A Discrete Galerkin Method for a Hypersingular

Boundary Integral Equation

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Abstract

Consider solving the interior Neumann problem

$$\Delta u(P) = 0, \qquad P \in D$$
 $\partial u(P)$

$$\frac{\partial u(P)}{\partial \mathbf{n}_P} = f(P), \qquad P \in S$$

with D a simply-connected planar region and $S = \partial D$ a smooth curve. A double layer potential is used to represent the solution, and it leads to the problem of solving a hypersingular integral equation. This integral equation is reformulated as a Cauchy singular integral equation. A discrete Galerkin method with trigonometric polynomials is then given for its solution. An error analysis is given; and numerical examples complete the paper.

Keywords: Hypersingular integral operator, Galerkin method.

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1 Introduction

Let D be a bounded open simply-connected region in the plane, and let its boundary S be sufficiently smooth. Consider the Neumann problem: Find $u \in C^1(\overline{D}) \cap C^2(D)$ that satisfies

$$\Delta u(P) = 0,$$
 $P \in D$
$$\frac{\partial u(P)}{\partial \mathbf{n}_{P}} = f(P), \qquad P \in S$$
 (1.1)

with $f \in C(S)$ a given boundary function.

One way of solving this problem is to express the solution u as a double layer potential,

$$u(A) = \int_{S} \rho(Q) \frac{\partial}{\partial \mathbf{n}_{Q}} \log |A - Q| dS_{Q}, \qquad A \in D$$
 (1.2)

The function ρ is called a double layer density function or a dipole density function. Form the derivative of u(A) in the direction \mathbf{n}_P , the inner normal to the boundary S at P, and take the limit as $A \to P$, thus obtaining the normal derivative. For the Neumann problem, this leads to

$$f(P) = \frac{\partial u(P)}{\partial \mathbf{n}_P} \tag{1.3}$$

$$= \lim_{A \to P} \mathbf{n}_P \cdot \nabla_A \int_S \rho(Q) \frac{\partial}{\partial \mathbf{n}_Q} \log |A - Q| dS_Q, \qquad P \in S$$
 (1.4)

The integral operator is often referred to as hypersingular, and we are looking for the density function ρ . For some discussion of this for S = U the unit circle, see Atkinson [5, §7.3.2].

Section 2 gives preliminary information on integral equations for S = U the unit circle; and Section 3 relates the hypersingular integral operator to other potential representations. Section 4 gives a reformulation of the integral equation. Section 5 gives the numerical method and Section 6 gives numerical examples. The numerical method is based on using 2 PRELIMINARIES 3

trigonometric approximations of the unknown density function, and we give what can be regarded as either a discrete Galerkin method or a discrete collocation method.

The general idea of using an approximation scheme using trigonometric approximations is quite old. An early use of this is given in Gabdulhaev [7]. Work from more recent years is given by Amosov [3], Atkinson [4], Atkinson and Sloan [6], Mclean [12], and McLean, Prößdorf, and Wendland [13]. Other approaches to the solution of the hypersingular equation are given in Amini and Maines [1], [2], Giroire and Nedelec [8], Kress [11], and Rathsfeld, Kieser, and Kleemann [15].

2 Preliminaries

In this paper, we consider the Neumann problem given in equation (1.1). Let D be a bounded open simply-connected region in the plane, and assume its boundary S is sufficiently smooth. Thus, S has a parameterization

$$\beta(s) = (\xi(s), \eta(s)), \qquad 0 \le s \le L \tag{2.1}$$

where s is the arc length coordinate of the point P on S and L is the arc length of S. Assume $\beta(s) \in C^2[0, L]$ and $|\beta'(s)| \neq 0$ for every $s \in [0, L]$. The normal vector **n** at P on S is directed into the interior of the domain D; and we assume the direction of integration on S to be counterclockwise.

Consider the normal derivative of u(A) in the inner direction to S at P:

$$\frac{\partial u(P)}{\partial \mathbf{n}_{P}} = \lim_{A \to P} \mathbf{n}_{P} \cdot \nabla_{A} \int_{S} \rho(Q) \frac{\partial}{\partial \mathbf{n}_{Q}} \log |A - Q| dS_{Q}$$
 (2.2)

$$\equiv \frac{\partial}{\partial \mathbf{n}_P} \int_S \rho(Q) \frac{\partial}{\partial \mathbf{n}_Q} \log |P - Q| dS_Q$$
 (2.3)

$$\equiv \mathcal{H}\rho(P), \qquad P \in S \tag{2.4}$$

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The resulting integral contains an integrand with a strongly nonintegrable singularity if the integral and derivative operators are interchanged. Such integral operators \mathcal{H} are often referred to as hypersingular, and the integrals do not exist in the usual sense.

The hypersingular integral operator is very closely related to the Cauchy singular integral operator:

$$C\rho(z) = \frac{1}{2\pi i} \int_{S} \frac{\rho(\zeta)}{\zeta - z} d\zeta, \qquad z \in S$$

where S is the boundary of D, as defined before. Properties of Cauchy singular integral operators can be found in Kress [10, p. 82].

