

# 22C:253 Lecture 10

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October 16, 2002

Last week three algorithms for MAX-SAT were introduced. The final algorithm was a combination of the first two and gave us a factor- $\frac{3}{4}$  approximation algorithm. The final algorithm was:

**Algorithm 3** : Toss an unbiased coin and depending on the outcome, pick algorithm 1 or algorithm 2 and run it.

For this algorithm we showed that if  $W$  is the random variable denoting the weight of the satisfied clauses then  $E[W] \geq \frac{3}{4} \cdot OPT$ . Alternately, a factor- $\frac{3}{4}$  approximation algorithm for MAX-SAT is given as:

Run algorithm 1 and algorithm 2 respectively, and pick the better solution.

**Claim:** Let  $W'$  denote the random variable that is the weight of clauses satisfied by the alternate algorithm, then  $E[W'] \geq \frac{3}{4} \cdot OPT$ . **Proof:**

$$W' = \max\{W^1, W^2\} \geq \frac{W^1 + W^2}{2}$$

obtain expectation of both sides,

$$E[W'] \geq \frac{E[W^1] + E[W^2]}{2}$$

the right side is the expected weight of solution if we use algorithm 3, which  $\geq \frac{3}{4} \cdot OPT$   $\square$

**Derandomization.** For each of these algorithms, we have only given approximation guarantees in an expected sense, which means it does not *guarantee* that we will not get a bad solution. However, both Algorithms 1 and 2 can be derandomized, that is, we can construct equivalent deterministic algorithms. We will derandomize Algorithm 1 using the technique of *conditional probabilities* to have a guaranteed factor- $\frac{1}{2}$  approximation.

In the computation tree for MAX-SAT, a level  $k$  node is identified by the  $k$ -tuple of the truth values  $(a_1, a_2, a_3, \dots, a_k)$ , where  $x_1 = a_1, x_2 = a_2, \dots, x_k = a_k$ . So each leaf of the computation tree represents a truth assignment. Define the conditional expectation of a node  $(a_1, a_2, a_3, \dots, a_k)$  as

$$E[W | x_1 = a_1, x_2 = a_2, \dots, x_k = a_k]$$

From the definition and previous algorithms, we obtain:

**Remarks:**

- The conditional expectation of the root is  $E[W]$ .

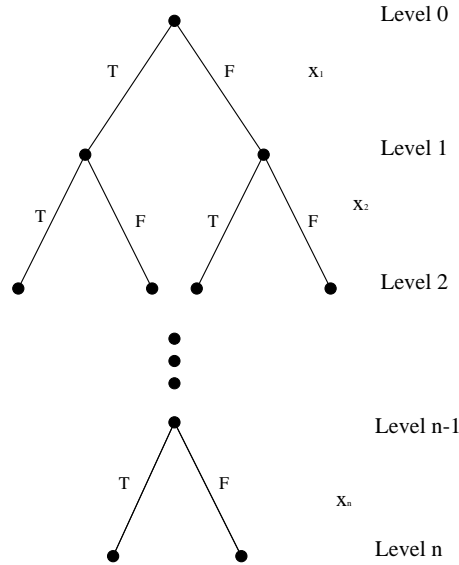


Figure 1: Computation tree for MAX-SAT

- The conditional expectation of a leaf  $(a_1, a_2, a_3, \dots, a_n)$  is the sum of the weights of satisfied clauses obtained by setting  $x_i = a_i, i = 1, 2, \dots, n$
- The conditional expectation of any node can be computed in polynomial time.

