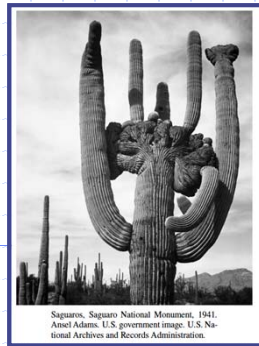


Presentation for use with the textbook, *Algorithm Design and Applications*, by M. T. Goodrich and R. Tamassia, Wiley, 2015

Minimum Spanning Trees



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1

Minimum Spanning Trees

Spanning subgraph

- Subgraph of a graph G containing all the vertices of G

Spanning tree

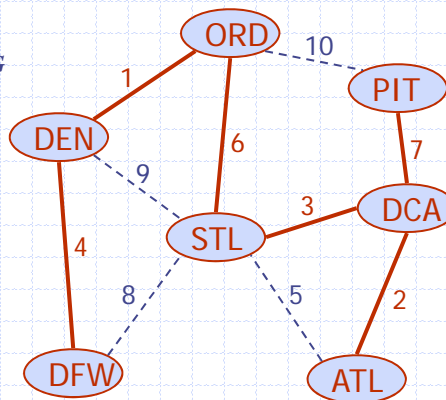
- Spanning subgraph that is itself a (free) tree

Minimum spanning tree (MST)

- Spanning tree of a weighted graph with minimum total edge weight

Applications

- Communications networks
- Transportation networks



2

2

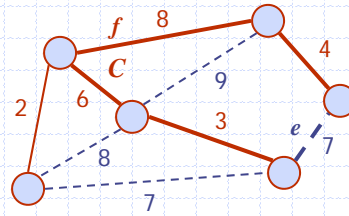
Cycle Property

Cycle Property:

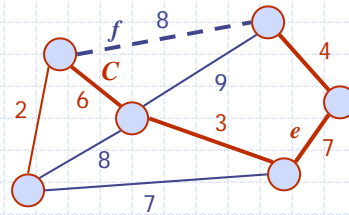
- Let T be a minimum spanning tree of a weighted graph G
- Let e be an edge of G that is not in T and C let be the cycle formed by e with T
- For every edge f of C , $weight(f) \leq weight(e)$

Proof:

- By contradiction
- If $weight(f) > weight(e)$ we can get a spanning tree of smaller weight by replacing e with f



Replacing f with e yields a better spanning tree



3

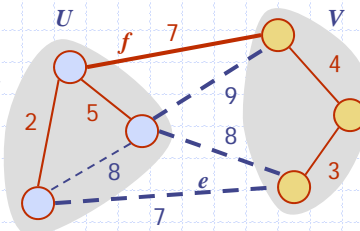
Partition Property

Partition Property:

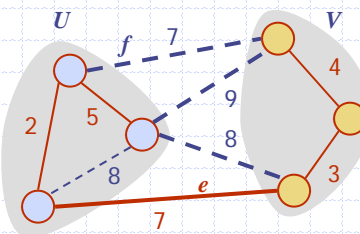
- Consider a partition of the vertices of G into subsets U and V
- Let e be an edge of minimum weight across the partition
- There is a minimum spanning tree of G containing edge e

Proof:

- Let T be an MST of G
- If T does not contain e , consider the cycle C formed by e with T and let f be an edge of C across the partition
- By the cycle property, $weight(f) \leq weight(e)$
- Thus, $weight(f) = weight(e)$
- We obtain another MST by replacing f with e



Replacing f with e yields another MST



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Prim-Jarnik's Algorithm

- Similar to Dijkstra's algorithm
- We pick an arbitrary vertex s and we grow the MST as a cloud of vertices, starting from s
- We store with each vertex v label $d(v)$ representing the smallest weight of an edge connecting v to a vertex in the cloud
- At each step:
 - We add to the cloud the vertex u outside the cloud with the smallest distance label
 - We update the labels of the vertices adjacent to u

