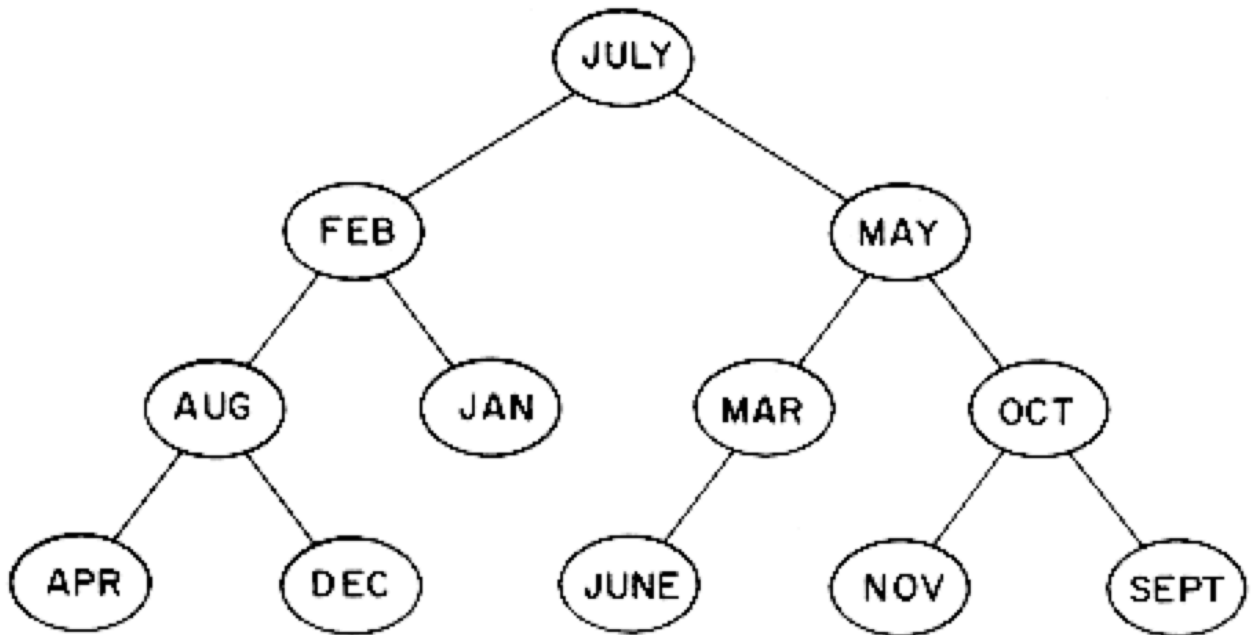


Binary Search Tree and AVL Tree



Is this a binary search tree?

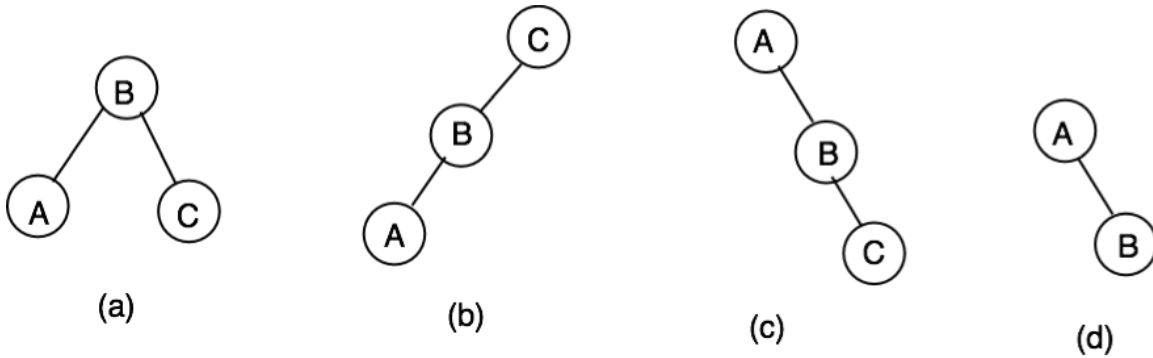
- Is this the only BST with the months of the year?
- Can you draw three binary search trees with the keys 12, 41, 9, 55, 36?