For a function $\varphi \in L^2(0, 2\pi)$, we write its Fourier expansion as

$$\varphi(s) = \sum_{m=-\infty}^{\infty} a_m \psi_m(s), \qquad \psi_m(s) = \frac{1}{\sqrt{2\pi}} e^{ims}$$
$$a_m = \int_0^{2\pi} \varphi(s) \overline{\psi_m(s)} ds$$

For any real number $q \geq 0$, define $H^q(2\pi)$ to be the set of all functions $\varphi \in L^2(0, 2\pi)$ for which

$$\|\varphi\|_q \equiv \left[|a_0|^2 + \sum_{\substack{m=-\infty\\m\neq 0}}^{\infty} |m|^{2q} |a_m|^2 \right]^{\frac{1}{2}} < \infty$$

Consider the case in which S=U, the unit circle. We denote the Cauchy singular integral operator by C_u in this case; and from Henrici [9, p. 109],

$$C_u: e^{ikt} \longrightarrow \operatorname{sign}(k) \cdot \frac{e^{ikt}}{2}, \qquad k = 0, \pm 1, \pm 2, \dots$$
 (2.5)

with sign(0) = 1. We can interpret C_u as a operator on $H^q(2\pi)$, and

$$C_u: H^q(2\pi) \xrightarrow{1-1} H^q(2\pi), \qquad q \ge 0$$

Consider the same boundary for the hypersingular integral operator, and denote the latter by \mathcal{H}_u in this case. From Atkinson [5, Sec. 7.3], we have

$$\mathcal{H}_u: e^{ikt} \longrightarrow \pi |k| e^{ikt}, \qquad k = 0, \pm 1, \pm 2, \dots$$
 (2.6)

For $\varphi \in H^1(2\pi)$ with $\varphi = \sum a_m \psi_m$, introduce the derivative operator \mathcal{D} :

$$\mathcal{D}\varphi(t) \equiv \frac{d\varphi(t)}{dt} = i \sum_{m \neq 0} m a_m \psi_m(t)$$

Regarding the Cauchy singular integral operator C_u as an operator on $H^q(2\pi)$, and using the mapping properties (2.5) and (2.6), we have

$$\mathcal{H}_u \varphi = -2\pi i \mathcal{D} C_u \varphi = -2\pi i C_u \mathcal{D} \varphi$$

3 Connection With Logarithmic Potential

Consider $\varphi(t)$ as a real function, and assume z does not lie on the boundary S. Introduce

$$\Phi(z) = U(x, y) + iV(x, y) = \frac{1}{2\pi i} \int_{S} \frac{\varphi(\zeta) d\zeta}{\zeta - z}$$
(3.1)

Substitute

$$\zeta - z = re^{i\vartheta} \tag{3.2}$$

where $r = |\zeta - z|$ and $\vartheta = \arg(\zeta - z)$. Taking the logarithmic derivative of (3.2) (for variable ζ and constant z),

$$\frac{d\zeta}{\zeta - z} = d\log r + id\vartheta = \left(\frac{\partial\log r}{\partial s} + i\frac{\partial\vartheta}{\partial s}\right)ds.$$

By the Cauchy-Riemann equations, applied to $\log(\zeta - z) = \log r + i\vartheta$, we have

$$\frac{\partial \vartheta}{\partial s} = -\frac{\partial \log r}{\partial \mathbf{n}}.$$

Substituting this into (3.1) and separating real and imaginary parts, we obtain

$$U(x, y) = \frac{1}{2\pi} \int_{S} \varphi \, d\vartheta = \frac{1}{2\pi} \int_{0}^{L} \varphi \frac{d\vartheta}{ds} ds = \frac{-1}{2\pi} \int_{0}^{L} \varphi \frac{\partial}{\partial \mathbf{n}_{\zeta}} \log r \, ds$$

and

$$V(x, y) = \frac{-1}{2\pi} \int_{S} \varphi \, d\log r \tag{3.3}$$

After an integration by parts (assuming that φ has an integrable derivative with respect to s) equation (3.3) can be written as

$$V(x, y) = \frac{1}{2\pi} \int_0^L \frac{d\varphi}{ds} \log r \, ds.$$

These formulae indicate that for real valued densities, the real part of the Cauchy integral coincides with the double layer potential (1.2)

$$u(x, y) = \int_0^L \rho(\beta(s)) \frac{\partial}{\partial \mathbf{n}_{\zeta}} \log r \, ds \qquad (x, y) \in D$$
 (3.4)

where

$$\rho(\beta(s)) = -\frac{1}{2\pi}\varphi(s).$$

From Kress [10, p. 100], we have the following theorem:

Theorem 1 The double layer potential u with Hölder continuous density ρ can be extended uniformly Hölder continuously from D into \overline{D} .

Proof: The definition of $C^{0,\alpha}(S)$, the set of all functions which are Hölder continuous, can be found from Kress [10, p. 82].

The next theorem gives us the existence and representation of the normal derivative of the double layer potential u on the boundary S.

Theorem 2 The normal derivative of the double layer potential u with density $\rho \in C^{1,\alpha}(S)$ can be extended uniformly Hölder continuously from D to \overline{D} . The normal derivative is given by

$$\frac{\partial u(P)}{\partial \mathbf{n}_{P}} = \frac{d}{ds_{0}} \int_{0}^{L} \frac{d\rho}{ds} \log |\beta(s) - \beta(s_{0})| ds \qquad \beta(s_{0}) = P \in S$$
 (3.5)

Proof: $C^{1,\alpha}(S)$ is the set of all continuously differentiable functions φ such that $\varphi' \in C^{0,\alpha}(S)$; and recall $\beta(s)$ from (2.1), a parameterization of S. See the proof in Kress [10, p. 102]

