i}:=n\}\langle\mathrm{p}(\mathrm{i})\rangle \phi)$

## Explicit State Updates

Updates record computation state in which we evaluate a formula

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Syntax
If $v$ is program variable, $t, t^{\prime}$ FOL terms, and $\phi$ any DL formula, then $\{\mathrm{v}:=t\} \phi$ is DL formula and $\{\mathrm{v}:=t\} t^{\prime}$ is DL term

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If $v$ is program variable, $t, t^{\prime}$ FOL terms, and $\phi$ any DL formula, then $\{\mathrm{v}:=t\} \phi$ is DL formula and $\{\mathrm{v}:=t\} t^{\prime}$ is DL term

## Semantics

$\mathcal{I}, \beta \models\{\mathrm{v}:=t\} \quad$ iff $\quad \mathcal{I}_{\mathrm{v}}^{v a l_{\mathcal{I}, \beta}(t)}, \beta \models \phi$
Semantics identical to assignment, may depend on logical variables in $t$
Updates work like "lazy" assignments
Updates are not assignments: may contain logical variable
Updates are not equations: change interpretation of non-rigid terms

## Computing Effect of Updates (Automatic)

Update followed by program variable

$$
\begin{aligned}
& \{\mathrm{x}:=t\} \mathrm{y} \leadsto \mathrm{y} \\
& \{\mathrm{x}:=t\} \mathrm{x} \leadsto t
\end{aligned}
$$

by logical variable
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Update followed by complex term

$$
\{\mathrm{x}:=t\} f\left(t_{1}, \ldots, t_{n}\right) \leadsto f\left(\{\mathrm{x}:=t\} t_{1}, \ldots,\{\mathrm{x}:=t\} t_{n}\right)
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Update followed by first-order formula

$$
\begin{aligned}
& \{\mathrm{x}:=t \mathfrak{\}}(\phi \boldsymbol{\&} \psi) \sim\{\mathrm{x}:=t\} \phi \&\{\mathrm{x}:=t\} \psi \text { etc. } \\
& \{\mathrm{x}:=t \mathfrak{\}}(\forall y \cdot \phi) \sim \forall y \cdot(\{\mathrm{x}:=t\} \phi) \text { etc. }
\end{aligned}
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& \{\mathrm{x}:=t\} \mathrm{x} \leadsto{ }^{2}
\end{aligned}
$$

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\end{aligned}
$$

Update followed by program formula

$$
\{\mathrm{x}:=t\}(\langle\mathrm{p}\rangle \phi) \sim\{\mathrm{x}:=t\}(\langle\mathrm{p}\rangle \phi)
$$

Update computation delayed until p symbolically executed

## Assignment Rule Using Updates

$$
\text { ASSIGN } \frac{\Gamma==>\{\mathrm{x}:=t\} \phi, \Delta}{\Gamma==>\langle\mathrm{x}=\mathrm{t} ;\rangle \phi, \Delta}
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Avoids renaming of program variables
Works as long as $t$ has no side effects (ok in simple DL)
But: rules dealing with programs need to account for updates

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Explicit concatenation rule not longer useful
General form of conclusion in rule for symbolic execution


## Example Proof

```
\programVariables { // program variables in FSym
    int x;
}
\problem {
    \exists int y; (x = y -> // y logical variable
    \<{while (x > 0) {x = x-1;}}\> true)
    // modal brackets written as \<, \>
}
Intuitive Meaning? Satisfiable? Valid?
```


## Demo

dlIntro/term.key