AVL trees

(Inventors G.M. **A**delson-**V**elsky and E.M. **L**andis)

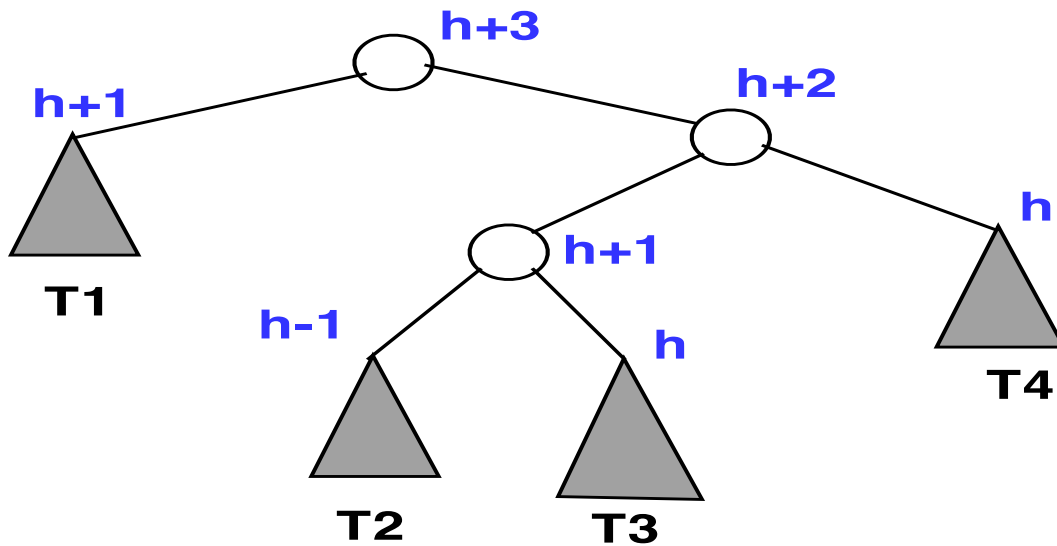
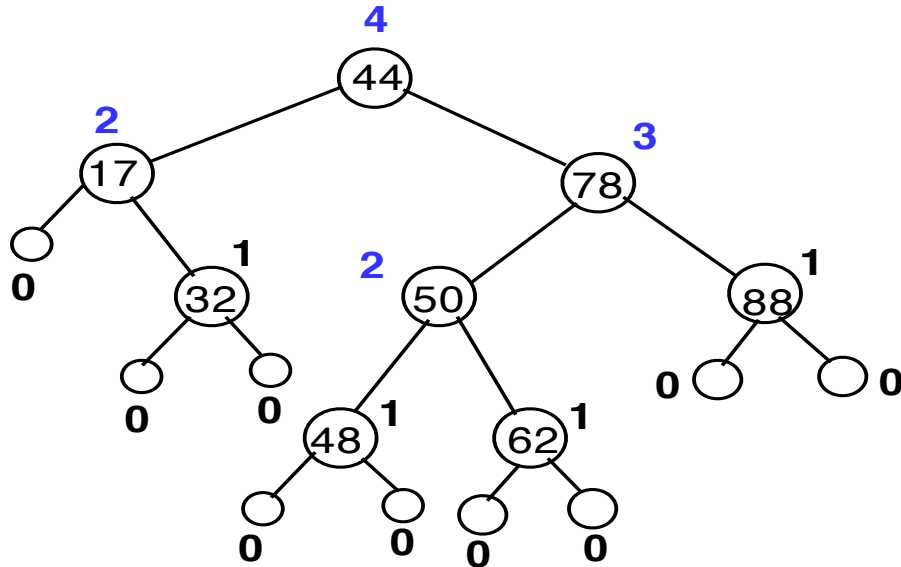
An AVL tree satisfies the **height-balance property**:

*For any tree rooted at an internal node n , the heights of the left and right subtrees **differ by at most 1**.*



(a)(d) satisfy height-balance property, (b) and (c) don't

Examples of AVL Trees



Valid AVL trees - satisfy height-balance property

Height of an AVL tree

Is $h = O(\log n)$ for AVL trees too? **Yes! Why?**

Let $n(h)$ be the smallest number of internal (i.e. non-leaf) nodes of height h in an AVL tree. Then

$$n(1) = 1, n(2) = 2, \text{ and}$$

$$n(h) = n(h-1) + n(h-2) + 1$$

So, $n(h) > 2n(h-2)$, and $n(h) > 2^i n(h-2i)$.

