Integrating Concurrency Control and Energy Management in Device Drivers

Kevin Klues, Vlado Handziski, Chenyang Lu, Adam Wolisz, David Culler, David Gay, and Philip Levis

Overview

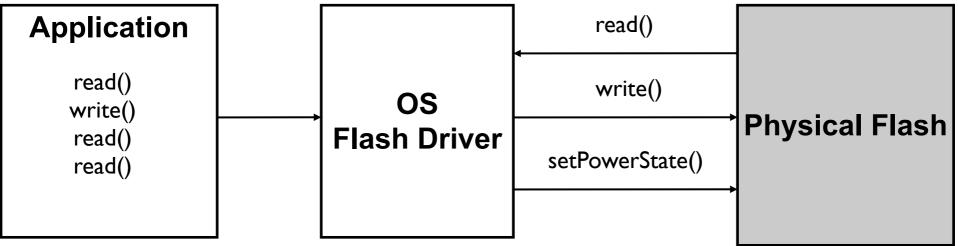
• Concurrency Control:

- Concurrency of I/O operations alone, not of threads in general
- Synchronous vs. Asynchronous I/O
- Energy Management:
 - Power state of devices needed to perform I/O operations
 - Determined by pending I/O requests using Asynchronous I/O

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The more workload information an application can give the OS, the more energy it can save when scheduling that workload

Outline

- Background Information
- Platform and Application
- Driver architecture
- Evaluation
- Conclusion

Motivation

- Difficult to manage energy in traditional OSs
 - Hard to tell OS about future application workloads
 - All logic pushed out to the application
 - API extensions for hints?

• Dynamic CPU Voltage Scaling

- Vertigo Application workload classes
- Grace OS Explicit real-time deadlines
- Disk Spin Down
 - Coop-IO Application specified timeouts

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Saving energy is a complex process

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Saving energy is a complex process A little application knowledge can help us alot

Sensor Networks

- Domain in need of unique solution to this problem
 - Harsh energy requirements
 - Very small source of power (2 AA batteries)
 - Must run unattended from months to years
- First generation sensornet OSes (TinyOS, Contiki, Mantis, ...)
 - Push all energy management to the application
 - Optimal energy savings at cost of application complexity





ICEM: Integrated Concurrency and Energy Management

• A device driver architecture that automatically manages energy

- Implemented in TinyOS 2.0 -- all drivers follow it
- Introduces Power Locks, split-phase locks with integrated energy and configuration management
- Defines three classes of drivers: dedicated, shared, virtualized
- Provides a component library for building drivers

• Advantages of using ICEM

- Energy efficient At least 98.4% as hand-tuned implementation
- Reduces code complexity 400 vs. 68 lines of code
- Enables natural decomposition of applications

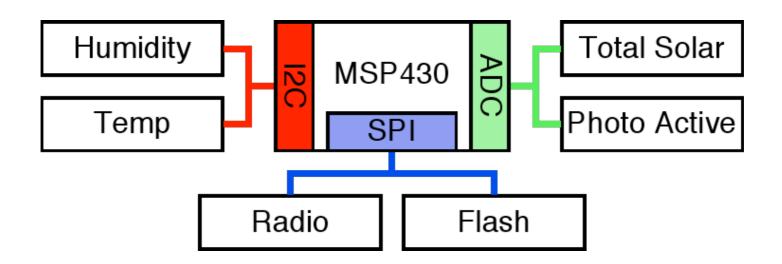
Outline

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The Tmote Platform

- Six major I/O devices
- Possible Concurrency
 - I2C, SPI, ADC
- Energy Management
 - Turn peripherals on only when needed
 - Turn off otherwise





Producer

Every 5 minutes: Write prior samples Sample photo active Sample total solar Sample temperature Sample humidity



Consumer

Every 12 hours: For all new entries: Send current sample Read next sample

Sensors



Producer

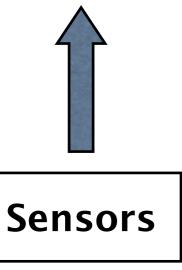
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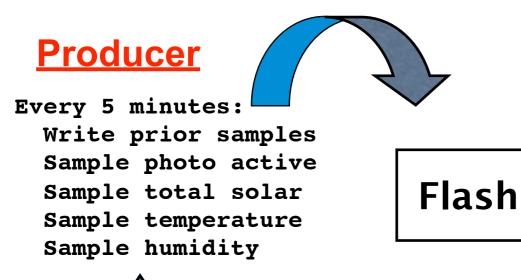


Consumer

Every 12 hours: For all new entries: Send current sample Read next sample

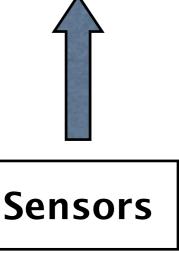
Radio



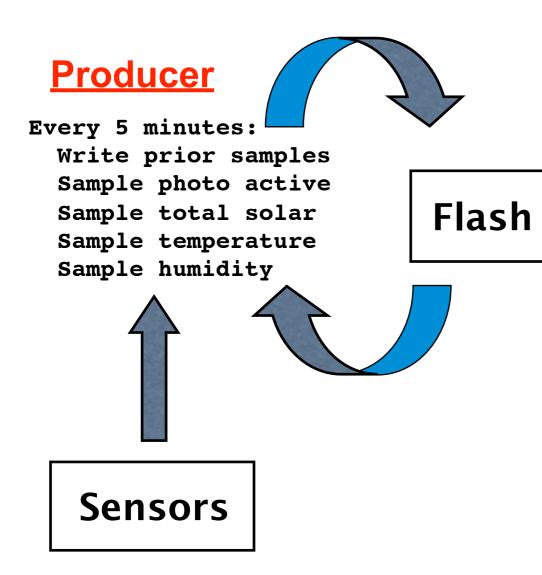


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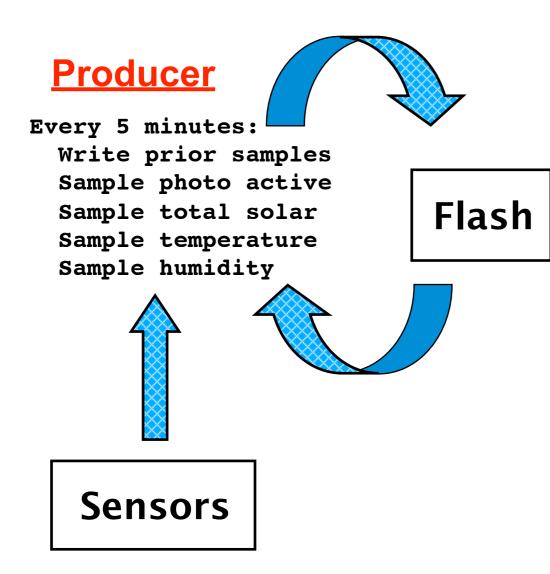




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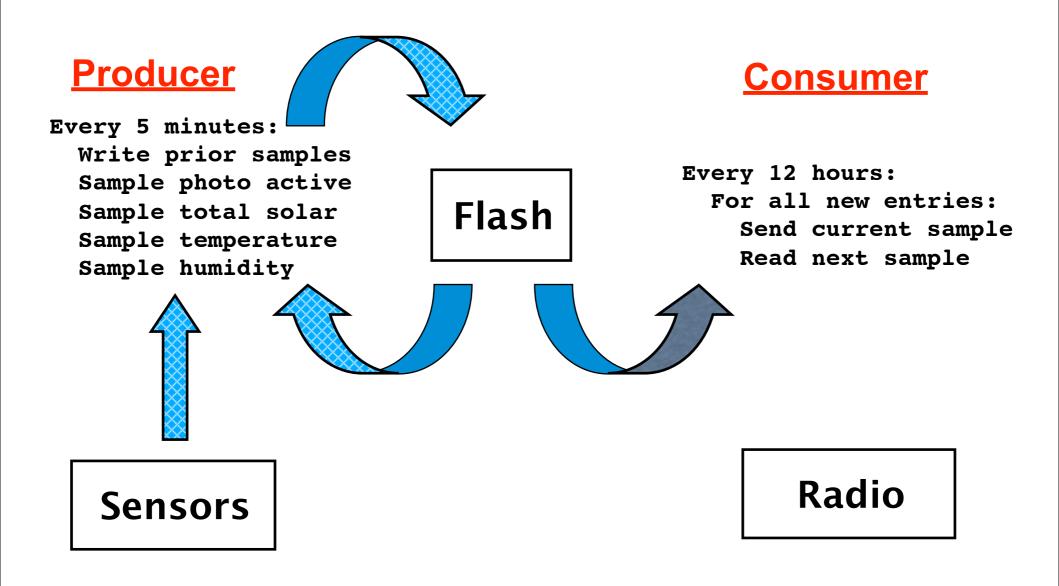
Radio

