

22C:253 Lecture 15

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We now have

$\max f(t,s)$
subject to

$$f(i, j) \leq c(i, j) \forall (i, j) \in E. - \mathbf{I}$$

$$\sum_{j:(j,i) \in E} f(j, i) - \sum_{j:(i,j) \in E} f(i, j) \leq 0 \forall i \in V. - \mathbf{II}$$

DUAL LP:

Let d_{ij} be the dual variable corresponding to the Type I constraint for edge (i,j) .

Let P_i be the dual variable for the Type II constraint for vertex i .

We want to minimize

$$\sum_{(i,j) \in E} c(i, j) \cdot d_{ij}$$

To obtain the dual constraints let us examine the primal constraint matrix.

Hence the dual constraint corresponding to primal variable $f(i,j)$ are

$$d_{ij} - P_i + P_j \geq 0 \forall (i, j) \in E$$

And dual constraint corresponding to $f(t,s)$ are

$$P_s - P_t \geq 1$$

$$d_{ij} \geq 0 \forall (i, j) \in E$$

$$P_i \geq 0 \forall i \in V$$

Hence Dual LP

$$\min \sum_{(i, j) \in E} c(i, j) \cdot d_{ij}$$

subject to

$$d_{ij} - P_i + P_j \geq 0 \forall (i, j) \in E$$

$$P_s - P_t \geq 1$$

$$d_{ij} \geq 0 \forall (i, j) \in E$$

$$P_i \geq 0 \forall i \in V$$

Consider the IP obtained by replacing $d_{ij} \geq 0$ by $d_{ij} \in \{0,1\}$ and $P_i \geq 0$ by $P_i \in \{0,1\}$.
Observe that the above LP is a relaxation of this IP.

* How is this IP interpreted ?

In any feasible solution $P_s = 0$ and $P_t = 1$.

Let $V_0 = \{ i \in V \mid P_i = 0 \}$

$V_1 = \{ i \in V \mid P_i = 1 \}$

In an optimal solution $d_{ij} = 0 \forall (i,j) \in E$ and $\{ (i \in V_0 \text{ and } j \in V_0) \text{ or } (i \in V_1 \text{ and } j \in V_1) \}$

$$d_{ij} = 0 \forall (i, j) \in E : i \in V_0 \text{ and } j \in V_1$$

$$d_{ij} = 1 \forall (i, j) \in E : i \in V_1 \text{ and } j \in V_0$$

Hence the objective function is minimizing the total capacity of edges from V_1 to V_0

Primal Dual Schema For Approximation Algorithms

Consider the following approximate complementary slackness conditions:

Approximate Primal Complementary Slackness

For each $j = 1, 2, \dots, n$ $x_j = 0$

OR

$$\frac{c_j}{\alpha} \leq \sum_{i=1}^m a_{ij} \cdot y_i \leq c_j \text{ where } \alpha \geq 0$$

Approximate Dual Complementary Slackness

For each $i = 1, 2, \dots, m$ $y_i = 0$

OR

$$\beta \cdot b_i \geq \sum_{j=1}^n a_{ij} \cdot x_j \geq b_i \text{ where } \beta \geq 0$$

Claim: Let x and y be feasible primal and dual solutions satisfying all of the above constraints.
Then

$$\sum_{j=1}^n c_j \cdot x_j \leq \beta \cdot \alpha \sum_{i=1}^m b_i \cdot y_i$$

Proof:

$$\begin{aligned} \sum_{j=1}^n c_j \cdot x_j &\leq \sum_{j=1}^n (\alpha \cdot \sum_{i=1}^m a_{ij} \cdot y_i) \cdot x_j \\ &= \alpha \cdot \sum_{i=1}^m \sum_{j=1}^n (a_{ij} \cdot x_j) \cdot y_i \\ &\leq \alpha \cdot \beta \cdot \sum_{i=1}^m b_i \cdot y_i \end{aligned}$$

Using this in Set Cover

Set Cover LP Relaxation

$$\min \sum_{j=1}^n c(s_j) \cdot s_j$$

Subject to

$$\sum_{j:u \in S_j} x_j \geq 1 \text{ for each element } i = 1, 2, \dots, m$$

$$x_j \geq 0 \text{ for each } j = 1, 2, \dots, n$$

Dual LP

$$\max \sum_{i=1}^m y_i$$

Subject to

$$\sum_{i \in S_j} y_i \leq c(S_j) \text{ for each } j = 1, 2, \dots, n$$

$$y_i \geq 0 \text{ for all } i = 1, 2, \dots, m$$

Let us state the Approximate Complementary Slackness Conditions with $\alpha = 1$ and $\beta = f$, where $f = \max.$ frequency of any element i .

Approximate Primal Complementary Slackness

For each set S_j , $x_j = 0$ or

$$\sum_{i \in S_j} y_i = C(S_j)$$

Approximate Dual Complementary Slackness

For each element $i = 1, 2, \dots, m$, $y_i = 0$ or

$$\sum_{j: i \in S_j} x_j \geq 1$$

If we can come up with an integral feasible solution x and a dual solution y satisfying the slackness conditions mentioned, then we get a factor- f approximation algorithm for Set Cover.

How do we find such x and y ? First let us restate the primal complementary slackness conditions: It is saying that for each set S_j , $j=1,2,\dots,n$, we cannot have $x_j > 0$ and

$$\sum_{i \in S_j} y_i < c(S_j)$$

\equiv For each set S_j , $j=1,2,\dots,n$, if $x_j > 0$ then

$$\sum_{i \in S_j} y_i = c(S_j)$$

1. Start with $x = 0$ (integral non-feasible Primal solution) and $y = 0$ (feasible dual solution)
2. At each step we make x more feasible maintaining integrality.
3. At each step make y more optimal.
4. At all steps approximate complementary slackness conditions are maintained.