**Lemma 1** *We can compute a path from root to a leaf, such that the conditional expectation at every node in the path  $\geq E[W]$ .*

**Proof:** A node  $(a_1, a_2, a_3, \dots, a_k)$  has two children  $(a_1, a_2, a_3, \dots, a_k, T)$ , and  $(a_1, a_2, a_3, \dots, a_k, F)$ . Since we toss a coin to decide the truth value for  $x_{k+1}$ , the conditional expectation at this node is

$$\begin{aligned}
 E[w|x_1 = a_1, x_2 = a_2, \dots, x_k = a_k] &= \frac{1}{2}E[w|x_1 = a_1, x_2 = a_2, \dots, x_k = a_k, x_{k+1} = T] \\
 &+ \frac{1}{2}E[w|x_1 = a_1, x_2 = a_2, \dots, x_k = a_k, x_{k+1} = F]
 \end{aligned}$$

If at node  $(a_1, a_2, a_3, \dots, a_k)$

$$E[w|x_1 = a_1, x_2 = a_2, \dots, x_k = a_k] \geq E[W],$$

then the conditional expectation of at least one child  $\geq E[W]$ . This implies that if we go to the child with a higher conditional expectation until we reach a leaf, the conditional expectation at every node in the path  $\geq E[W]$ .  $\square$

So at the end of this path, the truth assignment represented by the leaf gives a solution which satisfies  $W \geq E[W] \geq \frac{1}{2} \cdot OPT$

For the Algorithm 2 also, though conditional expectation at a node might not be the average of conditional expectations at its children, it is still true that the conditional expectation of at least one child  $\geq E[W]$ . So this works for Algorithm 2 as well.

### Scheduling on unrelated parallel machines (SUPM)

INPUT: A set  $J$  of jobs and a set  $M$  of machines, for each job  $j \in J$  and machine  $i \in M$ , a processing time  $p_{ij} \in \mathbb{Z}^+$ .

OUTPUT: An assignment of jobs to machines with minimum makespan.

Current status of this problem:

- A factor-2 approximate algorithm using LP-relaxation.
- A factor-1.5 hardness approximate algorithm (that is, if there exists a factor-1.5 approximation algorithm, then  $P = NP$ ).

Here is the IP for SUPM

$$\min t$$

such that

$$\begin{aligned} t &\geq \sum_{j \in J} p_{ij} \cdot x_{ij} \text{ for each } i \in M \\ \sum_{i \in M} x_{ij} &= 1 \text{ for each } j \in J \\ x_{ij} &\in \{0, 1\} \forall i \in M, j \in J \end{aligned}$$

And the LP-relaxation for SUPM is obtained by replacing  $x_{ij} \in \{0, 1\}$  by  $x_{ij} \geq 0$ ,  $\forall i \in M, j \in J$

The integrality gap between this IP and LP-relaxation is huge! Let  $OPT$  be the optimal makespan, and  $OPT_f$  be the optimal makespan of the LP-relaxation. Consider such a case where there is a single job, so

$$\begin{aligned} J &= \{1\}, \quad M = \{1, 2, \dots, m\} \\ p_{ij} &= T \text{ for all } i \in M \end{aligned}$$

and

$$OPT = T, \quad OPT_f = \frac{T}{m} \text{ (i.e., } x_{i1} = \frac{1}{m} \text{ for } i \in M)$$

So the gap is  $m$ , and one might wonder if we can add constraints to the LP-relaxation to reduce this gap. Let  $(x, T)$  be a feasible solution of the IP. If  $p_{ij} > T$  then job  $j$  is not assigned to machine  $i$  by the IP, and so  $x_{ij} = 0$ . However  $x_{ij}$  may be non-zero for the LP-relaxation. We could add a constraint  $C$  to the LP-relaxation as follows:

**Constraint  $C$ :** For each  $i \in M, j \in J$ , if  $p_{ij} > T$ , then  $x_{ij} = 0$

The problem here is that this is not a linear constraint. Let  $T^*$  be solution of the LP-relaxation with constraint  $C$ . Then

$$OPT_f \leq T^* \leq OPT$$

We know that the integrality gap between  $OPT$  and  $OPT_f$  is large, but the gap between  $OPT$  and  $T^*$  could be small. In fact, this is the case. So our algorithm for the problem will be:

**Algorithm:**

Step1. Compute  $(x^*, T^*)$  using parametric pruning.

Step2. Use rounding to go from  $x^*$  to an integral solution with makespan  $T \leq 2 \cdot T^* \leq 2 \cdot OPT$ .