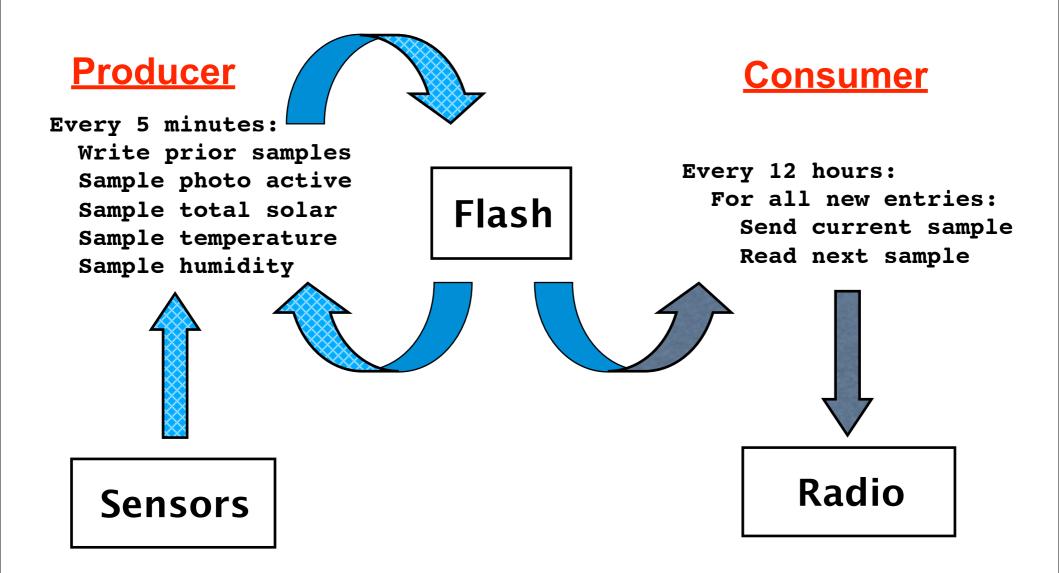


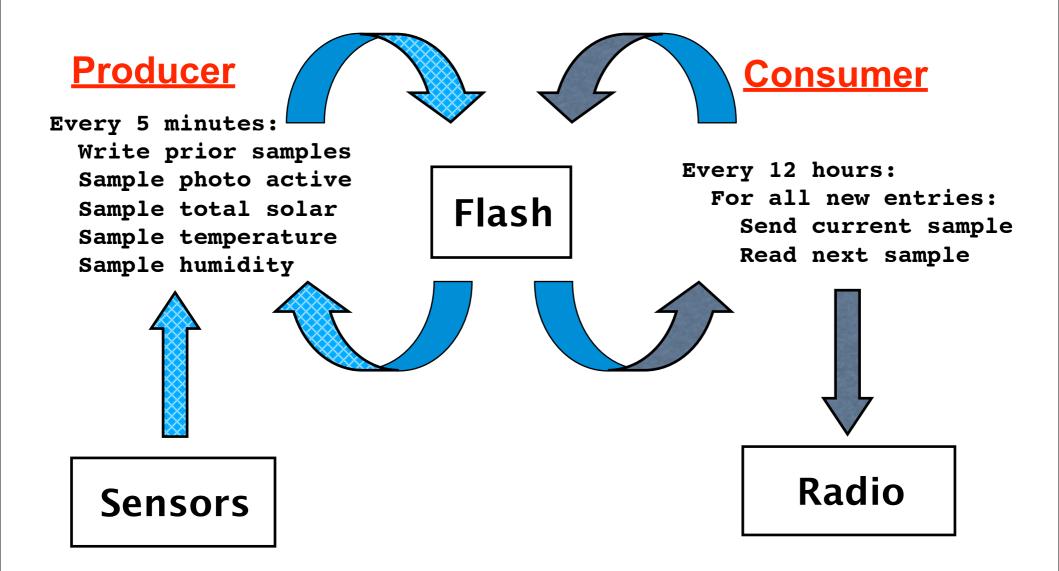
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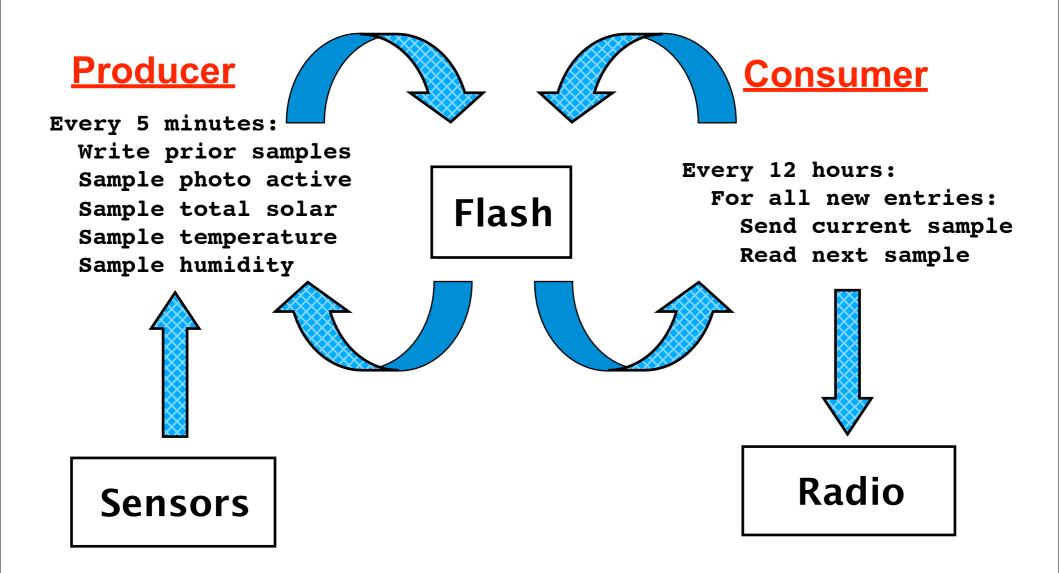
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Radio









Code Complexity

Hand-Tuned Application

| Every 5 minutes: |
|-------------------------------|
| Turn on SPI bus |
| Turn on flash chip |
| Turn on voltage reference |
| Turn on I ² C bus |
| Log prior readings |
| Start humidity sample |
| Wait 5ms for log |
| Turn off flash chip |
| Turn off SPI bus |
| Wait 12ms for vref |
| Turn on ADC |
| Start total solar sample |
| Wait 2ms for total solar |
| Start photo active sample |
| Wait 2ms for photo active |
| Turn off ADC |
| Turn off voltage reference |
| Wait 34ms for humidity |
| Start temperature sample |
| Wait 220ms for temperature |
| Turn off I ² C bus |

ICEM Application

Every 5 minutes: Log prior readings sample humidity sample total solar sample photo active sample temperature

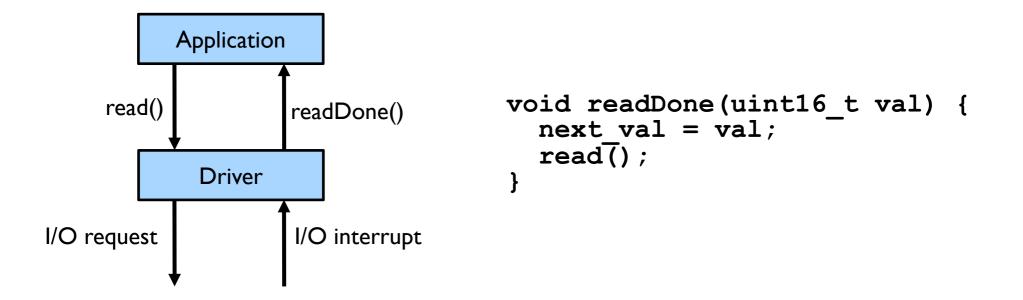
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Split-Phase I/O Operations

• Split-phase I/O operations

- Implemented within a single thread of control
- Application notified of I/O completion through direct upcall
- Driver given workload information before returning control
- Example: read() readDone()



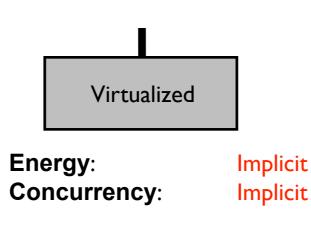
ICEM Architecture

• Defines three classes of drivers

- Virtualized provide only functional interface
- Dedicated provide functional and power interface
- Shared provide functional and lock interface

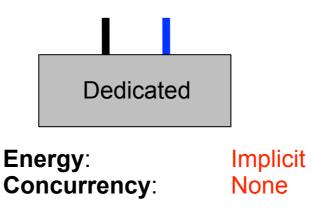
Virtualized Device Drivers

- Provide only a Functional interface
 - Assume multiple users
- Implicit concurrency control through buffering requests
- Implicit energy management based on pending requests
- Implemented for higher-level services that can tolerate longer latencies



Dedicated Device Drivers

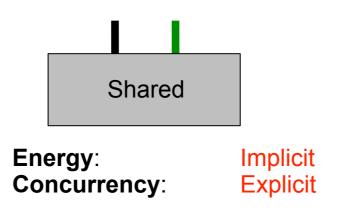
- Provide Functional and Power Control interfaces
 - Assume a single user
 - No concurrency control
- Explicit energy management
- Low-level hardware and bottom-level abstractions have a dedicated driver



Shared Device Drivers

• Provide Functional and Lock interfaces

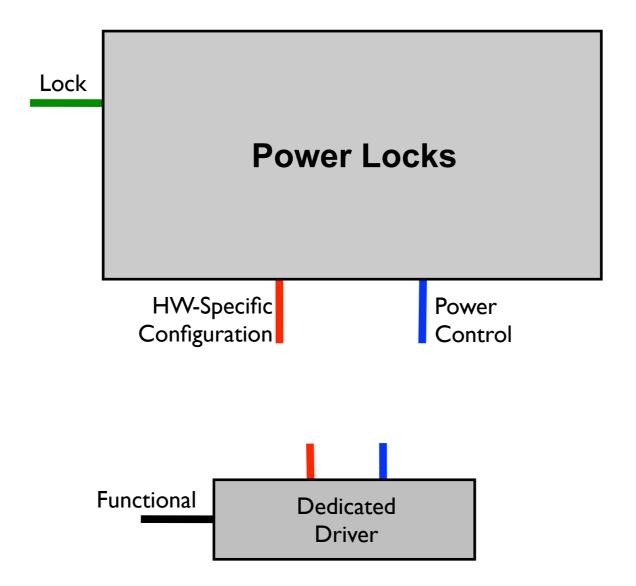
- Assume multiple users
- Explicit concurrency control through Lock request
- Implicit energy management based on pending requests
- Used by users with stringent timing requirements

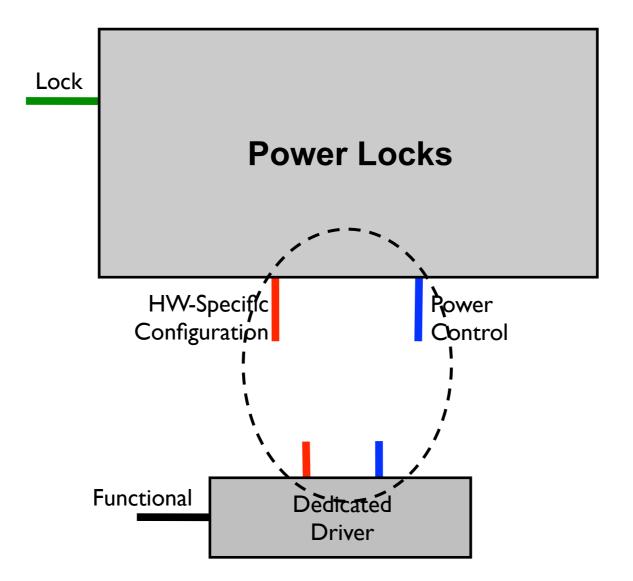


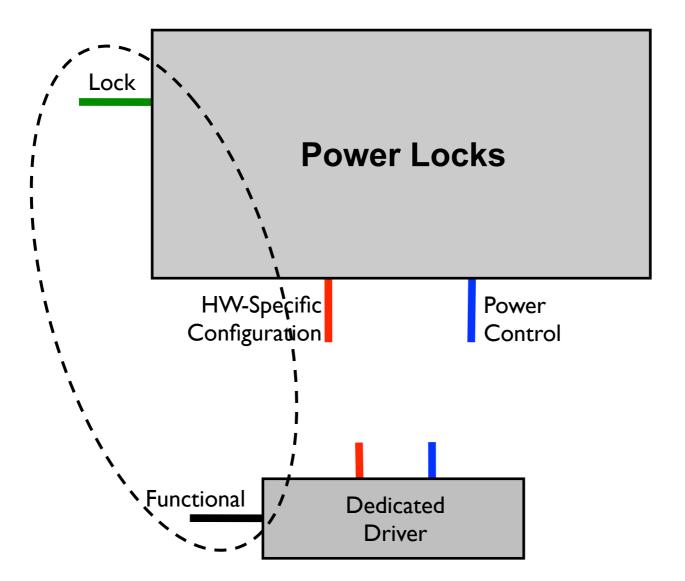
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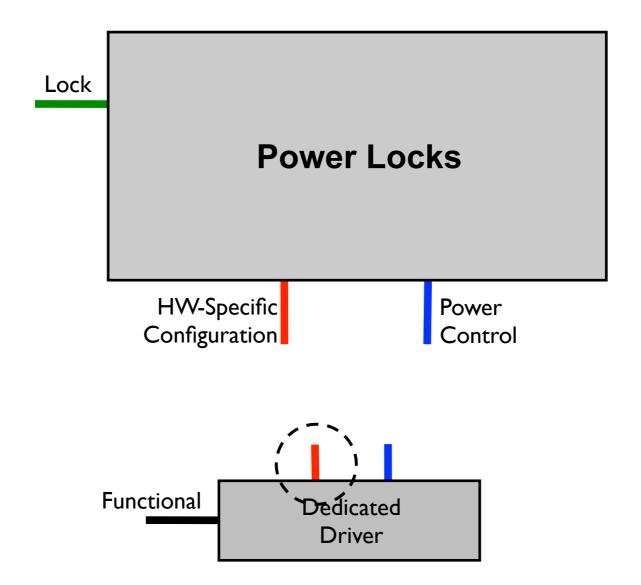
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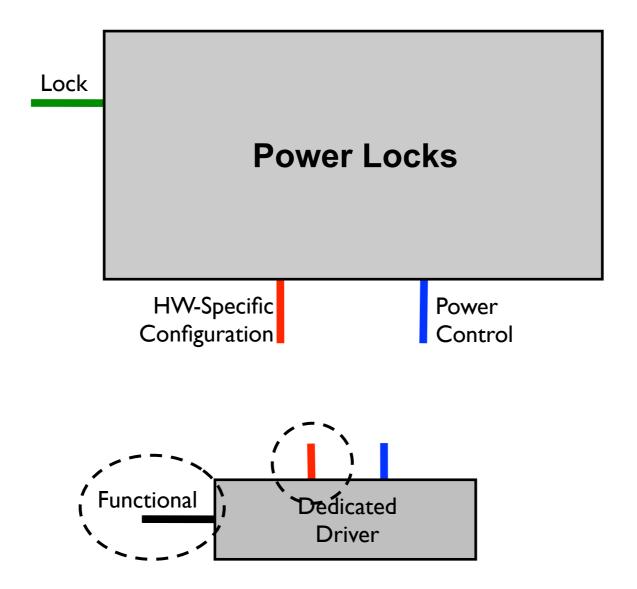
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- Shared provide functional and lock interface
- **Power Locks** split-phase locks with integrated energy and configuration management