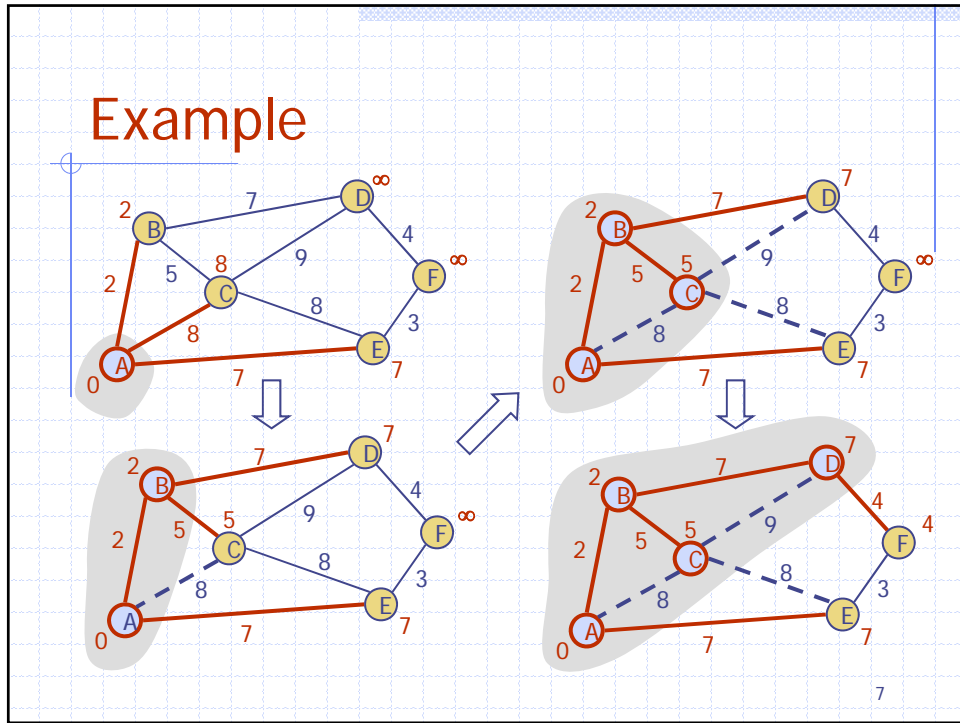
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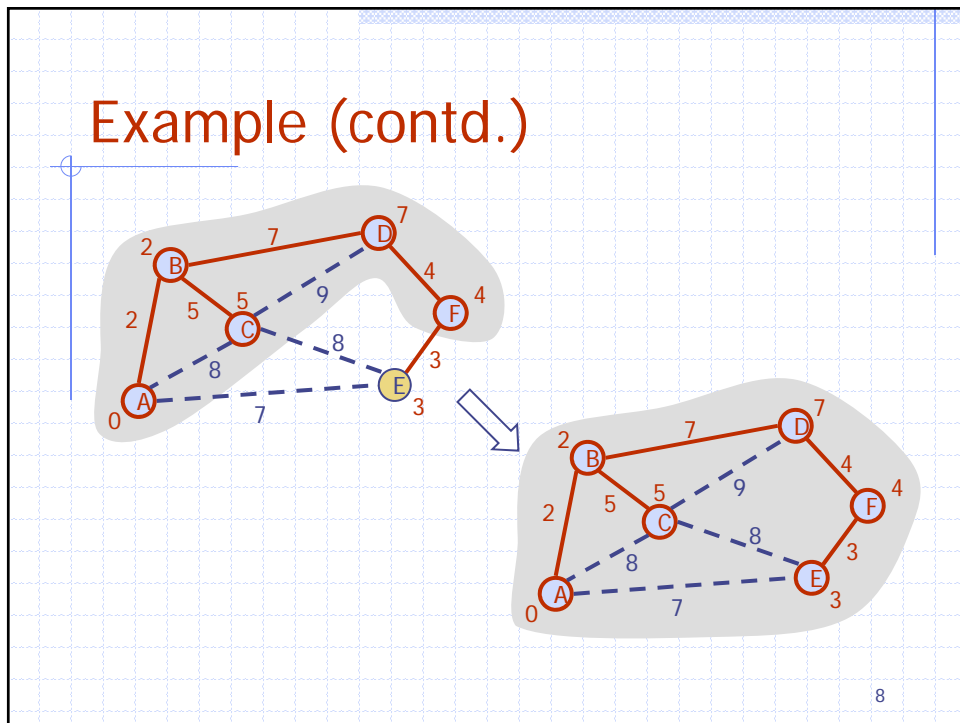
Prim-Jarnik's ~~Dijkstra's~~ Algorithm: Details