Notice that the right-hand side of the equation (3.5) is the tangential derivative of the simple layer potential V; and from Muskhelishvili [14, p. 31], we have

$$\frac{\partial u(P)}{\partial \mathbf{n}_{P}} = \frac{dV}{ds_{0}} = \int_{0}^{L} \frac{d\rho}{ds} \frac{\partial}{\partial s_{0}} \log |\beta(s) - \beta(s_{0})| ds$$

$$= -\int_{0}^{L} \frac{d\rho}{ds} \frac{\beta'(s_{0}) \cdot (\beta(s) - \beta(s_{0}))}{|\beta(s) - \beta(s_{0})|^{2}} ds$$
(3.6)

For the Neumann problem (1.1), the double layer potential

$$u(A) = \int_{S} \rho(Q) \frac{\partial}{\partial \mathbf{n}_{Q}} \log |A - Q| dS_{Q}, \qquad A \in D$$
 (3.7)

solves the Neumann problem with boundary condition $\partial u/\partial n = f$ on S provided the density $\rho \in C^{1,\alpha}(S)$ solves the integral equation

$$\frac{\partial}{\partial \mathbf{n}_{P}} \int_{0}^{L} \rho(\beta(s)) \frac{\partial}{\partial \mathbf{n}_{\beta(s)}} \log |P - \beta(s)| ds = f(P), \qquad P \in S$$
 (3.8)

Theorem 3 Let $f \in C^{0,\alpha}(S)$ satisfy the solvability condition

$$\int_0^L f \, ds = 0.$$

The Neumann problem (1.1) has a solution u of the form (3.7), with $\rho \in C^{1,\alpha}(S)$. Two solutions u can differ only by a constant, as do two solutions ρ .

This establishes the solvability of the integral equation (3.8), and symbolically we write this equation as

$$\mathcal{H}\rho = f.$$

4 Reformulation

With equation (3.6), we have

$$\mathcal{H}\rho(\beta(s_0)) = -\int_0^L \frac{d\rho}{ds} \frac{\beta'(s_0) \cdot (\beta(s) - \beta(s_0))}{|\beta(s) - \beta(s_0)|^2} ds \tag{4.1}$$

Change from the variable s to θ , with

$$s = \frac{L\theta}{2\pi}, \qquad 0 \le \theta \le 2\pi,$$

and do similarly with s_0 and θ_0 . Then equation (4.1) becomes

$$\mathcal{H}\rho(\beta(s_0)) = -\frac{L}{2\pi} \int_0^{2\pi} \frac{\beta'(\frac{L\theta_0}{2\pi}) \cdot \left(\beta(\frac{L\theta}{2\pi}) - \beta(\frac{L\theta_0}{2\pi})\right)}{\left|\beta(\frac{L\theta}{2\pi}) - \beta(\frac{L\theta_0}{2\pi})\right|^2} \frac{d\rho}{ds} d\theta \tag{4.2}$$

Introduce a function η defined on $[0, 2\pi]$, and implicitly on the unit circle U, by

$$\eta(\theta) = \rho\left(\beta\left(\frac{L\theta}{2\pi}\right)\right), \qquad \eta_s(\theta) = \frac{d}{ds}\rho\left(\beta\left(\frac{L\theta}{2\pi}\right)\right), \qquad 0 \le \theta \le 2\pi$$

The parameterization of the unit circle is

$$\beta_u(\theta) = (\cos(\theta), \sin(\theta)), \qquad 0 \le \theta \le 2\pi$$

Using these definitions, write (4.2) as

$$\mathcal{H}\eta(\theta_0) = -\frac{L}{2\pi} \int_0^{2\pi} \frac{\beta'(\frac{L\theta_0}{2\pi}) \cdot \left(\beta(\frac{L\theta}{2\pi}) - \beta(\frac{L\theta_0}{2\pi})\right)}{\left|\beta(\frac{L\theta}{2\pi}) - \beta(\frac{L\theta_0}{2\pi})\right|^2} \eta_s(\theta) d\theta$$

$$= -\int_{0}^{2\pi} \frac{\beta'_{u}(\theta_{0}) \cdot (\beta_{u}(\theta) - \beta_{u}(\theta_{0}))}{|\beta_{u}(\theta) - \beta_{u}(\theta_{0})|^{2}} \cdot \left[\frac{|\beta_{u}(\theta) - \beta_{u}(\theta_{0})|^{2}}{|\beta'_{u}(\theta_{0}) \cdot (\beta_{u}(\theta) - \beta_{u}(\theta_{0}))} \frac{\beta'(\frac{L\theta_{0}}{2\pi}) \cdot (\beta(\frac{L\theta}{2\pi}) - \beta(\frac{L\theta_{0}}{2\pi}))}{|\beta(\frac{L\theta}{2\pi}) - \beta(\frac{L\theta_{0}}{2\pi})|^{2}} \right] \eta'(\theta) d\theta$$

$$= -\int_{0}^{2\pi} \frac{\sin(\theta - \theta_{0})}{2(1 - \cos(\theta - \theta_{0}))} \cdot \left[\frac{2(1 - \cos(\theta - \theta_{0}))}{\sin(\theta - \theta_{0})} \cdot \frac{\beta'(\frac{L\theta_{0}}{2\pi}) \cdot (\beta(\frac{L\theta}{2\pi}) - \beta(\frac{L\theta_{0}}{2\pi}))}{|\beta(\frac{L\theta}{2\pi}) - \beta(\frac{L\theta_{0}}{2\pi})|^{2}} \right] \eta'(\theta) d\theta$$