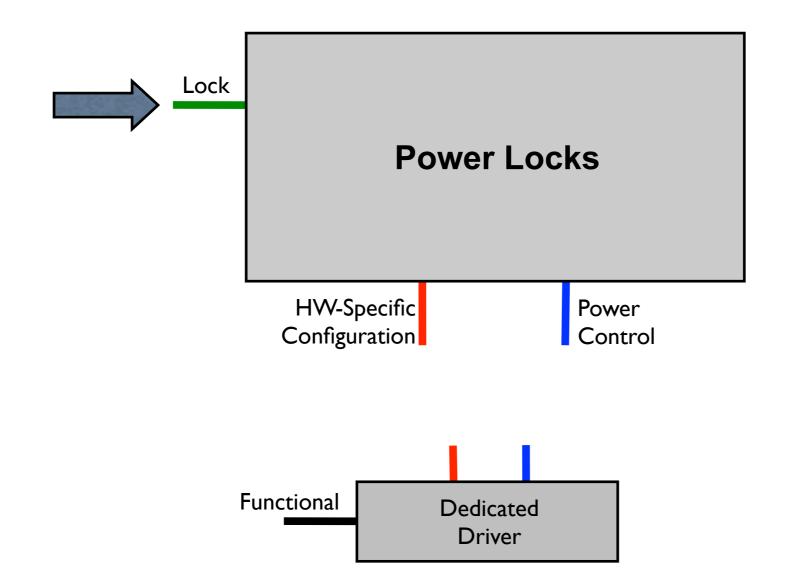


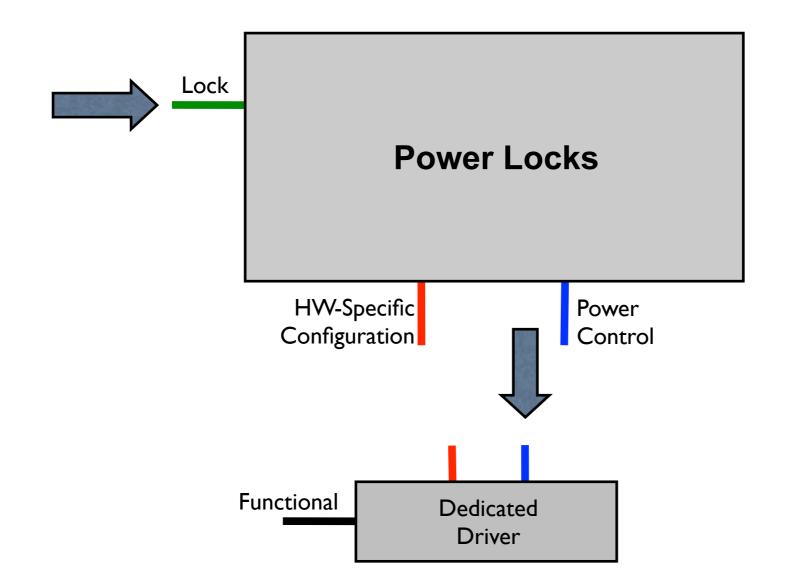


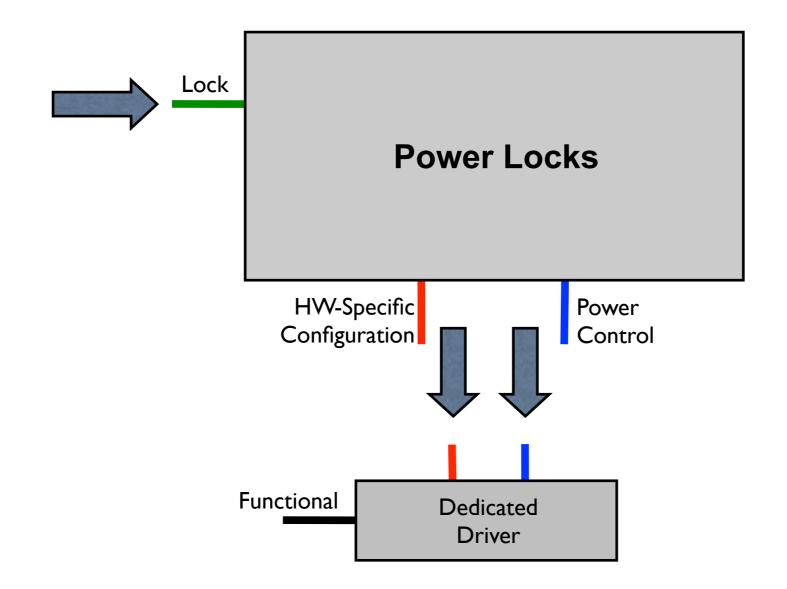


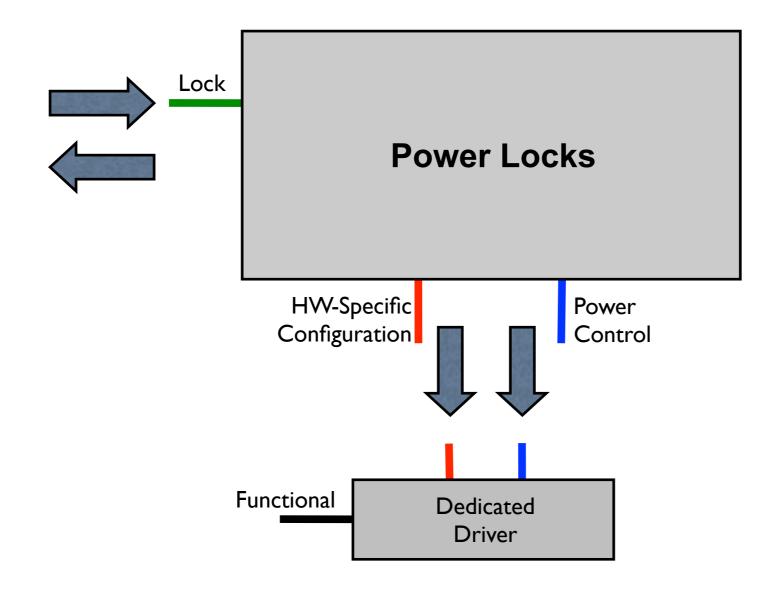


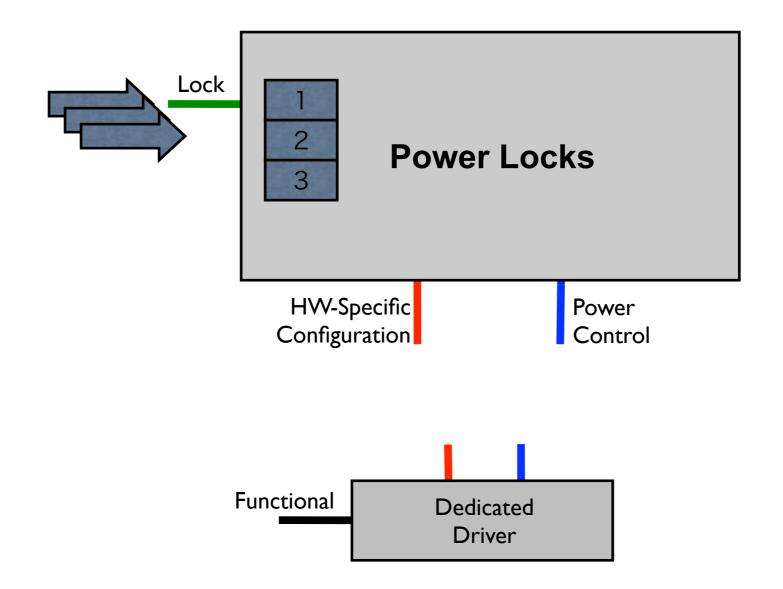


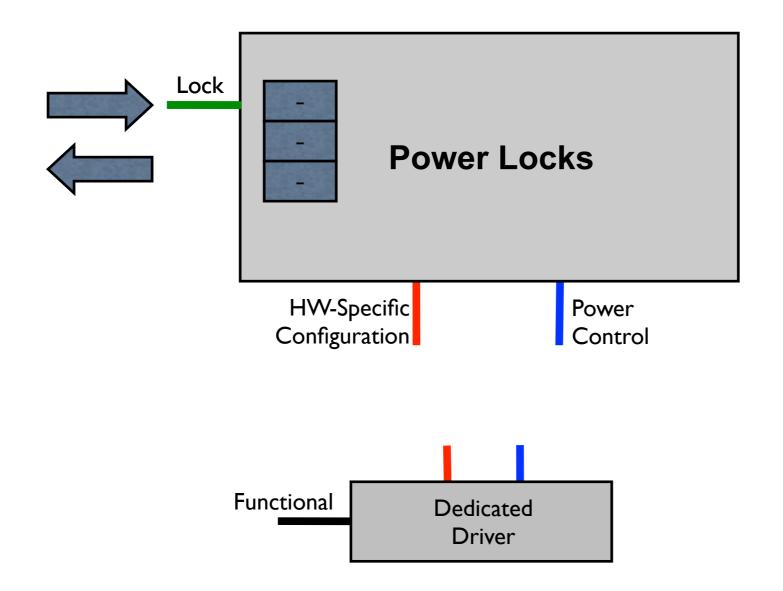


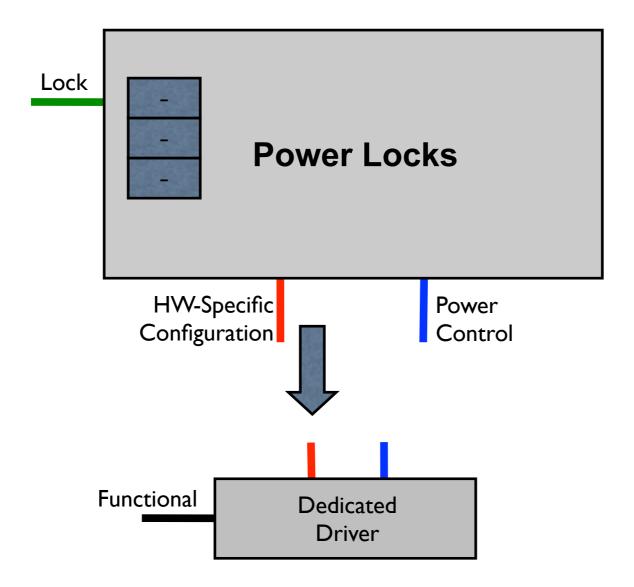


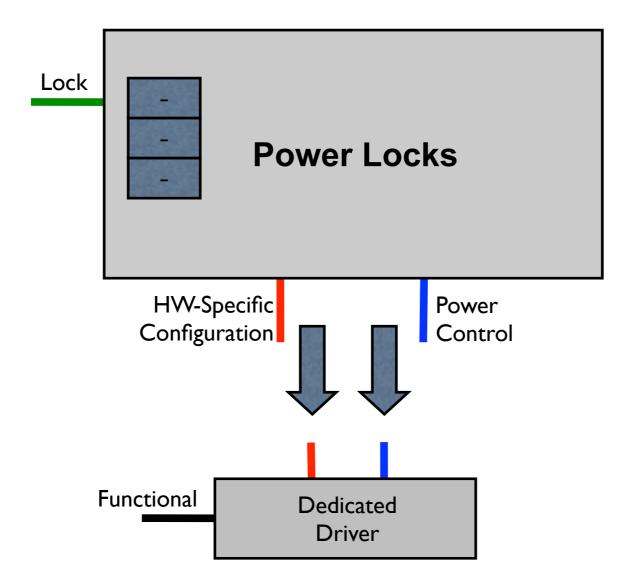








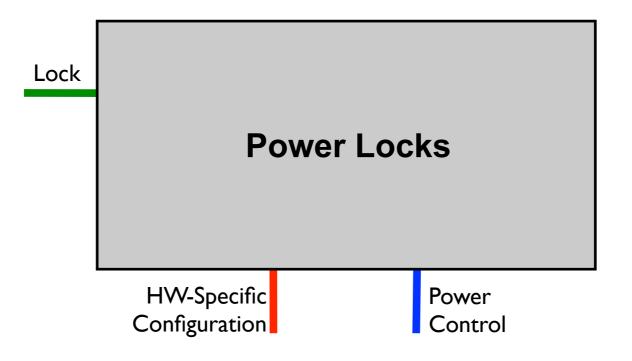


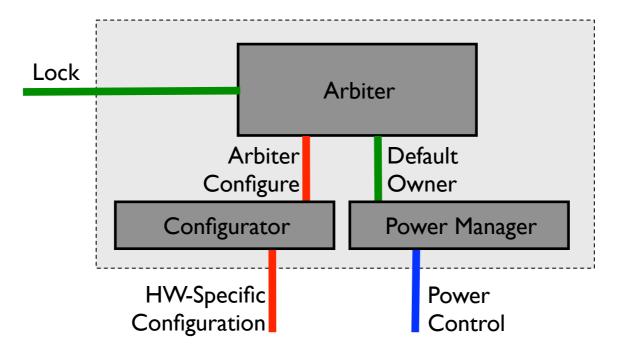


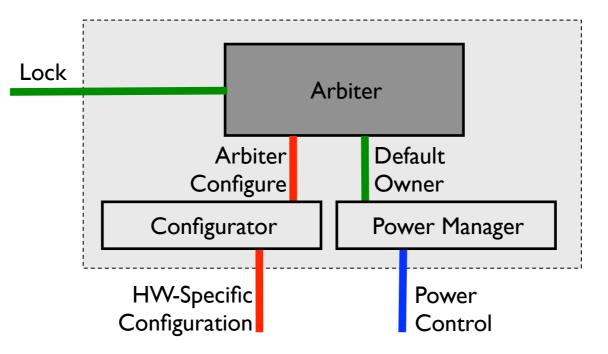
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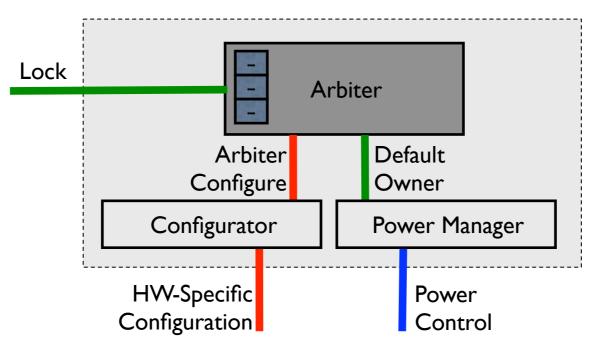
- Virtualized provide only functional interface
- Dedicated provide functional and power interface
- Shared provide functional and lock interface
- **Power Locks:** split-phase locks with integrated energy and configuration management
- Component library
 - Arbiters manage I/O concurrency
 - Configurators setup device specific configurations
 - Power Managers provide automatic power management