- **Input:** A weighted directed graph $G = (V, E)$, where $V = \{1, 2, \dots, n\}$;
- **Output:** The distance from vertex 1 to every other vertex in G ;
- 1. $X = \{1\}$; $Y \leftarrow V - \{1\}$; $D[1] \leftarrow 0$;
- 2. for $y \leftarrow 2$ to n
- 3. if (y is adjacent to 1) { $D[y] \leftarrow \text{length}[1, y]$; $p[y] \leftarrow 1$ }
- 4. else $D[y] \leftarrow \infty$;
- 5. for $j \leftarrow 2$ to n
- 6. Let $y \in Y$ be such that $D[y]$ is minimum;
- 7. $X \leftarrow X \cup \{y\}$; // add vertex y to X
- 8. $Y \leftarrow Y - \{y\}$; // delete vertex y from Y
- 9. for each edge (y, w)
- 10. if ($w \in Y$ and ~~$D[y]$~~ $\text{length}[y, w] < D[w]$)
- 11. { ~~$D[y]$~~ $D[w] \leftarrow \text{length}[y, w]$; $p[w] \leftarrow y$; }

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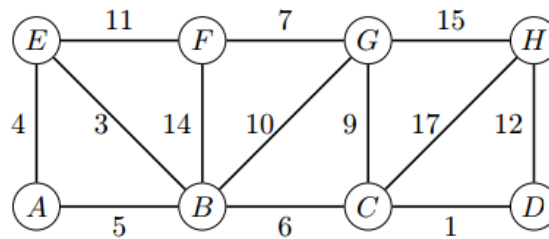
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Possible Quiz Question

Find and draw the minimum spanning tree using **Prim-Jarnik's** Algorithm and list the nodes in the order of entering the cloud.



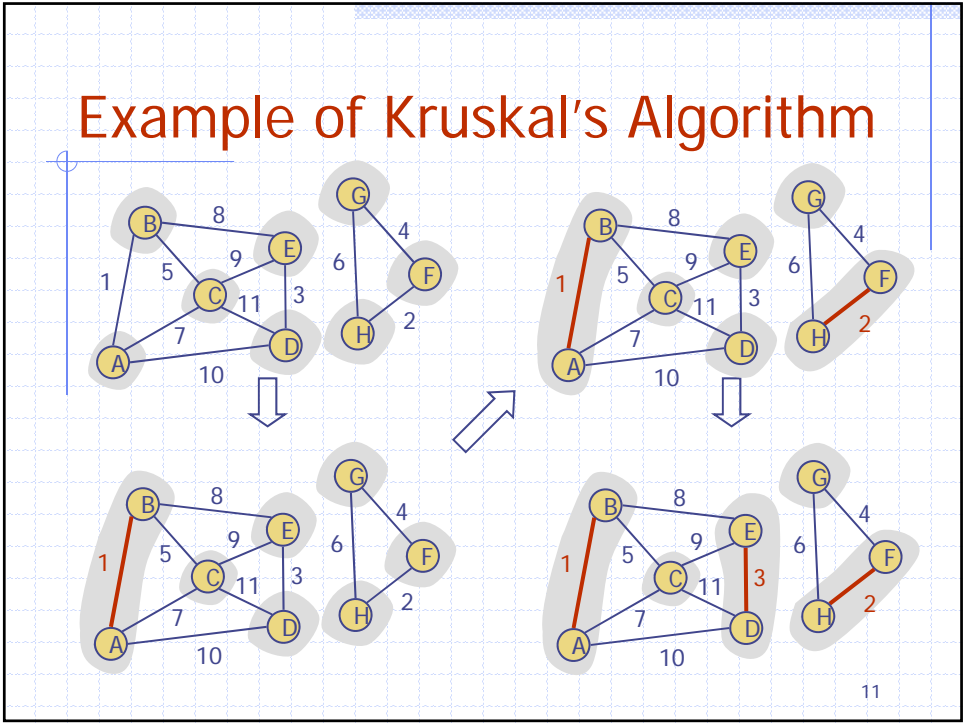
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Kruskal's Approach