$$= -\frac{2\pi}{L} \left(\int_{0}^{2\pi} \frac{\sin(\theta - \theta_{0})}{2(1 - \cos(\theta - \theta_{0}))} \eta'(\theta) d\theta + \mathcal{B}\mathcal{D}\eta(\theta_{0}) \right)$$

$$= \frac{2\pi}{L} \left(\mathcal{H}_{u}\eta(\theta_{0}) + \mathcal{B}\mathcal{D}\eta(\theta_{0}) \right)$$

$$= \frac{2\pi}{L} \left(-2\pi i C_{u} \mathcal{D}\eta(\theta_{0}) + \mathcal{B}\mathcal{D}\eta(\theta_{0}) \right)$$

$$(4.3)$$

where the kernel B of the integral operator \mathcal{B} is

$$B(\theta_0, \theta) = -\left(\frac{L}{2\pi}\right) \left[\frac{\beta'(\frac{L\theta_0}{2\pi}) \cdot \left(\beta(\frac{L\theta_0}{2\pi}) - \beta(\frac{L\theta_0}{2\pi})\right)}{\left|\beta(\frac{L\theta}{2\pi}) - \beta(\frac{L\theta_0}{2\pi})\right|^2} - \frac{\pi}{L} \frac{\sin(\theta - \theta_0)}{(1 - \cos(\theta - \theta_0))} \right]$$
(4.4)

The kernel $B(\theta_0, \theta)$ is continuous, and it has periodicity 2π for both θ and θ_0 . It's easy to see B is a periodic function, and we need to show it is continuous when either $\sin(\theta - \theta_0) \to 0$ or $\beta(\frac{L\theta}{2\pi}) - \beta(\frac{L\theta_0}{2\pi}) \to 0$.

Theorem 4 Assume $\beta(s) \in C^2[0, L]$, then the kernel function $B(\theta_0, \theta)$ is continuous over $[0, 2\pi] \times [0, 2\pi]$, and it is periodic with respect to both θ and θ_0 , with period 2π .

Proof: It suffices to show three cases:

Case 1: $\theta_0 \in (0, 2\pi)$ and $\theta \to \theta_0$.

Note that we drop the coefficient $-L/2\pi$ in (4.4) for convenience and rewrite it as

$$B(\theta_0, \theta) = \frac{\beta'(\frac{L\theta_0}{2\pi}) \cdot \left(\beta(\frac{L\theta}{2\pi}) - \beta(\frac{L\theta_0}{2\pi})\right)}{\left|\beta(\frac{L\theta}{2\pi}) - \beta(\frac{L\theta_0}{2\pi})\right|^2} - \left(\frac{\pi}{L}\right) \frac{\sin(\theta - \theta_0)}{1 - \cos(\theta - \theta_0)}$$
(4.5)

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$$= \frac{\beta'(\frac{L\theta_0}{2\pi}) \cdot \left(\beta(\frac{L\theta}{2\pi}) - \beta(\frac{L\theta_0}{2\pi})\right)}{\left|\beta(\frac{L\theta}{2\pi}) - \beta(\frac{L\theta_0}{2\pi})\right|^2} - \frac{2\pi}{L(\theta - \theta_0)}$$
(4.6)

$$-\frac{\pi}{L} \left(\frac{\sin(\theta - \theta_0)}{1 - \cos(\theta - \theta_0)} - \frac{2}{\theta - \theta_0} \right) \tag{4.7}$$

In this proof, we take the advantage of the parameterization β of the boundary S. Since s is the arc coordinate of the point P on S, we have

$$|\beta'(s_0)| = 1$$
 and $\beta'(s_0) \cdot \beta''(s_0) = 0$ $\forall \beta(s_0) \in S$

The term (4.7) approaches 0 as θ approaches θ_0 . For the term (4.6), we first expand β about θ_0 :

$$\beta\left(\frac{L\theta}{2\pi}\right) = \beta\left(\frac{L\theta_0}{2\pi}\right) + \frac{L}{2\pi}\beta'\left(\frac{L\theta_0}{2\pi}\right)(\theta - \theta_0) + \left(\frac{L}{2\pi}\right)^2\beta''\left(\frac{L\theta_1}{2\pi}\right)\frac{(\theta - \theta_0)^2}{2}$$

where θ_1 is between θ and θ_0 . Then

$$\beta'\left(\frac{L\theta_0}{2\pi}\right) \cdot \left(\beta\left(\frac{L\theta}{2\pi}\right) - \beta\left(\frac{L\theta_0}{2\pi}\right)\right) = \frac{L}{2\pi}(\theta - \theta_0) + \left(\frac{L}{2\pi}\right)^2 \beta'\left(\frac{L\theta_0}{2\pi}\right) \cdot \beta''\left(\frac{L\theta_1}{2\pi}\right) \frac{(\theta - \theta_0)^2}{2} \tag{4.8}$$

and

$$\left| \beta(\frac{L\theta}{2\pi}) - \beta(\frac{L\theta_0}{2\pi}) \right|^2$$

$$= \left(\frac{L}{2\pi} \right)^2 (\theta - \theta_0)^2 + \left(\frac{L}{2\pi} \right)^3 \beta' \left(\frac{L\theta_0}{2\pi} \right) \cdot \beta'' \left(\frac{L\theta_1}{2\pi} \right) (\theta - \theta_0)^3 + c_1(\theta - \theta_0)^4$$
(4.9)

where

$$c_1 = \frac{1}{4} \left(\frac{L}{2\pi} \right)^4 \left| \beta'' \left(\frac{L\theta_1}{2\pi} \right) \right|^2$$

