# Routing: Collection Tree Protocol

Original slides by Omprakash Gnawal

### Collection

#### • Anycast route to the sink(s)

- collects data from the network to a small number of sinks
- network primitive for other protocols
- A distance vector protocol

### Why focus on a few sinks?

### distance vector vs link state



### **Common Architecture**



### **Wireless Link Dynamics**



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### **Control and Data Rate Mismatch**

#### Can lead to poor performance



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#### Can lead to poor performance







### **CTP Noe's Approach**

- Enable control and data plane interaction
- Two mechanisms for efficient and agile topology maintenance
  - datapath validation
  - adaptive beaconing



# Outline

#### Control plane

- datapath validation
- adaptive beacons

#### Data plane

- queuing
- transmit time
- cache
- Evaluation
- Conclusion

# Data path validation

### **Datapath validation**

- Use data packets to validate the topology
  - inconsistencies
  - loops
- Receiver checks for consistency on each hop
  - transmitter's cost is in the header
- Same time-scale as data packets
  - validate only when necessary













Cost does not decrease



### **Routing Consistency**

- Next hop should be closer to the destination
- Maintain this consistency criteria on a path

$$\forall i \in \{0, k-1\}, ETX(n_i) > ETX(n_{i+1})$$



Inconsistency due to stale state

### Datapath validation

- cost in the packet
- receiver checks

- larger cost than on the packet
- On Inconsistency
  - don't drop the packets
  - signal the control plane



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# **Routing Consistency**

# **How Fast to Send Beacons?**

#### • Using a fixed rate beacon interval

- Can be too fast
- Can be too slow
- Agility-efficiency tradeoff
- Agile+Efficient possible?

# **Routing as Consistency**

- Routing as a consistency problem
  - costs along a path must be consistent
- Use consistency protocol in routing
  - leverage research on consistency protocols
  - trickle

# **Trickle**

#### Detecting inconsistency

- code propagation: version number mismatch
- does not work for routing: use path consistency
- Control propagation rate
  - start with a small interval
  - double the interval up to some max
  - reset to the small interval when inconsistent

# **Control Traffic Timing**

- Extend Trickle to time routing beacons
- Reset the interval
  - ETX(receiver) >= ETX(sender)
  - significant decrease in gradient [found better link]
  - "Pull" bit no valid route



### **Adaptive Beacon Timing**



Tutornet

Infrequent beacons in the long run

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### **Adaptive vs Periodic Beacons**



### **Adaptive vs Periodic Beacons**



# **Node Discovery**



# Data Plane

# Data plane

• Goals: efficient, robust, and reliable forwarding

#### • Mechanisms

- per client queueing
- hybrid send queue
- transmit timer
- transmit cache

# Data plane mechanisms

#### • Queueing discipline

- Per-client queueing [top-level]
  - each client may have one outstanding packet
  - achieves better fairness than a shared queue
- Hybrid send queue [lower-level]
  - contains both route-through and locally-generated traffic
  - duplicate packets are dropped [i.e., not inserted in the queue]

#### Transmission Cache

- for each transmitted packet insert (src, seq, THL)
- determine if a packet is duplicate

# **Transmit Timer**

• Self-interference between packets may be a problem



# **Transmit Timer**

#### • Rate control: delay the transmission of packets

- the transmission of consecutive packets is randomized between (1.5, 2.5) packet times
- Is this good enough?

# Evaluation

# **Experiments**

- 12 testbeds
- 20-310 nodes
- 7 hardware platforms
- 4 radio technologies
- 6 link layers

Testbed	Platform	Nodes	Physical size $m^2$ or $m^3$
Tutornet (16)	Tmote	91	$50 \times 25 \times 10$
Wymanpark	Tmote	47	$80 \times 10$
Motelab	Tmote	131	$40 \times 20 \times 15$
Kansei <sup>a</sup>	TelosB	310	40×20
Mirage	Mica2dot	35	50×20
NetEye	Tmote	125	6×4
Mirage	MicaZ	86	50×20
Quanto	Epic-Quanto	49	35×30
Twist	Tmote	100	$30 \times 13 \times 17$
Twist	eyesIFXv2	102	$30 \times 13 \times 17$
Vinelab	Tmote	48	60×30
$Blaze^b$	Blaze	20	30×30

Variations in hardware, software, RF environment, and topology

# **Evaluation Goals**

#### • Reliable?

- Packets delivered to the sink
- Efficient?
  - TX required per packet delivery
- Robust?
  - Performance with disruption

### **CTP Noe Trees**



Testbed	Delivery Ratio	
Wymanpark	0.9999	
Vinelab	0.9999	
Tutornet	0.9999	
NetEye	0.9999	
Kansei	0.9998	
Mirage-MicaZ	0.9998	
Quanto	0.9995	
Blaze	0.9990	
Twist-Tmote	0.9929	
Mirage-Mica2dot	0.9895	
Twist-eyesIFXv2	0.9836	
Motelab	0.9607	

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Delivery Ratio	
0.9999	]
0.9999	
0.9999	
0.9999	
0.9998	
0.9998	
0.9995	
0.9990	
0.9929	
0.9895	False
0.9836	ack
0.9607	] <retransmit< td=""></retransmit<>
	Delivery Ratio 0.9999 0.9999 0.99999 0.99998 0.99998 0.99998 0.99998 0.99995 0.99990 0.99929 0.9895 0.9836 0.9836 0.9607

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Twist-Tmote	0.9929	
Mirage-Mica2dot	0.9895	False
Twist-eyesIFXv2	0.9836	ack
Motelab	0.9607	Retransmit

High end-to-end delivery ratio (but not on all the testbeds!)





High delivery ratio across time (short experiments can be misleading!) 28





Tutornet









Low duty-cycle with low-power MACs

30












High delivery ratio despite serious network-wide disruption (most loss due to reboot while buffering packet)

# **CTP Noe Performance Summary**

#### • Reliability

- Delivery ratio > 90% in all cases
- Efficiency
  - Low cost and 5% duty cycle
- Robustness
  - Functional despite network disruptions

# Conclusion

- "Hard" networks → good protocols
  - Tutornet & Motelab
- Wireless routing benefits from data and control plane interaction
- Lessons applicable to distance vector routing
  - Datapath validation & adaptive beaconing
- Data trace from all the testbeds available at
- http://sing.stanford.edu/gnawali/ctp/

## **Control Plane**

ETX, MT, MultiHopLQI, EAR, LOF, AODV, DSR, BGP, RIP, OSPF, Babel

### Data Plane

Flush, RMST, CODA, Fusion, IFRC, RCRT

## Link Layer

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