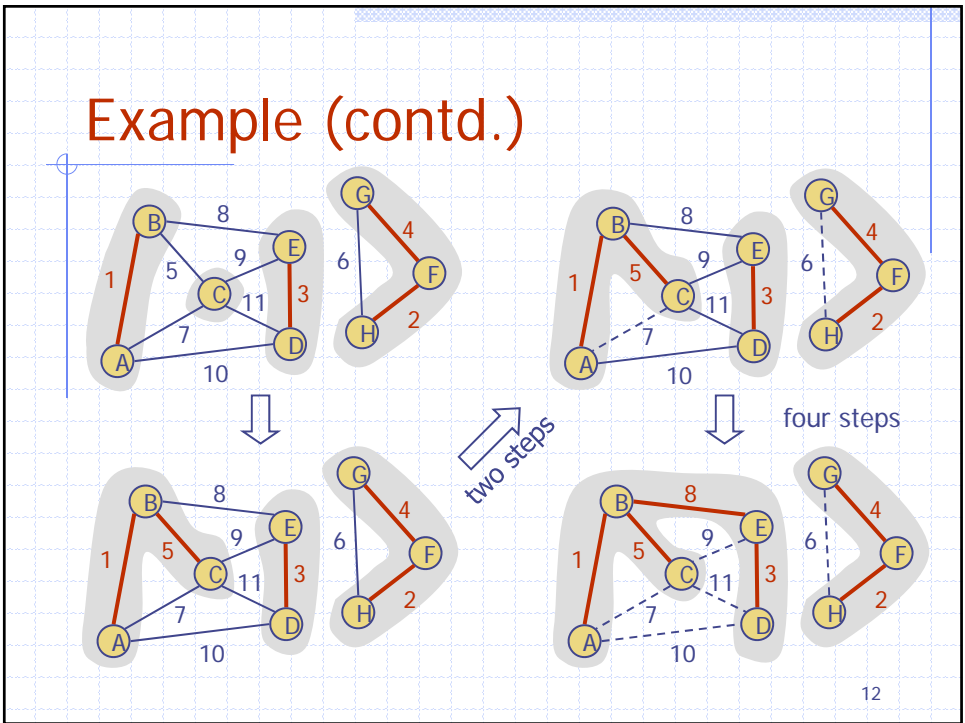
- Maintain a partition of the vertices into clusters
 - Initially, single-vertex clusters
 - Keep an MST for each cluster
 - Merge “closest” clusters and their MSTs
- A priority queue stores the edges outside clusters
 - Key: weight
 - Element: edge
- At the end of the algorithm
 - One cluster and one MST

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Kruskal's Algorithm

Algorithm KruskalMST(G):

Input: A simple connected weighted graph G with n vertices and m edges

Output: A minimum spanning tree T for G

for each vertex v in G **do**

 Define an elementary cluster $C(v) \leftarrow \{v\}$.

Let Q be a priority queue storing the edges in G , using edge weights as keys

$T \leftarrow \emptyset$ // T will ultimately contain the edges of the MST

while T has fewer than $n - 1$ edges **do**

$(u, v) \leftarrow Q.\text{removeMin}()$

 Let $C(v)$ be the cluster containing v

 Let $C(u)$ be the cluster containing u

if $C(v) \neq C(u)$ **then**

 Add edge (v, u) to T

 Merge $C(v)$ and $C(u)$ into one cluster, that is, union $C(v)$ and $C(u)$

return tree T

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Data Structure for Kruskal's Algorithm