Substituting (4.8) and (4.9) to (4.6) we have

$$\frac{\beta'(\frac{L\theta_0}{2\pi}) \cdot \left(\beta(\frac{L\theta}{2\pi}) - \beta(\frac{L\theta_0}{2\pi})\right)}{\left|\beta(\frac{L\theta}{2\pi}) - \beta(\frac{L\theta_0}{2\pi})\right|^2} - \frac{2\pi}{L(\theta - \theta_0)}$$

$$= \frac{\frac{L}{2\pi}(\theta - \theta_0) \left(1 + \left(\frac{L}{2\pi}\right) \beta' \left(\frac{L\theta_0}{2\pi}\right) \cdot \beta'' \left(\frac{L\theta_1}{2\pi}\right) \frac{(\theta - \theta_0)}{2}\right)}{\left(\frac{L}{2\pi}\right)^2 (\theta - \theta_0)^2 \left(1 + \left(\frac{L}{2\pi}\right) \beta' \left(\frac{L\theta_0}{2\pi}\right) \cdot \beta'' \left(\frac{L\theta_1}{2\pi}\right) (\theta - \theta_0) + c_2(\theta - \theta_0)^2\right)}$$

$$- \frac{2\pi}{L(\theta - \theta_0)}$$

$$= \frac{2\pi}{L(\theta - \theta_0)} \left(\frac{1 + \left(\frac{L}{2\pi}\right) \beta' \left(\frac{L\theta_0}{2\pi}\right) \cdot \beta'' \left(\frac{L\theta_1}{2\pi}\right) \frac{(\theta - \theta_0)}{2}}{1 + \left(\frac{L}{2\pi}\right) \beta' \left(\frac{L\theta_0}{2\pi}\right) \cdot \beta'' \left(\frac{L\theta_1}{2\pi}\right) (\theta - \theta_0) + c_2(\theta - \theta_0)^2} - 1\right)$$

$$= \frac{2\pi}{L} \left(\frac{-\left(\frac{L}{2\pi}\right) \beta' \left(\frac{L\theta_0}{2\pi}\right) \cdot \beta'' \left(\frac{L\theta_1}{2\pi}\right) \frac{1}{2} - c_2(\theta - \theta_0)}{1 + \left(\frac{L}{2\pi}\right) \beta' \left(\frac{L\theta_0}{2\pi}\right) \cdot \beta'' \left(\frac{L\theta_1}{2\pi}\right) (\theta - \theta_0) + c_2(\theta - \theta_0)^2}\right)$$

$$(4.10)$$

Let $\theta \to \theta_0$, (4.10) becomes

$$\lim_{\theta \to \theta_0} \frac{2\pi}{L} \left(\frac{-\left(\frac{L}{2\pi}\right) \beta'\left(\frac{L\theta_0}{2\pi}\right) \cdot \beta''\left(\frac{L\theta_1}{2\pi}\right) \frac{1}{2} - c_2(\theta - \theta_0)}{1 + \left(\frac{L}{2\pi}\right) \beta'\left(\frac{L\theta_0}{2\pi}\right) \cdot \beta''\left(\frac{L\theta_1}{2\pi}\right) (\theta - \theta_0) + c_2(\theta - \theta_0)^2} \right) = 0$$

since

$$\lim_{\theta \to \theta_0} \beta' \left(\frac{L\theta_0}{2\pi} \right) \cdot \beta'' \left(\frac{L\theta_1}{2\pi} \right) = \beta' \left(\frac{L\theta_0}{2\pi} \right) \cdot \beta'' \left(\frac{L\theta_0}{2\pi} \right) = 0$$

Thus, $B(\theta_0, \theta)$ is continuous over $(0, 2\pi) \times (0, 2\pi)$, and B = 0 for $\theta_0 = \theta \in (0, 2\pi)$.

Case 2: $\theta_0 = 0$, $\theta > 0$, and $\theta \to \theta_0$.

The proof of this case is the same as for case 1.

Case 3: $\theta_0 = 0$, $\theta < 2\pi$, and $\theta \to 2\pi$.

Since B has period 2π , $B(0, \theta) = B(2\pi, \theta)$. Therefore, let $\theta_0 = 2\pi$ and the proof follows as for the case 1.

This completes the proof that B is continuous over $[0, 2\pi] \times [0, 2\pi]$; and B = 0 for $\theta_0 = \theta \in [0, 2\pi]$.

Corollary 5 Assume $\beta(s) \in C^n[0, L]$, then the kernel function $B(\theta_0, \theta)$ is n-2 times continuously differentiable over $[0, 2\pi] \times [0, 2\pi]$.

Proof: B is expressed in terms of (4.6) and (4.7). (4.7) can be checked easily that it is a very smooth function. For (4.6), we examine (4.10) carefully, we can see that the denominator of

(4.10) never equal to zero when θ and θ_0 are close to each other. Therefore, (4.6) is n-2 times continuously differentiable if $\beta(s)$ is n times continuously differentiable.