Substitute $i = \frac{h-1}{2}$. This leads to

$$n(h) > 2^{h-1/2} n(h - (h-1)) = 2^{h-1/2}$$

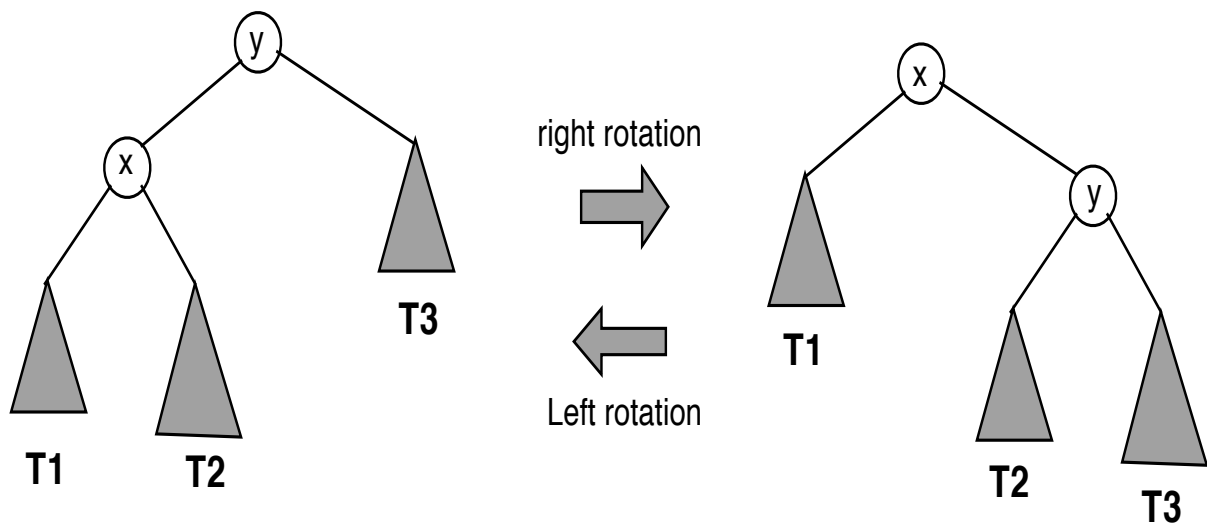
Therefore, $\log n(h) > \frac{h-1}{2}$

So $h < 1 + 2 \log n(h)$, and the number of leaves \leq
1 + number of internal nodes

Insertion algorithms for AVL Trees

1. First insert the key w into the BST. If it maintains the height-balance property then fine. Otherwise we need to rebalance it.