- The algorithm maintains a forest of trees
- Sort all edges into non-decreasing order
- An edge is accepted if it connects distinct trees
- We need a data structure that maintains a **partition**, i.e., a collection of disjoint sets, with operations:
 - **find**(u): return the set storing u
 - **union**(A, B): replace sets A and B with their union

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Implementation with Union-Find

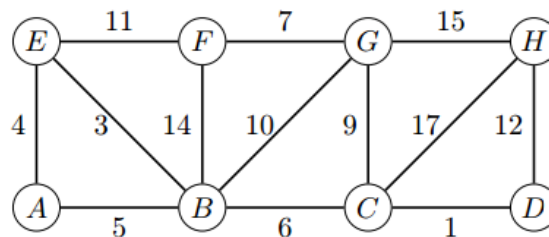
- Kruskal's Algorithm
 - Cluster merges as unions
 - Cluster locations as finds
- Running time $O(m \log n)$
 - Sorting: $O(m \log m) = O(m \log n)$
 - Union-Find operations: (practically) $O(n + m)$

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Possible Quiz Question

Find and draw the minimum spanning tree using **Kruskal's** Algorithm and list the edges in the MST in the order of entering the MST.



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Baruvka's Algorithm

- Like Kruskal's Algorithm, Baruvka's algorithm grows many clusters at once and maintains a forest T
- Each iteration of the while loop halves the number of connected components in forest T
- The running time: $O(m \log n)$

Algorithm *BaruvkaMST(G)*

$T \leftarrow V$ {just the vertices of G }

while T has fewer than $n - 1$ edges **do**

for each connected component C in T **do**

 Let edge e be the smallest-weight edge from C to another component in T

if e is not already in T **then**

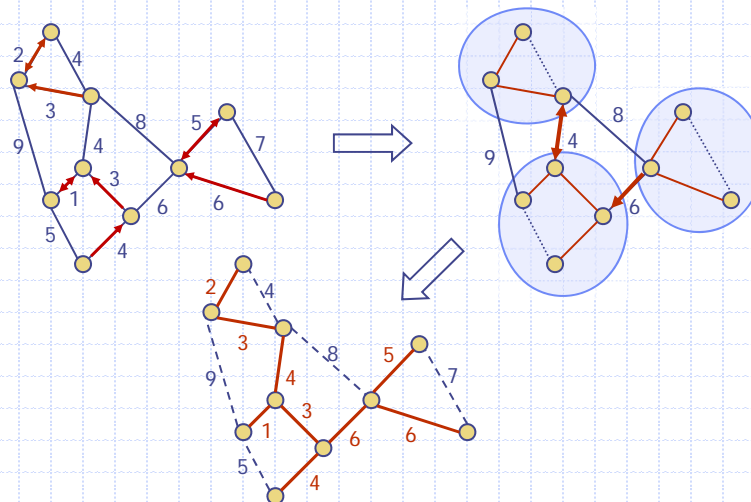
 Add edge e to T

return T

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Example of Baruvka's Algorithm



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Data Structure for Baruvka's Algorithm

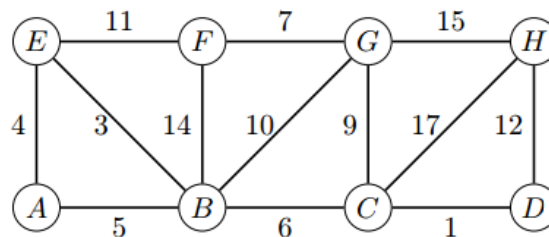
- Maintain the forest T subject to edge insertion, $O(1)$ using linked list for T .
- Each vertex remembers its tree number, which is updated by DFS ($O(n)$ time) after each round.
- For complexity analysis:
 - Minimum weight edges are obtained by going through all the edges in one tree ($O(m)$ time) in each round.
 - Since the number of trees in T is halved after each round, there are at most $O(\log n)$ rounds. So the total complexity is $O((n+m)\log n)$.

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Possible Quiz Question

Find and draw the minimum spanning tree using **Baruvka's** Algorithm and list the edges in the MST in the order of entering the MST.



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