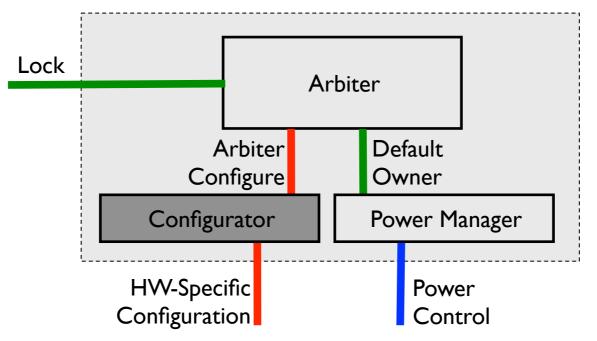




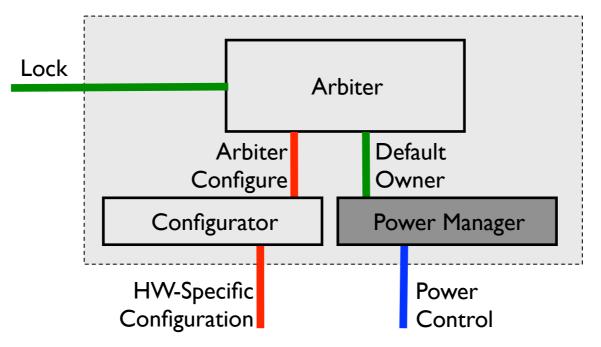
- Lock interface for concurrency control (FCFS, Round-Robin)
- ArbiterConfigure interface automatic hardware configuration
- DefaultOwner interface for automatic power management



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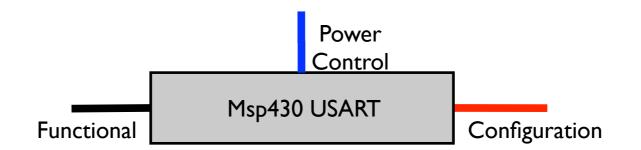
- Implement ArbiterConfigure interface
- Call hardware specific configuration from dedicated driver

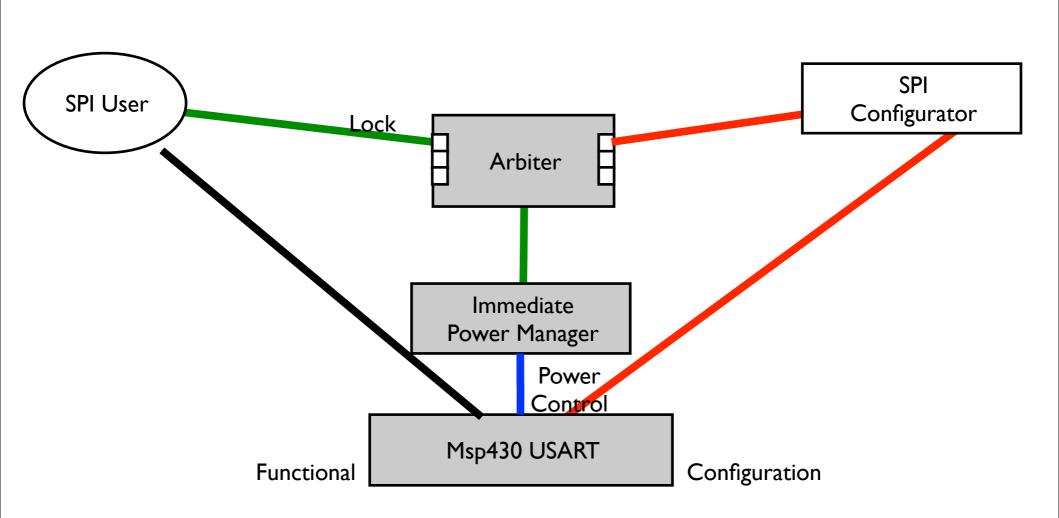


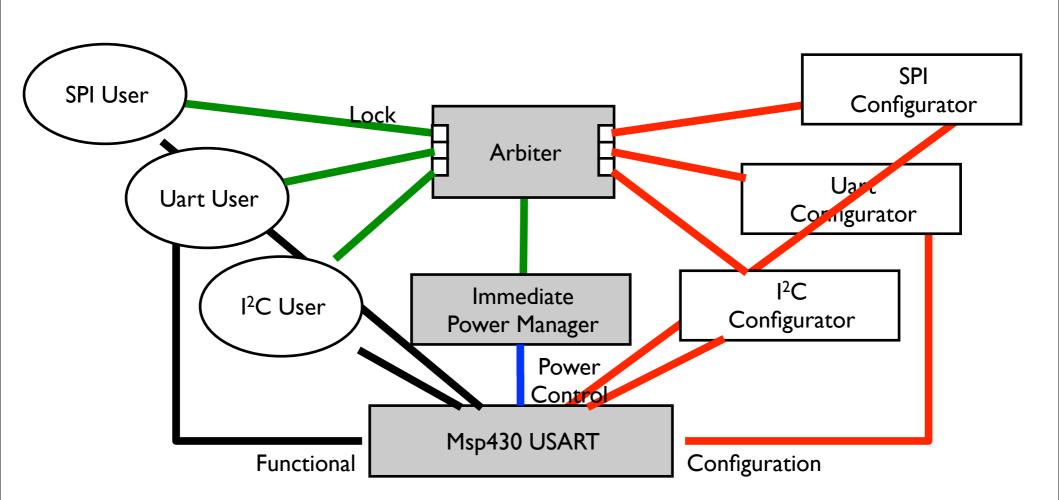
- Implement **DefaultOwner** interface
- Power down device when device falls idle
- Power up device when new lock request comes in
- Currently provide Immediate and Deferred policies

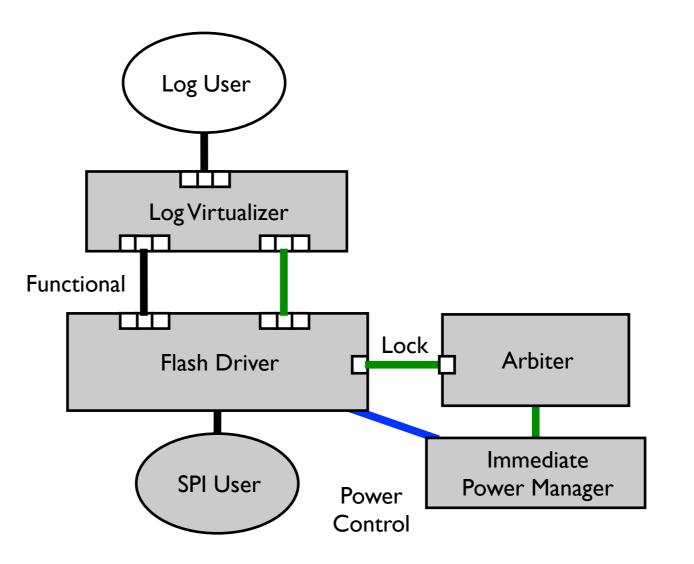
• Msp430 USART (Serial Controller)

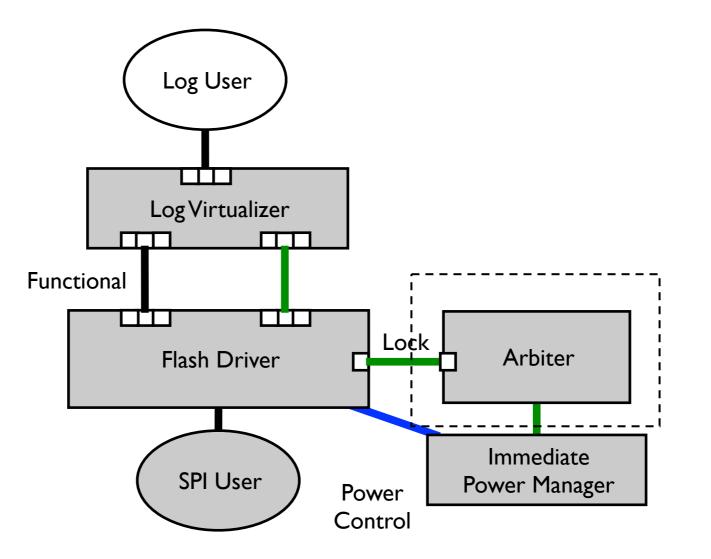
• Three modes of operation – SPI, I2C, UART