3. Re-balance the tree by performing appropriate **rotations** as shown below to repair the tree.



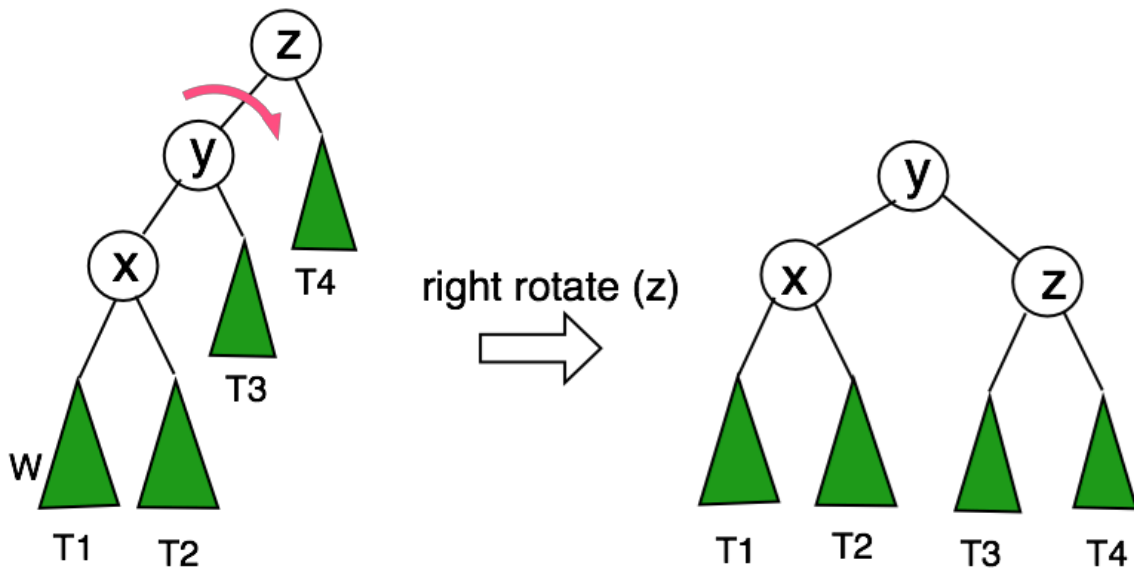
Rotation Operations for rebalancing

Starting from w , travel up and find the first unbalanced node. Let z be the first unbalanced node, y be the child of z that comes on the path from w to z , and x be the grandchild of z that comes on the path from w to z .

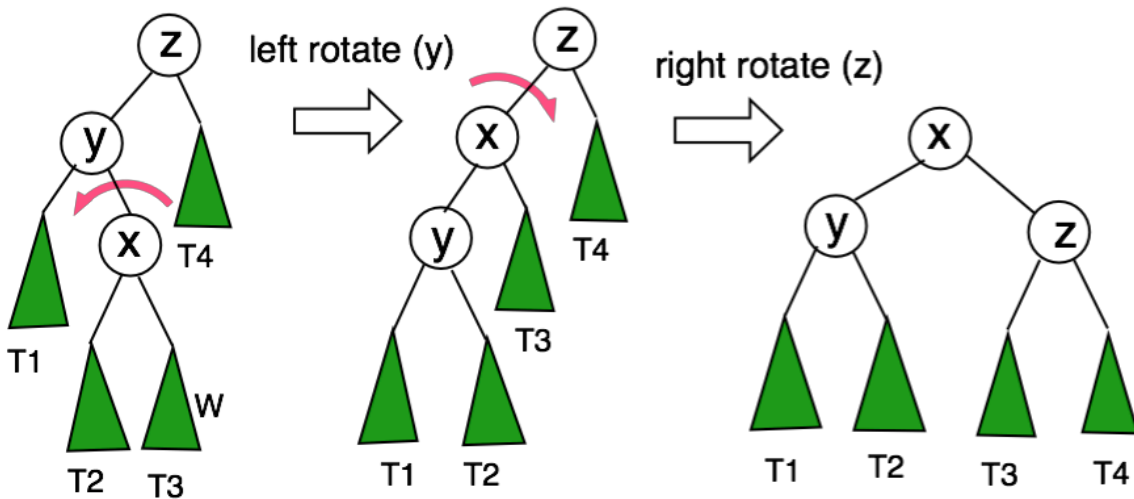
There can be four possible cases that need to be handled as x , y and z can be arranged in 4 ways. Following are the possible 4 arrangements:

Four different cases

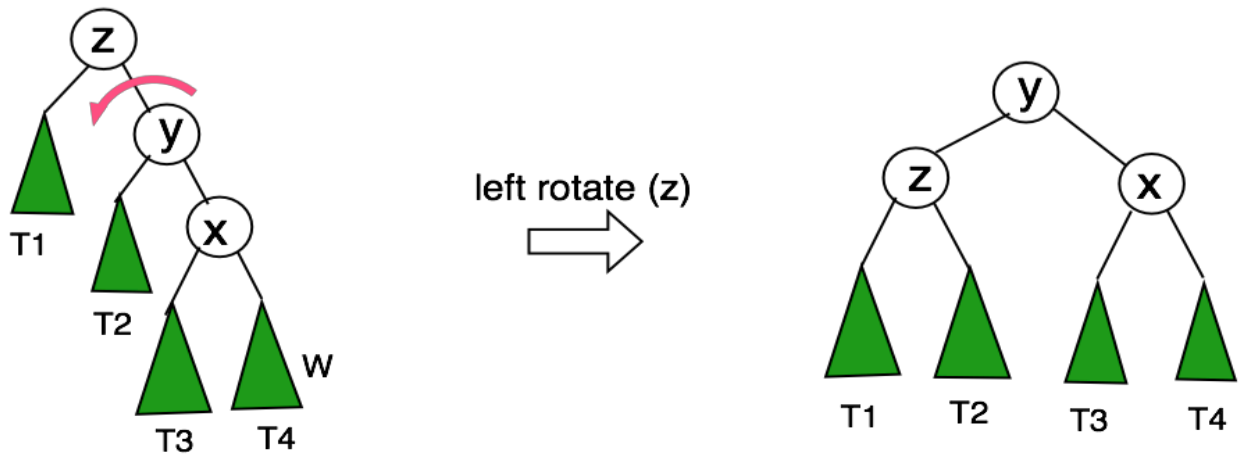
1. $y =$ left child of z , $x =$ left child of y (Right rotation)
2. $y =$ left child of z , $x =$ right child of y (Left Right)
3. $y =$ right child of z , $x =$ right child of y (Left rotation)
4. $y =$ right child of z , $x =$ left child of y (Right Left)



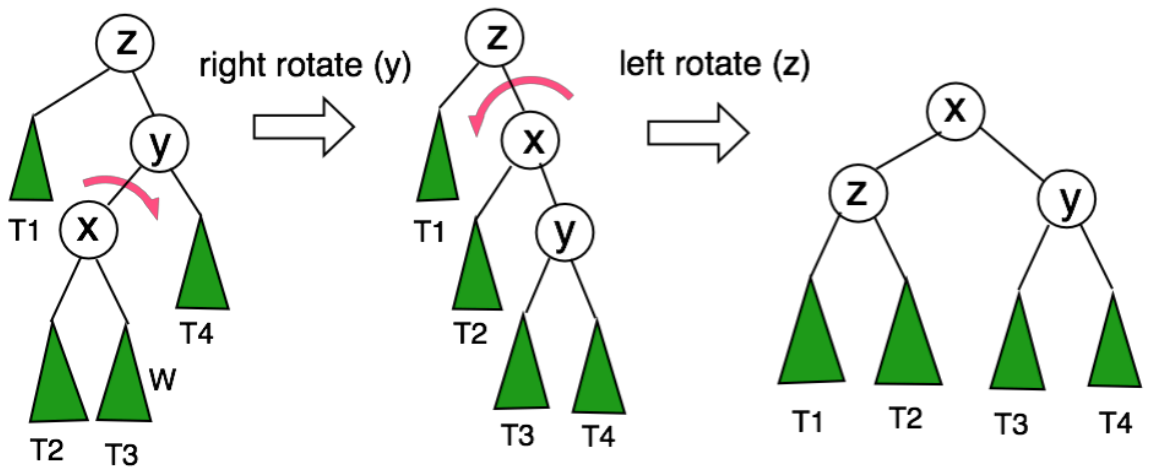
$y = \text{left child of } z, x = \text{left child of } y$ (Right rotation)



$y = \text{left child of } z, x = \text{right child of } y$ (Left Right)