5 The Numerical scheme

We begin by defining a Galerkin method for solving the hypersingular integral equation (3.8) in the space $L^2(0, 2\pi)$. However, instead of solving equation (3.8), we solve the equation (4.3):

$$-2\pi i C_u \mathcal{D}\eta(\theta_0) + \mathcal{B}\mathcal{D}\eta(\theta_0) = g(\theta_0)$$
(5.1)

where

$$g(\theta_0) \equiv \frac{L}{2\pi} f(\beta(\frac{L\theta_0}{2\pi})).$$

Let

$$\phi(\theta) \equiv \mathcal{D}\eta(\theta). \tag{5.2}$$

We solve (5.1) for $\phi \in L^2(0, 2\pi)$:

$$-2\pi i C_u \phi + \mathcal{B}\phi = g \tag{5.3}$$

From Theorem 3, this is uniquely solvable on $L^2(0, 2\pi)$. By making the unknown a derivative, we are decreasing the order of the pseudo-differential operator. Also, the first term of (5.3) is a Cauchy singular integral operator on the unit circle, and therefor, we can compute it easily.

The equation (5.3) is equivalent to

$$\phi - \frac{1}{2\pi i} C_u^{-1} \mathcal{B} \phi = -\frac{1}{2\pi i} C_u^{-1} g \tag{5.4}$$

The right side function $C_u^{-1}g$ is in $L^2(0, 2\pi)$. Because \mathcal{B} has a continuous differentiable kernel B, \mathcal{B} is a bounded compact operator from $H^q(2\pi)$ into $H^{q+1}(2\pi)$, and $C_u^{-1}\mathcal{B}$ is a

compact mapping from $L^2(0, 2\pi)$ into $L^2(0, 2\pi)$. Thus, (5.4) is a Fredholm integral equation of the second kind. By the earlier assumption on the unique solvability of (5.3), we have $\left(I - \frac{1}{2\pi i}C_u^{-1}\mathcal{B}\right)^{-1}$ exists on $L^2(0, 2\pi)$ to $L^2(0, 2\pi)$.

Introduce

$$\mathcal{X}_n = \operatorname{span} \left\{ \psi_{-n}, \dots, \psi_0, \dots, \psi_n \right\}$$

for a given $n \geq 0$, and let \mathcal{P}_n denote the orthogonal projection of $L^2(0, 2\pi)$ onto \mathcal{X}_n . For $\varphi = \sum a_m \psi_m$, we have

$$\mathcal{P}_n\varphi(\theta) = \sum_{m=-n}^n a_m \psi_m(\theta)$$

the truncation of the Fourier series for φ .

Approximate (5.3) by the equation

$$\mathcal{P}_n\left(-2\pi i C_u \phi_n + \mathcal{B}\phi_n\right) = \mathcal{P}_n g, \qquad \phi_n \in \mathcal{X}_n$$
 (5.5)

Let

$$\phi_n(\theta) = \sum_{\substack{m=-n\\m\neq 0}}^n a_m^{(n)} \psi_m(\theta)$$

Note that ϕ_n does not have the constant term, i.e., $\phi_n \in \{\phi_n \in \mathcal{X} \mid a_0^{(n)} = 0\}$, because ϕ is the derivative of η (see (5.2)). The equation (5.5) implies that the coefficients $\{a_m^{(n)}\}$ are determined from the linear system

$$-\operatorname{sign}(k)i\pi a_k^{(n)} + \sum_{\substack{m=-n\\m\neq 0}}^n a_m^{(n)} \int_0^{2\pi} \int_0^{2\pi} B(\theta_0, \theta) \psi_m(\theta) \overline{\psi_k(\theta_0)} d\theta d\theta_0$$

$$= \int_0^{2\pi} g(\theta) \overline{\psi_k(\theta_0)} d\theta, \qquad k = \pm 1, \dots, \pm n$$
(5.6)

Using

$$\mathcal{P}_n C_u = C_u \mathcal{P}_n, \qquad \qquad \mathcal{P}_n C_u^{-1} = C_u^{-1} \mathcal{P}_n,$$

the approximating equation (5.5) is equivalent to

$$\phi_n - \frac{1}{2\pi i} \mathcal{P}_n C_u^{-1} \mathcal{B} \phi_n = -\frac{1}{2\pi i} \mathcal{P}_n C_u^{-1} g$$
 (5.7)

This is simply a standard Galerkin method for solving (5.4).

Since $\mathcal{P}_n \phi \to \phi$, for all $\phi \in L^2(0, 2\pi)$, and since $C_u^{-1} \mathcal{B}$ is compact, we have

$$\|(I - \mathcal{P}_n) C_u^{-1} \mathcal{B}\| \longrightarrow 0 \text{ as } n \to \infty$$

Then by standard arguments, the existence of $\left(I - \frac{1}{2\pi i}C_u^{-1}\mathcal{B}\right)^{-1}$ implies that of $\left(I - \frac{1}{2\pi i}\mathcal{P}_nC_u^{-1}\mathcal{B}\right)^{-1}$ exists and is uniformly bounded for all sufficiently large n, and

$$\|\phi - \phi_n\|_0 \le \left\| \left(I - \frac{1}{2\pi i} \mathcal{P}_n C_u^{-1} \mathcal{B} \right)^{-1} \right\| \|\phi - \mathcal{P}_n \phi\|_0$$

where $\|\cdot\|_0$ is the norm for $H^0(2\pi) \equiv L^2(0, 2\pi)$. For more detailed bounds on the rate of convergence, see Atkinson [5, §7.3]:

$$\|\phi - \phi_n\|_0 \le \frac{c}{n^q} \|\phi\|_q$$
, $\phi \in H^q(2\pi)$

for any q > 0.