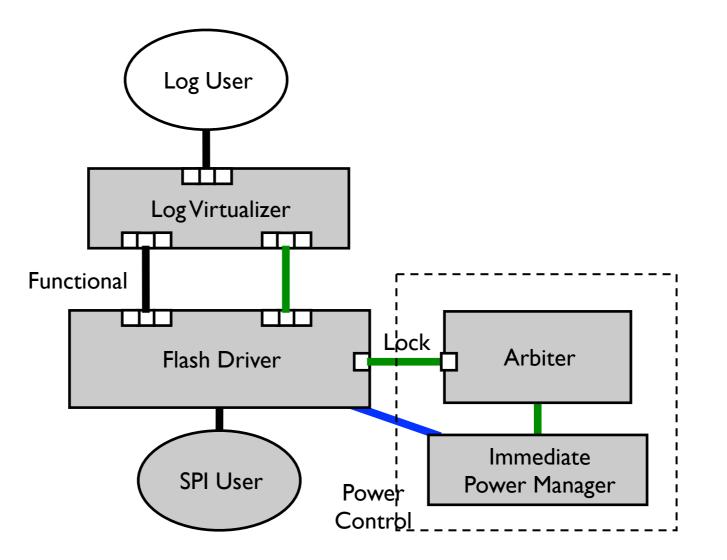


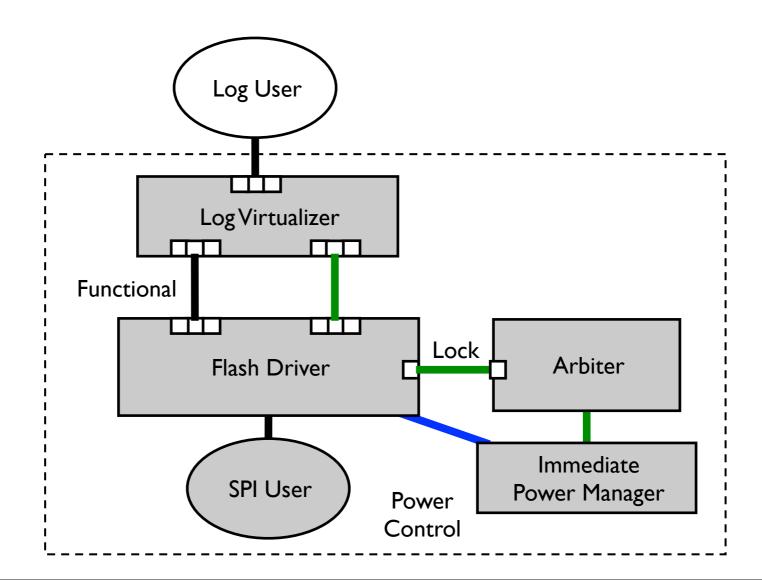


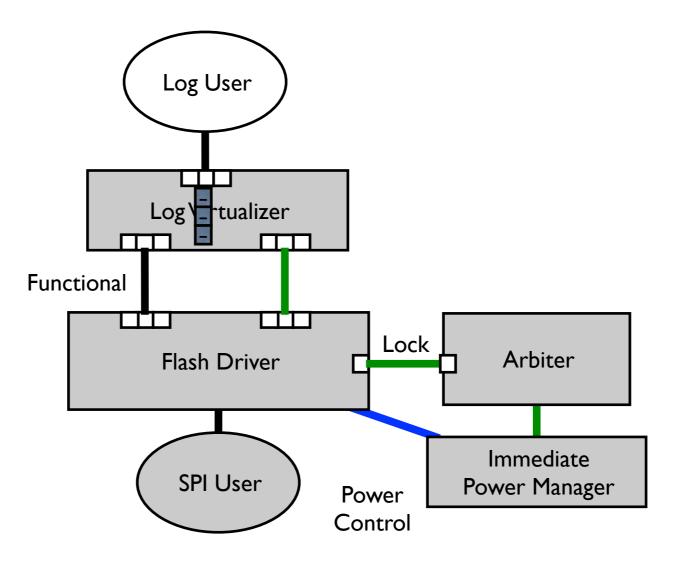


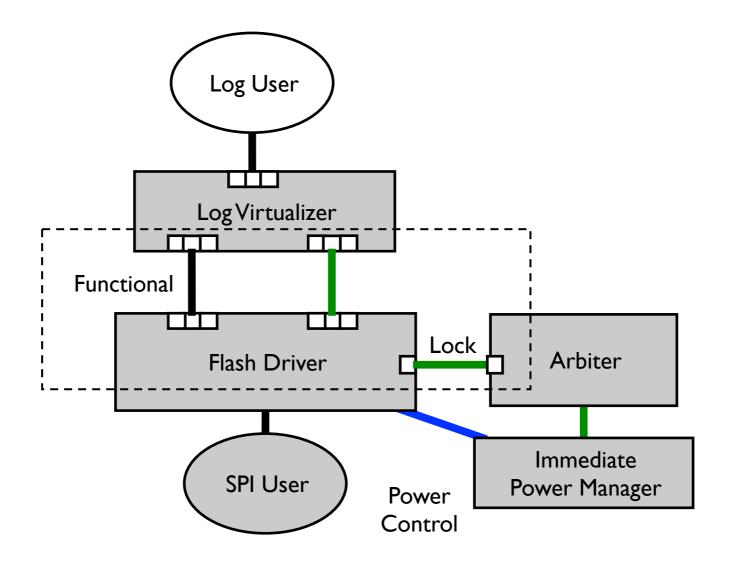


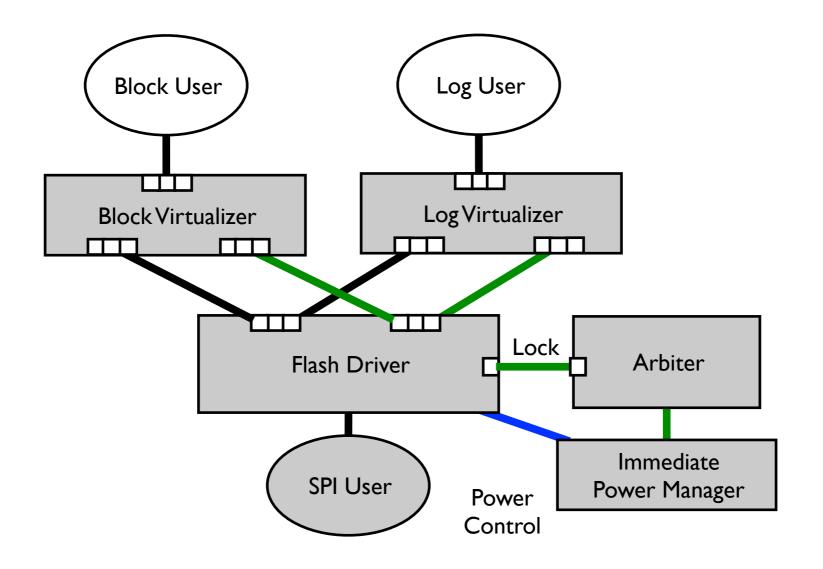


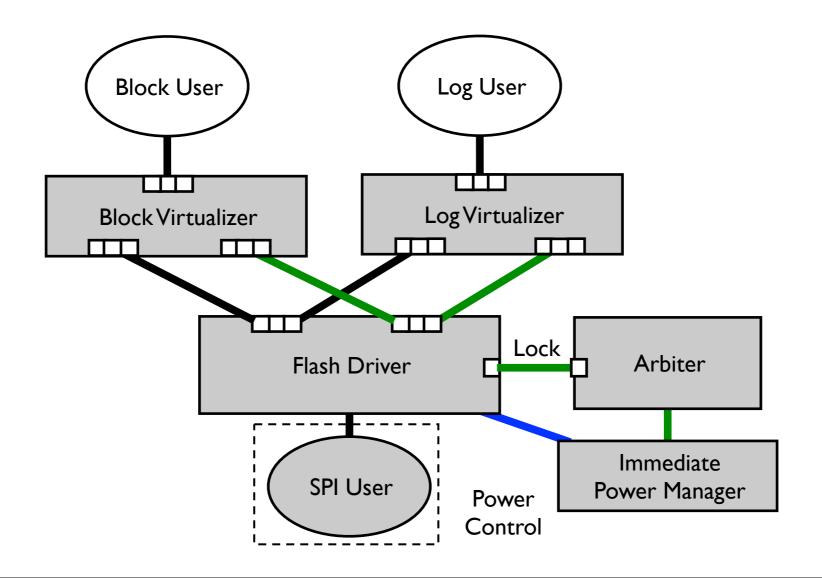












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Applications

- Hand Tuned Most energy efficient
 - ICEM All concurrent operations

Flash

- Optimal serial ordering
- Worst case serial ordering

<u>Consumer</u>

For all new entries:

Read next sample

Radio

Send current sample

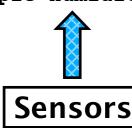
Every 12 hours:



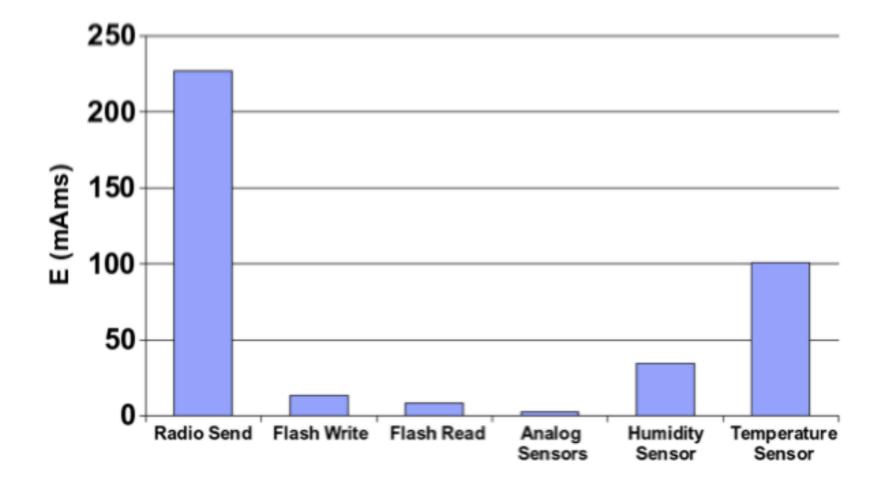
Serial +

Serial -

Every 5 minutes: Write prior samples Sample photo active Sample total solar Sample temperature Sample humidity

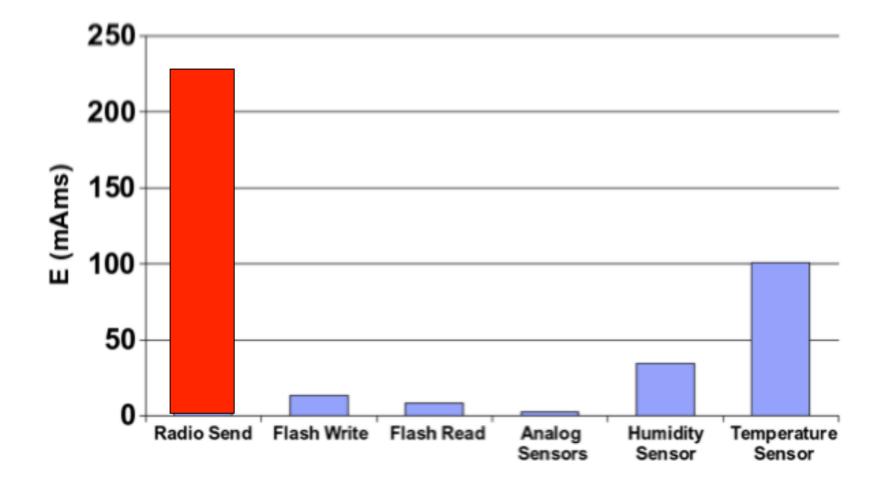


Tmote Energy Consumption



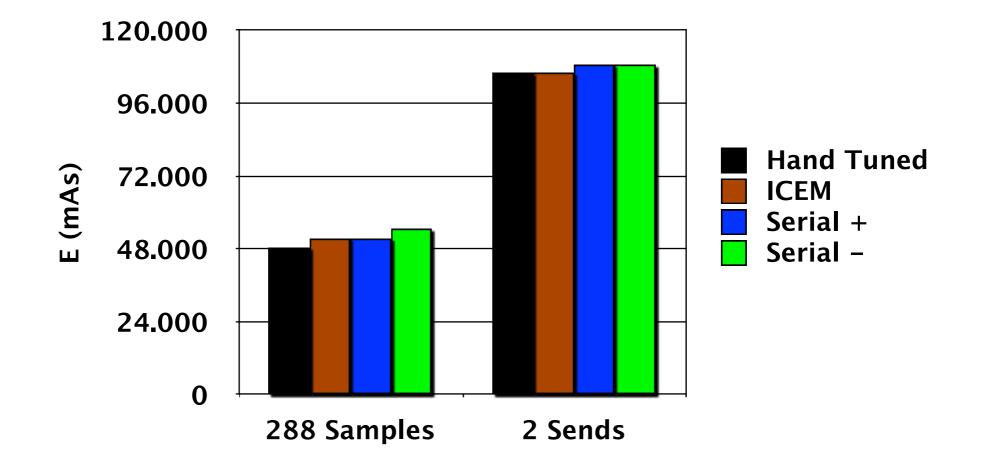
Average energy consumption for application operations

Tmote Energy Consumption



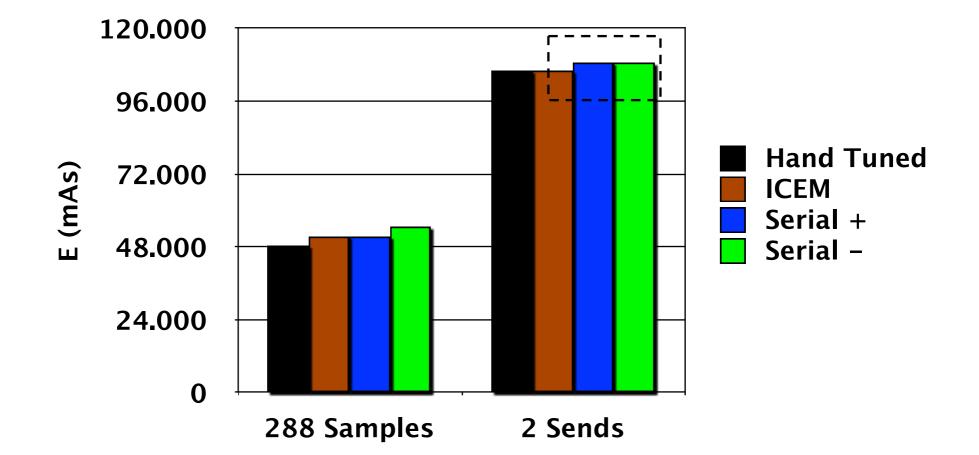
Average energy consumption for application operations