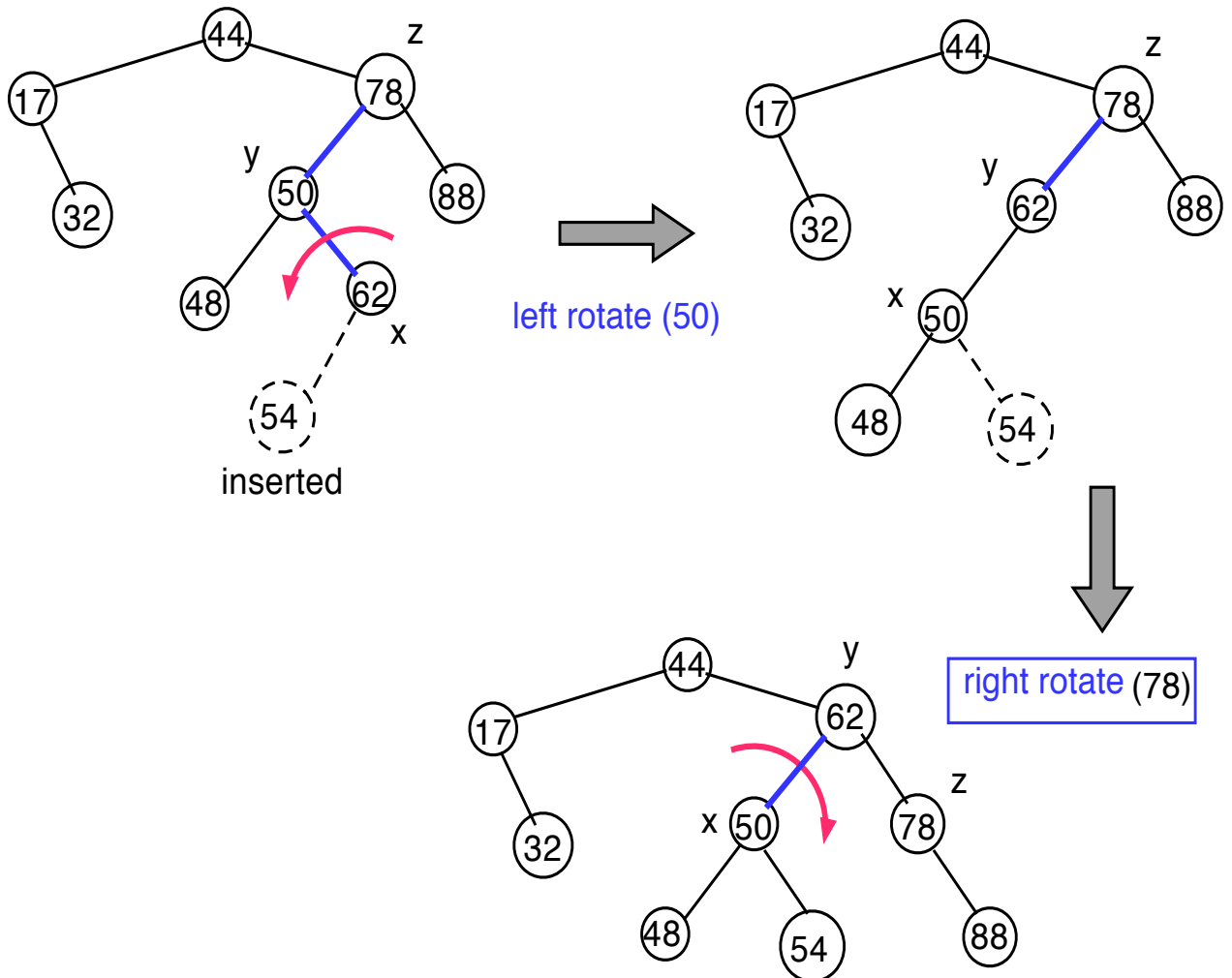


y = right child of z, x = right child of y (Left rotation)



y = right child of z, x = left child of y (Right Left)

Here is an example



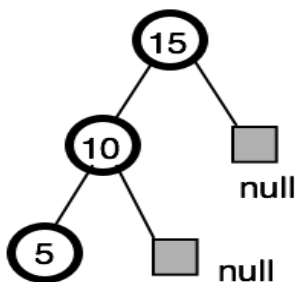
For the **delete operation**, follow the usual delete algorithms for BST and then, if needed, restore the height-balance property.

Red-Black trees

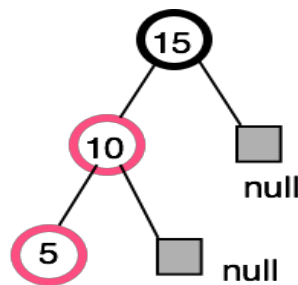
Another approach to keeping a binary search tree balanced. Contains two types of nodes: **red** and **black**. By definition, all ***null entries*** (non-existent children) are **black**. Maintains **three invariants**:

1. The **root** is always black.
2. A **red** node always has **black** children.
3. The number of black nodes in any path from the root to a leaf (a. k. a. **black depth**) is the same.

The following are NOT red-black trees. Why?



Violates property 3



Violates property 2

The following ARE valid red black trees.