Generally the integrals in (5.6) must be evaluated numerically, and therefore we introduce a discrete Galerkin method. We give a numerical method which amounts to using the trapezoidal rule to numerically integrate the integrals in (5.6). Introduce the discrete inner product

$$(f, g)_n = h \sum_{j=0}^{2n} f(t_j) \overline{g(t_j)}, \qquad f, g \in C_p(2\pi)$$
 (5.8)

with $h = 2\pi/(2n+1)$, and $t_j = jh$, j = 0, 1, ..., 2n; and note $(\cdot, \cdot)_n$ is only semi-definite. This is the trapezoidal rule with 2n+1 subdivisions of the integration interval $[0, 2\pi]$, because the integrand is 2π -periodic; and $(\cdot, \cdot)_n$ is a true inner product on the set of all trigonometric polynomials of degree less than or equal to n. Also, approximate the integral operator \mathcal{B} of (4.4) by

$$\mathcal{B}_n \phi(\theta_0) = h \sum_{j=0}^{2n} B(\theta_0, t_j) \phi(t_j), \qquad \phi \in C_p(2\pi)$$

We approximate (5.6) using

$$\sigma_n(\theta) = \sum_{\substack{m=-n\\m\neq 0}}^n b_m^{(n)} \psi_m(\theta)$$

with $\left\{b_m^{(n)}\right\}$ determined from the linear system

$$-\operatorname{sign}(k)i\pi b_k^{(n)} + \sum_{\substack{m=-n\\m\neq 0}}^n b_m^{(n)} (\mathcal{B}_n \psi_m, \psi_k)_n = (g, \psi_k)_n, \qquad k = \pm 1, \pm 2, \dots, \pm n$$
 (5.9)

We give the framework of the error analysis of the discrete Galerkin method here, and the proof of the error analysis follows the same pattern as the proof of Theorem 6 in Atkinson and Sloan [6].

Associated with the discrete inner product (5.8) is the discrete orthogonal projection operator \mathcal{Q}_n mapping $\mathcal{X} = C_p(2\pi)$ into \mathcal{X}_n ; for more details about \mathcal{Q}_n see Atkinson [5, §4.4]. In particular,

$$(\mathcal{Q}_n \varphi, \psi)_n = (\varphi, \psi)_n, \qquad \forall \psi \in \mathcal{X}_n$$
 (5.10)

$$Q_n \varphi = \sum_{m=-n}^n (\varphi, \psi_m)_n \psi_m \tag{5.11}$$

Using (5.10) and (5.11), equation (5.9) can be written symbolically as

$$Q_n \left(-2\pi i C_u \sigma_n + \mathcal{B}_n \sigma_n \right) = Q_n g, \qquad \sigma_n \in \mathcal{X}_n \tag{5.12}$$

This equation is equivalent to the equation

$$-2\pi i C_u \sigma_n + \mathcal{Q}_n \mathcal{B}_n \sigma_n = \mathcal{Q}_n g, \qquad \sigma_n \in \mathcal{X}$$
 (5.13)

In order to prove the equivalence, we begin by assuming (5.13) is solvable. Then

$$-2\pi i C_n \sigma_n = \mathcal{Q}_n q - \mathcal{Q}_n \mathcal{B}_n \sigma_n \in \mathcal{X}_n.$$

Using (2.5) for C_u , this implies $\sigma_n \in \mathcal{X}_n$ and $\mathcal{Q}_n \sigma_n = \sigma_n$. Using this in (5.13) implies the equation (5.12). A similar argument shows that (5.12) implies (5.13).

Equation (5.13) is equivalent to

$$\sigma_n - \frac{1}{2\pi i} C_u^{-1} \mathcal{Q}_n \mathcal{B}_n \sigma_n = -\frac{1}{2\pi i} C_u^{-1} \mathcal{Q}_n g \tag{5.14}$$

This is an approximation of (5.3). The equation (5.4), which is equivalent to (5.3), and its approximation (5.14)

$$\phi - \frac{1}{2\pi i} C_u^{-1} \mathcal{B} \phi = -\frac{1}{2\pi i} C_u^{-1} g \tag{5.15}$$

$$\sigma_n - \frac{1}{2\pi i} C_u^{-1} \mathcal{Q}_n \mathcal{B}_n \sigma_n = -\frac{1}{2\pi i} C_u^{-1} \mathcal{Q}_n g \tag{5.16}$$

are used for an error analysis of the discrete Galerkin method (5.9).

Then follow the same pattern as the proof for Theorem 6 in Atkinson and Sloan [6], we can show

$$\|\phi - \sigma_n\|_{\infty} \le \frac{c}{n^{q - 0.5 - \epsilon}} \tag{5.17}$$

when $g \in H^q(2\pi)$ and $\phi \in C_p(2\pi) \cap H^{q-1}(2\pi)$, for some q > 0.5 and any small $\epsilon > 0$.