Application Energy Consumption



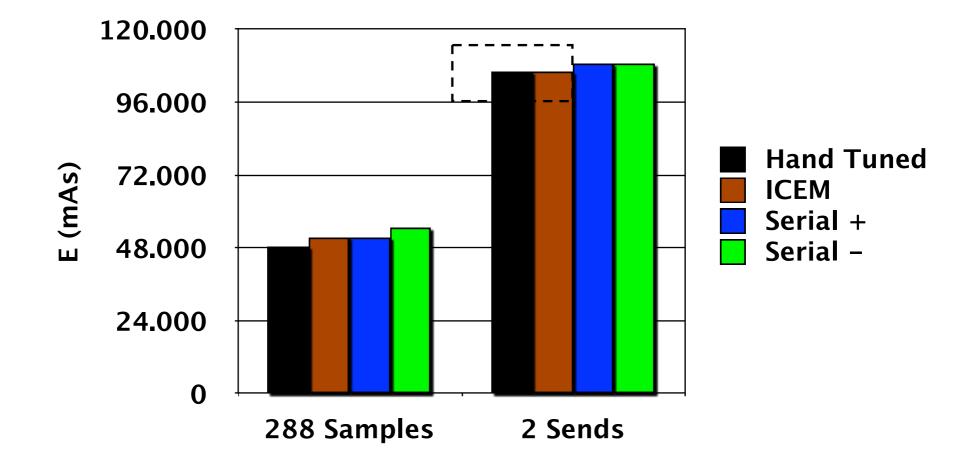
Application energy with 5 minute sampling interval and one send batch every 12 hours

Application Energy Consumption



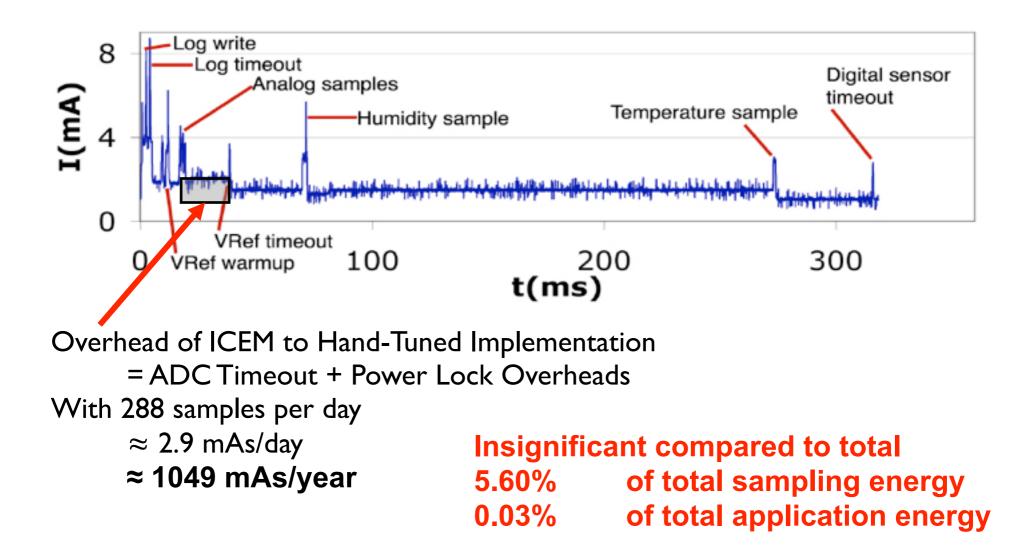
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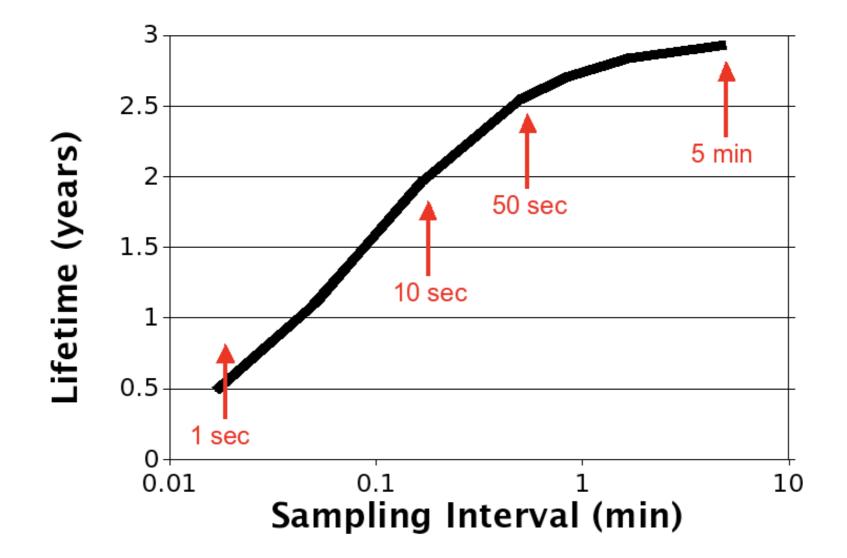


Application energy with 5 minute sampling interval and one send batch every 12 hours

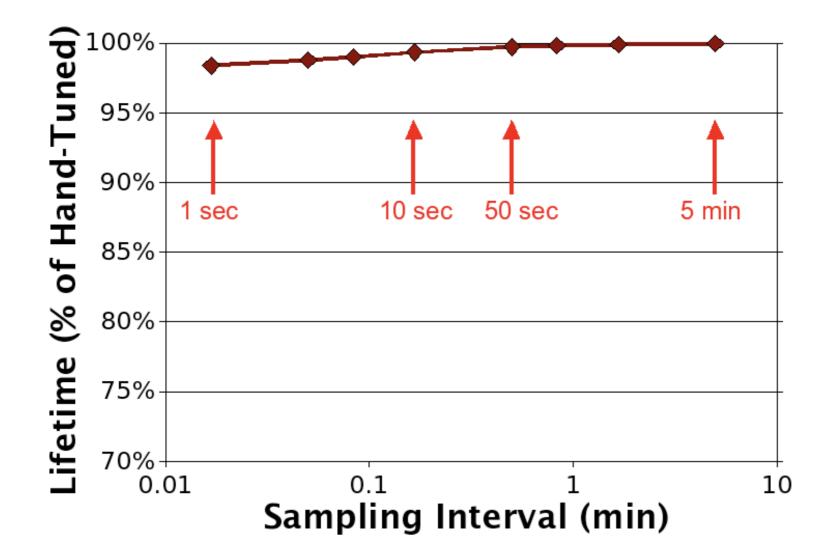
Sampling Power Trace



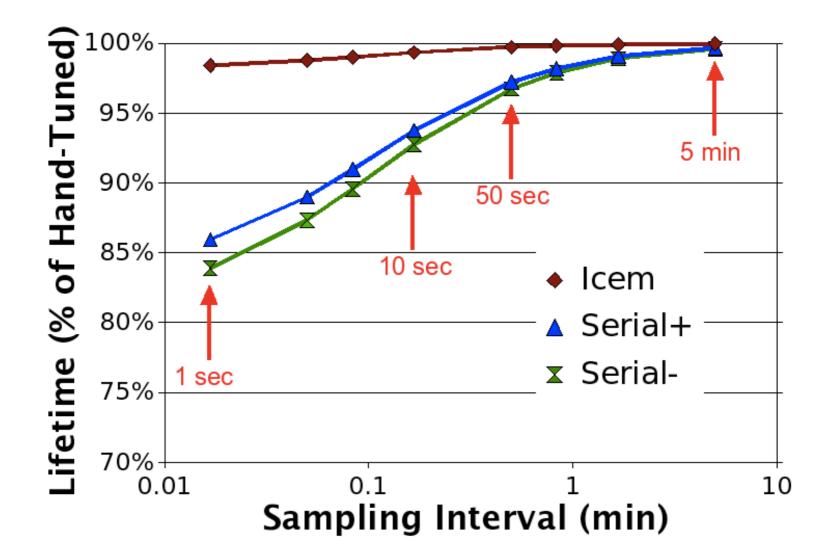
Expected Node Lifetimes



Expected Node Lifetimes



Expected Node Lifetimes



Evaluation Conclusions

• Conclusions about the OS

- Small RAM/ROM overhead
- Small computational overhead
- Efficiently manages energy when given enough information

• Conclusions for the developer

- Build drivers short power down timeouts
- Submit I/O requests in parallel

Conclusion

• ICEM: Integrated Concurrency and Energy Management

- Device driver architecture for low power devices
- At least 98.4% as energy efficient as hand-tuned implementation of representative application
- Simplifies application and driver development
- Questions the assumption that applications must be responsible for all energy management and cannot have a standardized OS with a simple API

Questions?





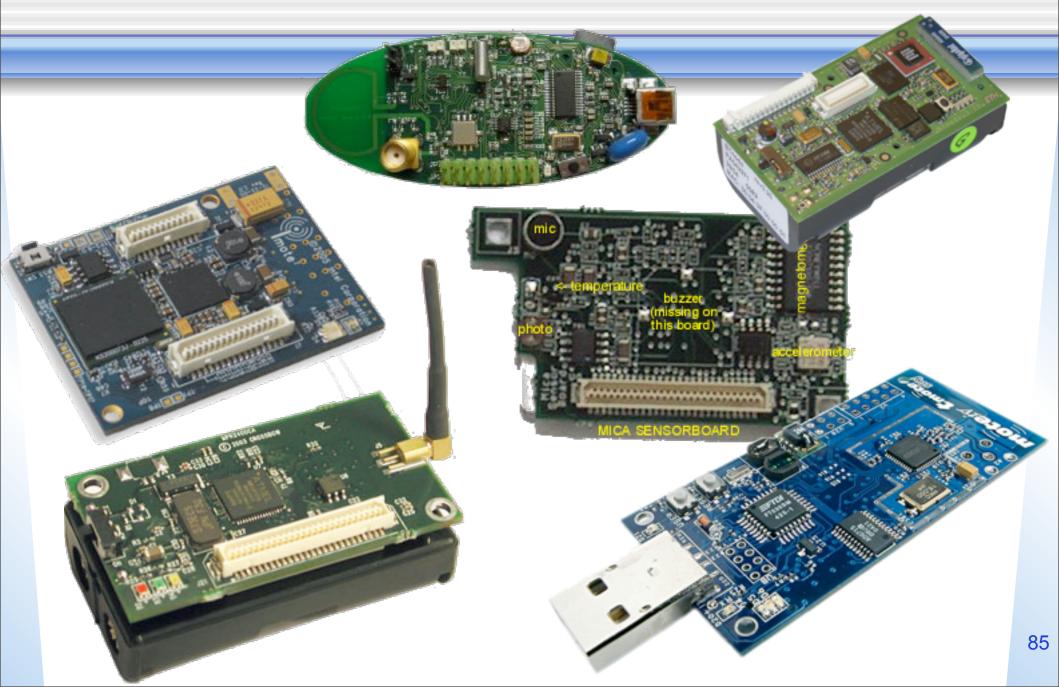
TKN Telecommunication Networks Group



Questions?