1. Why do we need to learn about this?

Because $h \leq 2 \log (n+1)$: It guarantees search, insert, delete in $O(\log n)$ time.

2. But isn't that true for AVL trees too?

Yes, but in AVL trees, there are more *rotations* on an average (up to $O(\log n)$ in the worst case) during insert operations. In contrast Red-Black trees need **at most one** rotation per insertion and **at most two** rotations for deletion, so they work better with frequent insert and delete operations.

3. Search in Red-black trees

For AVL trees, $h \leq 1.44 \log n$

For RB trees, $h \leq 2 \log(n)$

So lookup is faster in AVL trees, particularly for large n , but it comes at the expense of slower insertion and deletion times.

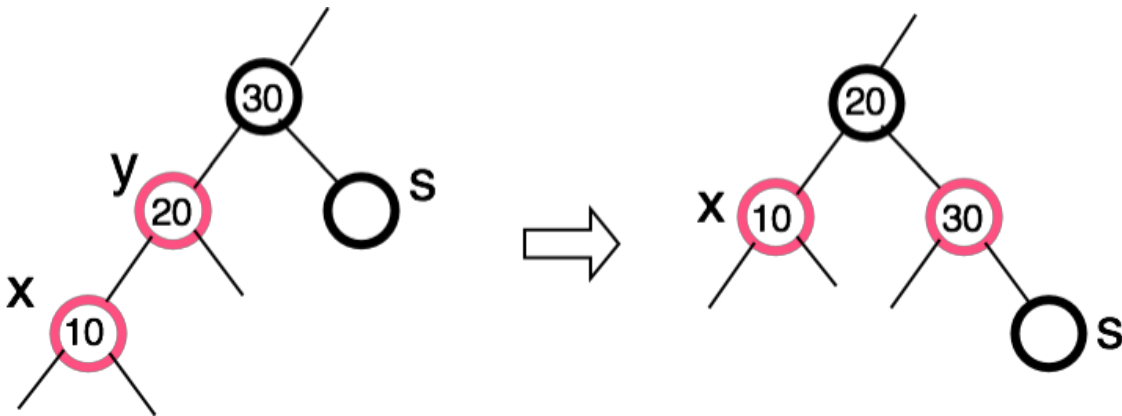
3. The TreeMap class

TreeMap class implements the Map interface using a **Red-Black tree**. The binary tree sorts the keys in the ascending order. The **HashMap** class also implements a Map interface, but is an unordered collection of key-value pairs.

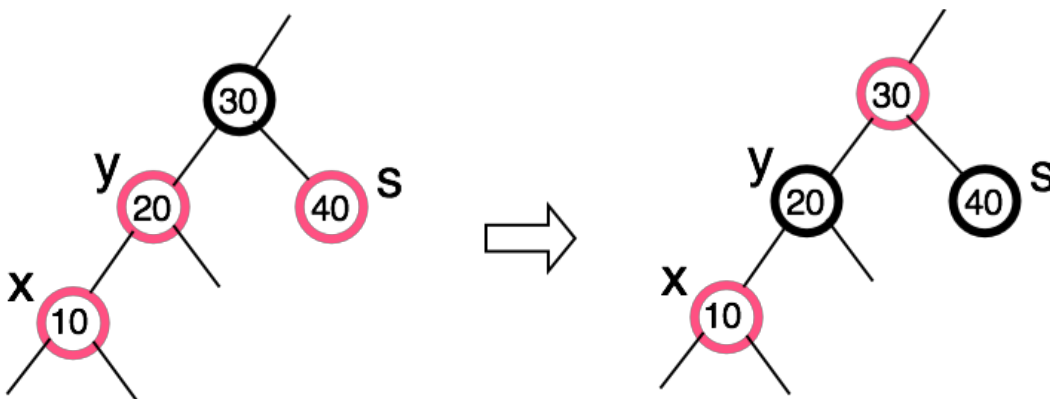
Inserting a node

Follow the normal rules of insertion in a BST. Let x = node to be inserted, and y = parent of x . Make the new node x a **red node**. Two sample cases:

Case 1. The sibling s of y is black



Case 2. The sibling s of y is red



If 30 is the root, then color it black.