6 Numerical Examples

We give two numerical examples for the interior Neumann problem (1.1). The domain D for both of the examples is an ellipse and its boundary S is

$$\beta(t) = (a\cos t, b\sin t), \qquad 0 \le t \le 2\pi$$

where a = 0.5 and b = 2.5. Consider the interior Neumann problem

$$\Delta u(P) = 0,$$
 $P \in D$
$$\frac{\partial u(P)}{\partial \mathbf{n}_P} = f(P),$$
 $P \in S$

We represent the solution u as the double layer potential (1.2). The derivative of the

Table 1: Errors in u_n , true solution = $e^x \sin y$							
n	j = 1	j=2	j=3	j=4	j=5		
4	8.28E - 3	8.28E-2	2.07E - 1	4.17E - 1	7.70E - 1		
8	3.40E - 3	$3.40\mathrm{E}{-2}$	$8.56E{-2}$	1.75E - 1	$3.29\mathrm{E}\!-\!1$		
12	1.79E - 3	1.79E - 2	$4.50\mathrm{E}{-2}$	$9.13E{-2}$	1.73E - 1		
16	1.01E - 3	1.01E - 2	$2.54\mathrm{E}{-2}$	5.16E - 2	9.75E - 2		
20	5.96E - 4	5.96E - 3	1.50E - 2	3.04E - 2	5.74E - 2		
24	3.61E - 4	3.61E - 3	9.07E - 3	1.84E - 2	3.49E - 2		
28	2.23E-4	2.23E - 3	5.60E - 3	1.14E - 2	$2.15\mathrm{E}{-2}$		
32	1.40E - 4	1.40E - 3	3.51E - 3	7.13E - 3	$1.35\mathrm{E}{-2}$		
36	8.82E - 5	8.82E - 4	2.22E - 3	4.50E - 3	8.51E - 3		
40	5.66E - 5	5.66E - 4	1.42E - 3	2.89E - 3	5.44E - 3		

unknown density function ρ is obtained by solving (5.7).

Table 2: Errors in u_n , $u(Q) = \log Q - P $, $P = (1, 2)$								
n	j = 1	j=2	j=3	j = 4	j=5			
4	-1.96E - 3	-1.91E-2	-4.94E-2	-1.28E - 1	-3.57E - 1			
8	-1.90E - 3	-1.97E - 2	-5.28E-2	-1.19E - 1	-2.65E-1			
12	-9.46E-4	-9.87E - 3	-2.70E - 2	-6.06E-2	-1.36E - 1			
16	-5.49E-4	-5.74E - 3	-1.55E-2	$-3.50\mathrm{E}\!-\!2$	-7.76E-2			
20	-3.27E-4	-3.42E - 3	-9.21E - 3	-2.08E-2	-4.52E - 2			
24	-1.99E-4	-2.08E - 3	-5.60E - 3	-1.26E-2	-2.83E-2			
28	-1.24E-4	-1.29E - 3	-3.47E - 3	-7.84E - 3	-1.71E-2			
32	-7.75E - 5	-8.10E-4	-2.18E - 3	-4.92E - 3	-1.08E-2			
36	-4.92E - 5	-5.14E-4	-1.38E - 3	-3.12E - 3	-6.91E - 3			
40	-3.14E-5	-3.28E-4	-8.83E-4	-1.99E - 3	-4.34E - 3			

After solving the equation (5.7) for the approximate solution σ_n , the approximate density

function η_n is given by

$$\eta_n(\theta) = \frac{2\pi}{L} \sum_{\substack{m=-n\\m\neq 0}}^n \frac{b_m}{im} \psi_m(\theta) \qquad \theta \in [0, 2\pi]$$

We obtain an approximation u_n by substituting η_n for ρ in equation (1.2) and then integrating it numerically. The integral is evaluated with the trapezoidal rule T_{2m+1} where m=256.

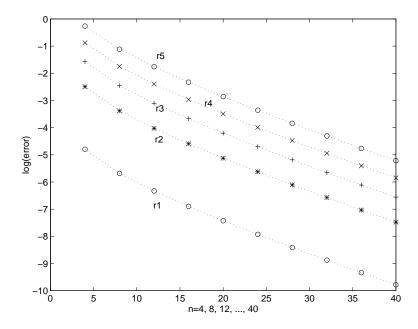


Figure 1: n vs $\log(\text{error})$ for $u(x, y) = e^x \sin y$

We give the results of this integration at a set of five points inside of D:

$$(x_j, y_j) = r_j \left(a \cos(\frac{4}{\pi}), b \sin(\frac{4}{\pi}) \right), \qquad j = 1, 2, 3, 4, 5$$

with $r_j = 0.01, 0.1, 0.25, 0.5, 0.9$. The point (x_5, y_5) is close to the boundary S, making the integrand in (1.2) quite peaked.

Two problems have been solved. The true solution for the first example is

$$u(x, y) = e^x \sin y,$$
 $\forall (x, y) \in D.$

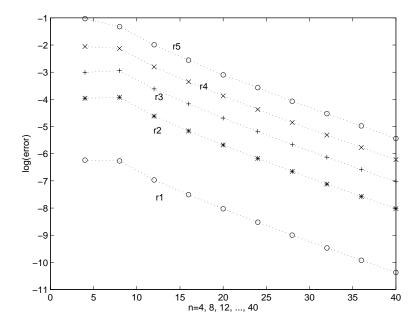


Figure 2: n vs $\log(\text{error})$ for $u(Q) = \log |Q - P|$

The true solution of the second example is

$$u(x, y) = \log | (x, y) - P |, \qquad \forall (x, y) \in D$$

where P is a point out side of D, and we arbitrarily choose P = (1, 2). Boundary data f for the Neumann problem are computed based on these two true solutions.

Tables 1 and 2 are errors for the true solutions $e^x \sin y$ and $\log |Q-P|$, respectively. We also plot the errors as Figures 1 and 2. The y-axis of the figures are the natural logarithm of the absolute value of the errors.

From Tables 1 and 2, we have noticed that the closer the points are to the boundary, the larger are the errors. From Figures 1 and 2, it appears that the rate of convergence is exponential:

$$u(A) - u_n(A) = \mathcal{O}(e^{-cn})$$

for some positive number c, which is better than what is proved in (5.17).

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