- SourceForge TinyOS CVS repository:
 - http://sourceforge.net/cvs/?group_id=28656
- Library components and interfaces
 - tinyos-2.x/tos/interfaces
 - tinyos-2.x/tos/lib/power
 - tinyos-2.x/tos/system
- Example Drivers
 - Atmega128 ADC: tos/chips/atm128/adc
 - MTS300 Photo: tos/sensorboards/mts300
 - MSP430 USART0: tos/chips/msp430/usart
 - Storage: tos/chips/stm25p
 - CC2420: tos/chips/cc2420

Hardware



Future Work

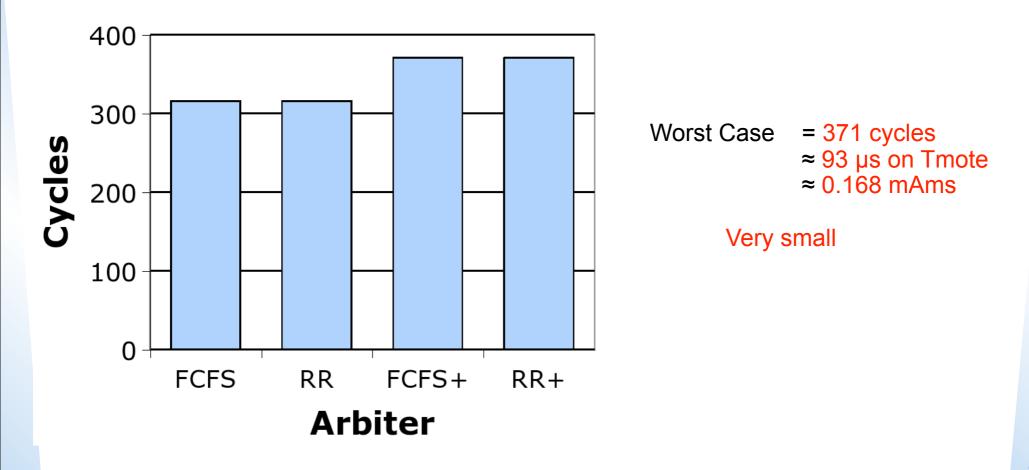
- Compile-time deadlock detection
- Conditional I/O Operations if(Temp.read() > 30) Humidity.read()
- Improved OS scheduling

Disclaimers

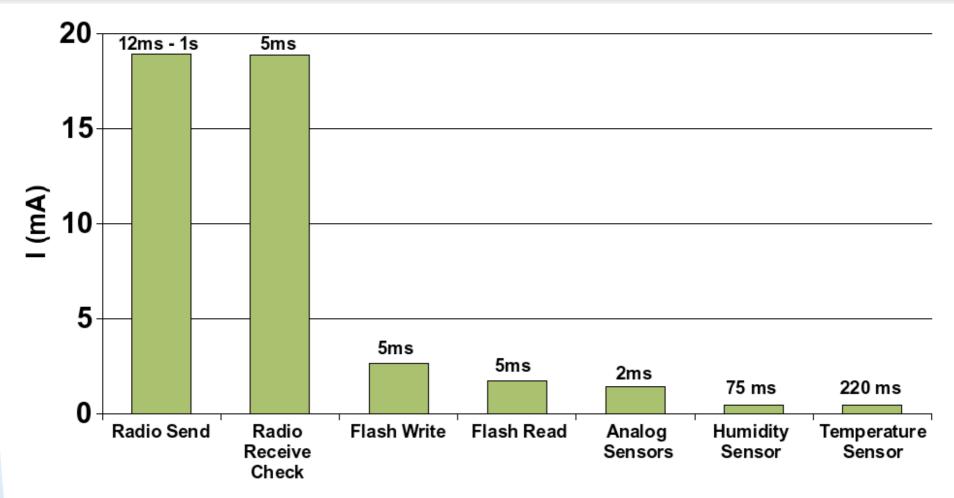
- Omission of MCU power management discussion
- Run time checks on arbiter operations
- Implementing ICEM in threaded OS

Microbenchmarks: Overhead

Per request MCU cycle overhead (locking, unlocking)



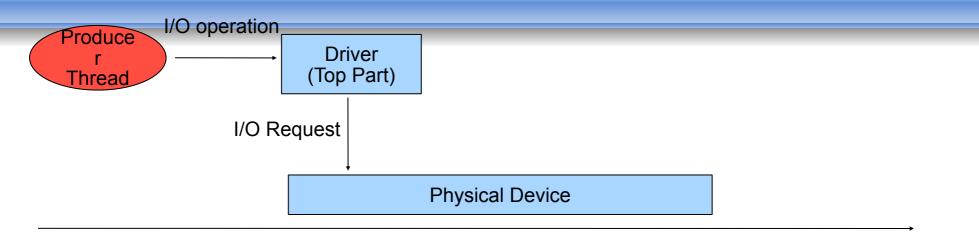
Tmote Current Consumption

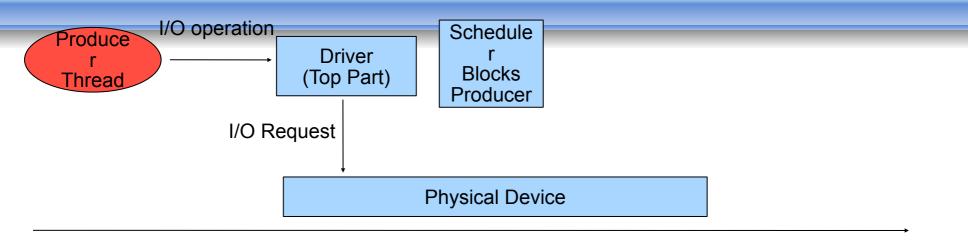


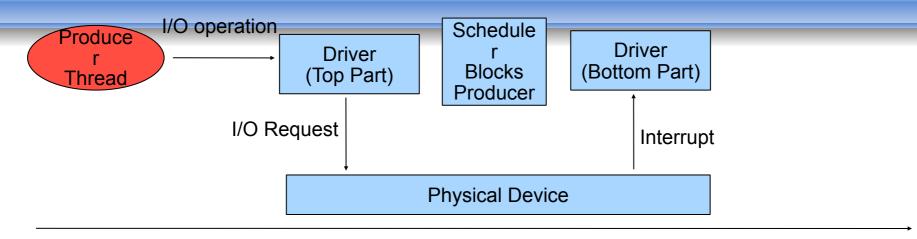
Average current consumption for application operations

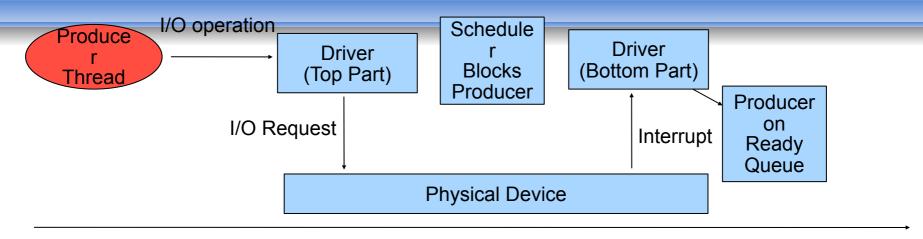


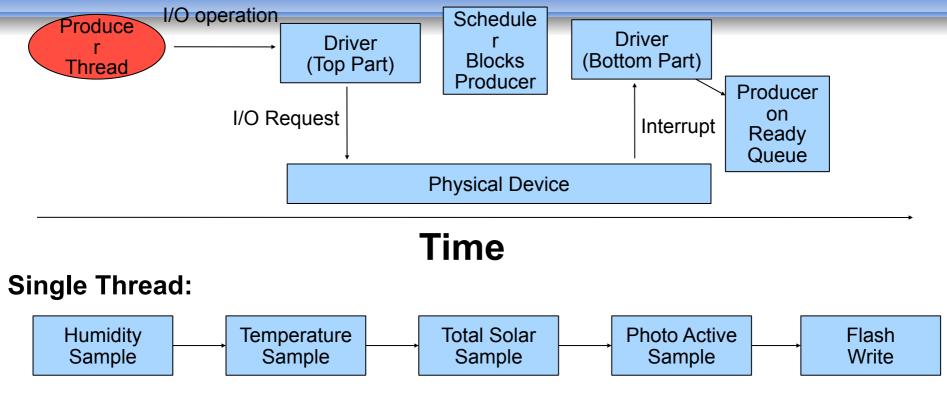
Physical Device



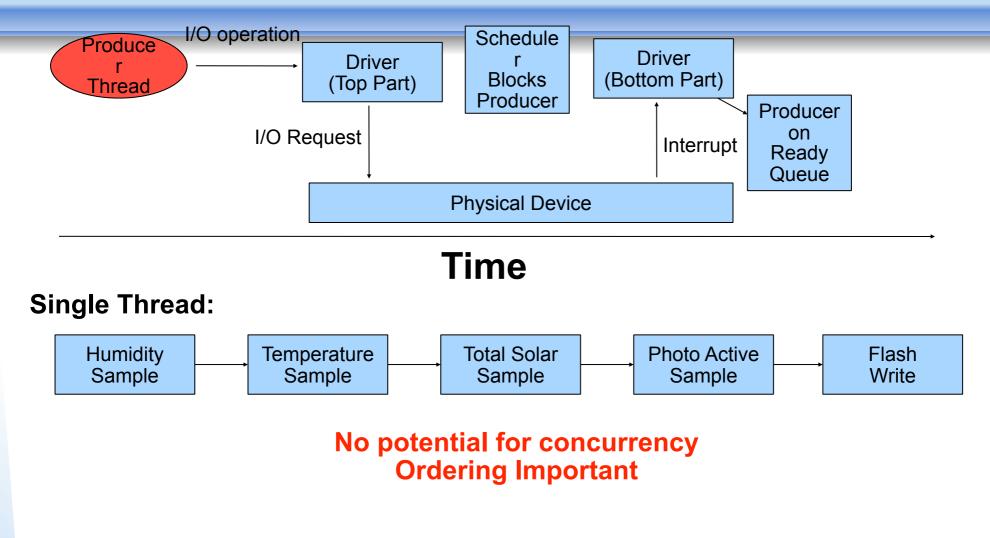


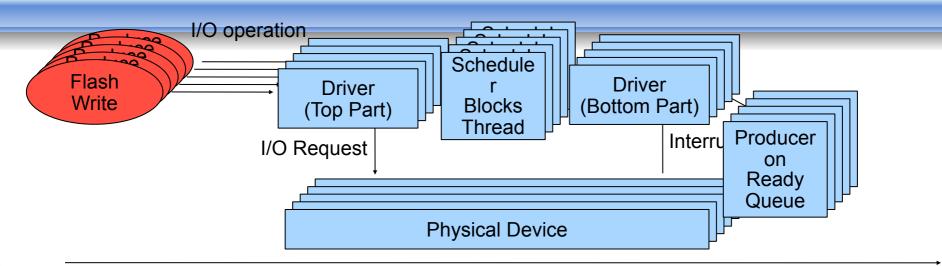






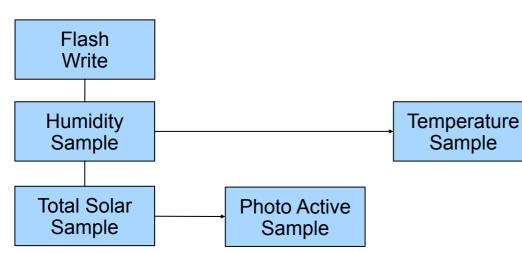
No potential for concurrency

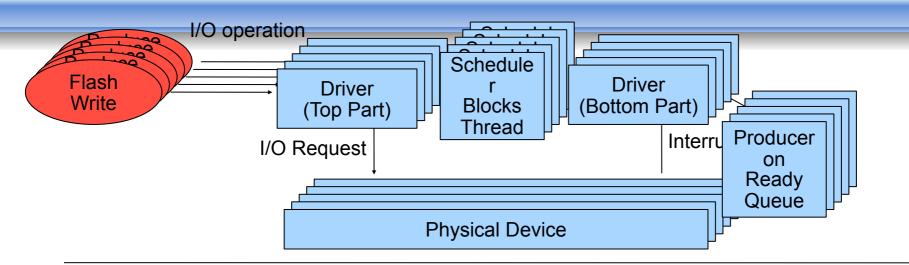




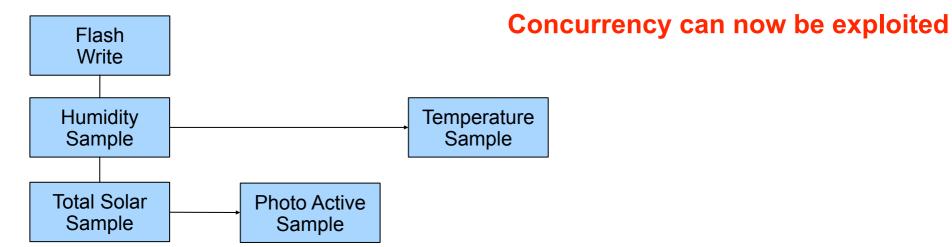
Time

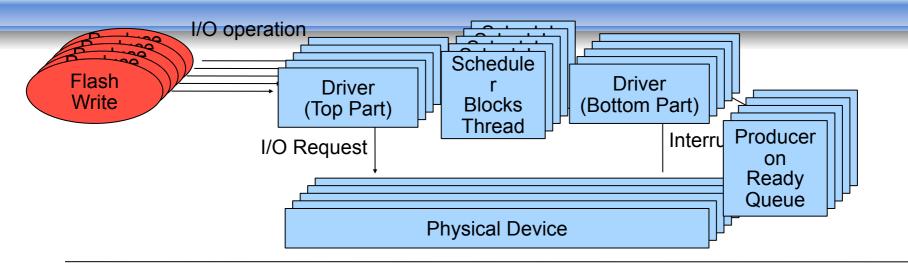
Multi-thread:



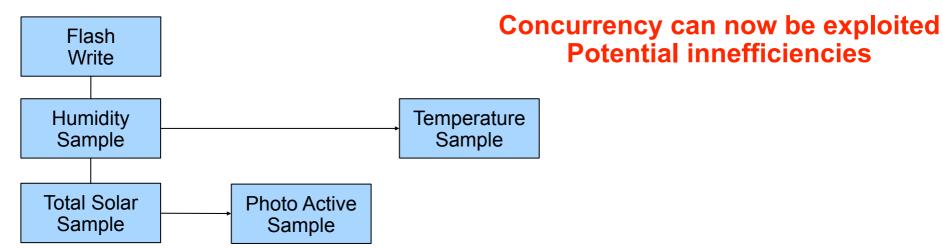


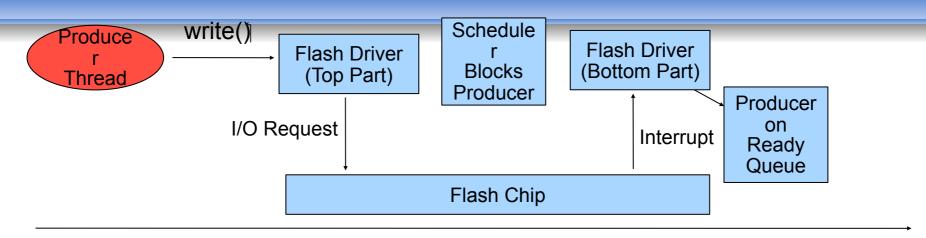
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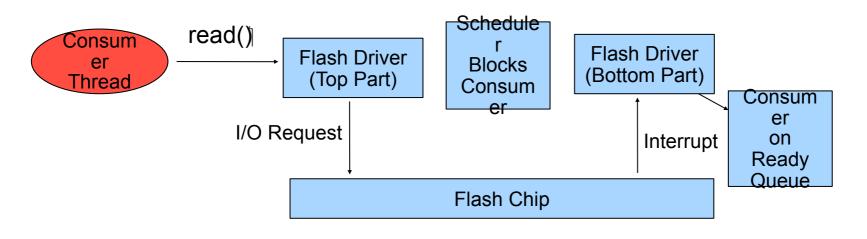


Multi-thread:

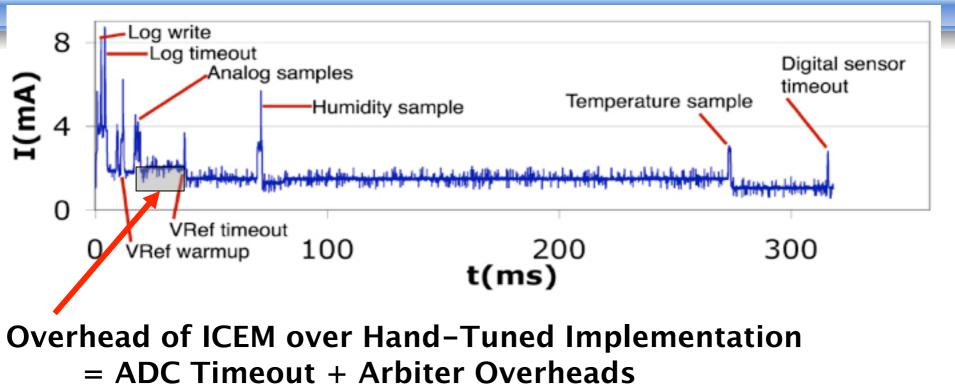




Time

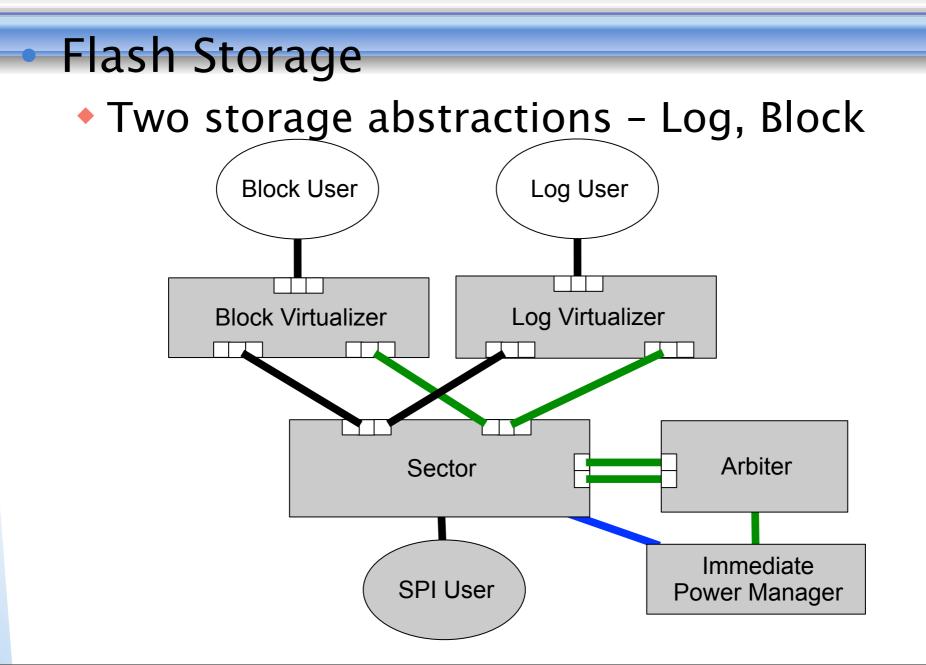


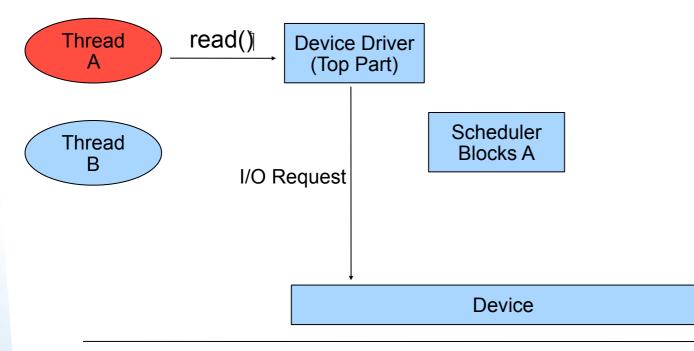
Sampling Power Trace

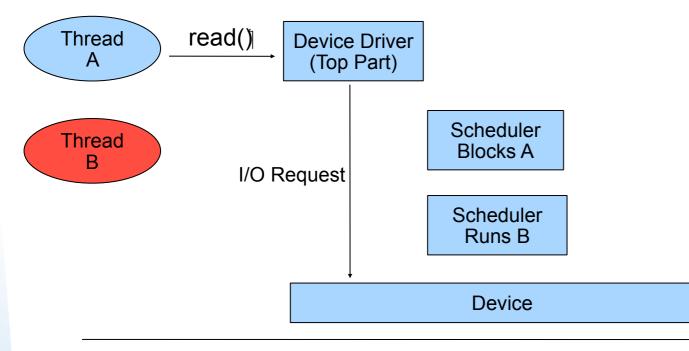


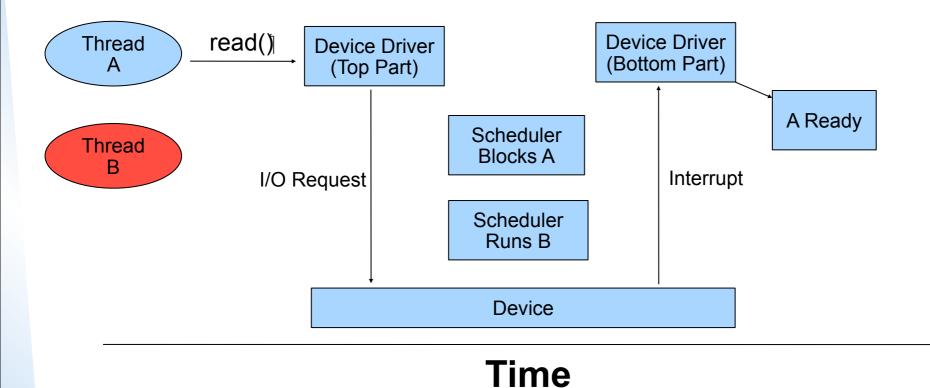
- = (536uA * 17ms) + (1920uA * 0.45ms)
 - = 9976 uAms/sample
 - \approx 0.01mAs / sample

Virtualized Driver Example

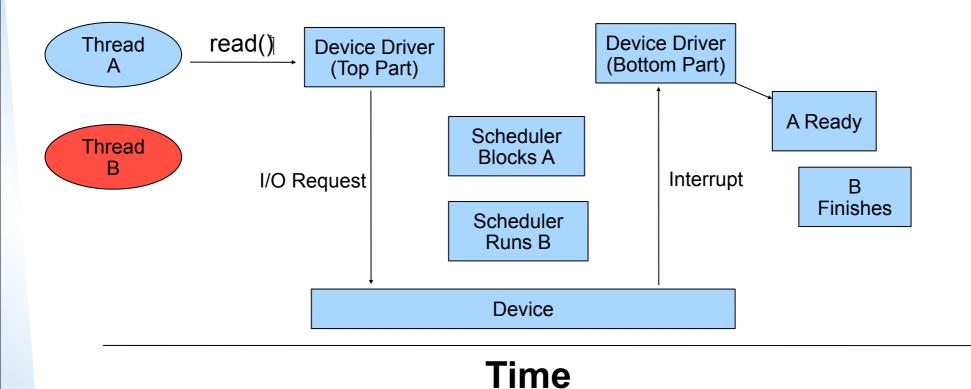




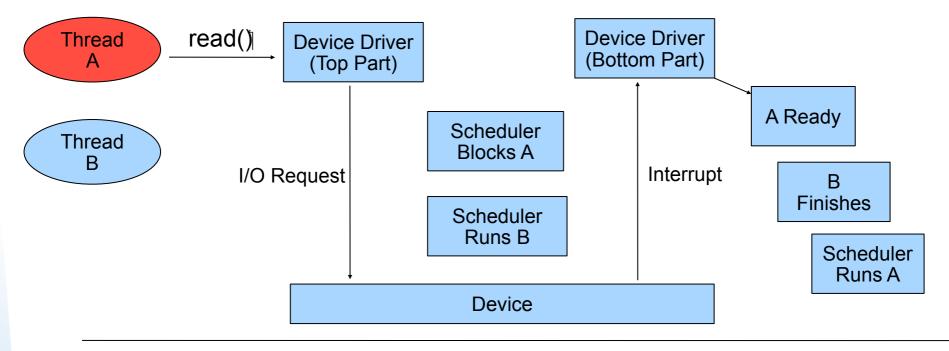


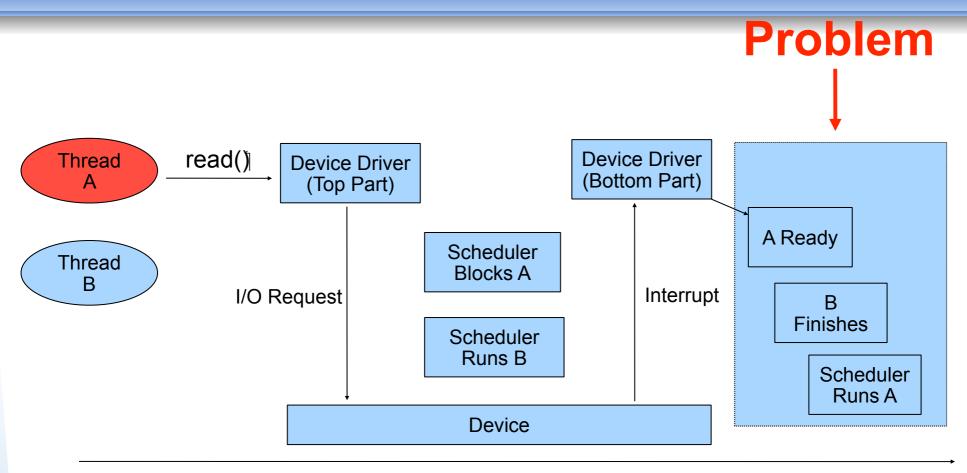


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Problem

- Sensornet applications have the capability of exploiting high levels of concurrency
 - Must do so without threads (i.e no concept of an execution entity)
 - Require extreme low-power operation
- Traditional systems not well suited
 - Blocking application level I/O calls
 - Thread scheduling in the device driver

